

CP-15

FULL AUTOMATIC SCREEN PRINTING MACHINE

INSTRUCTION MANUAL

marushin

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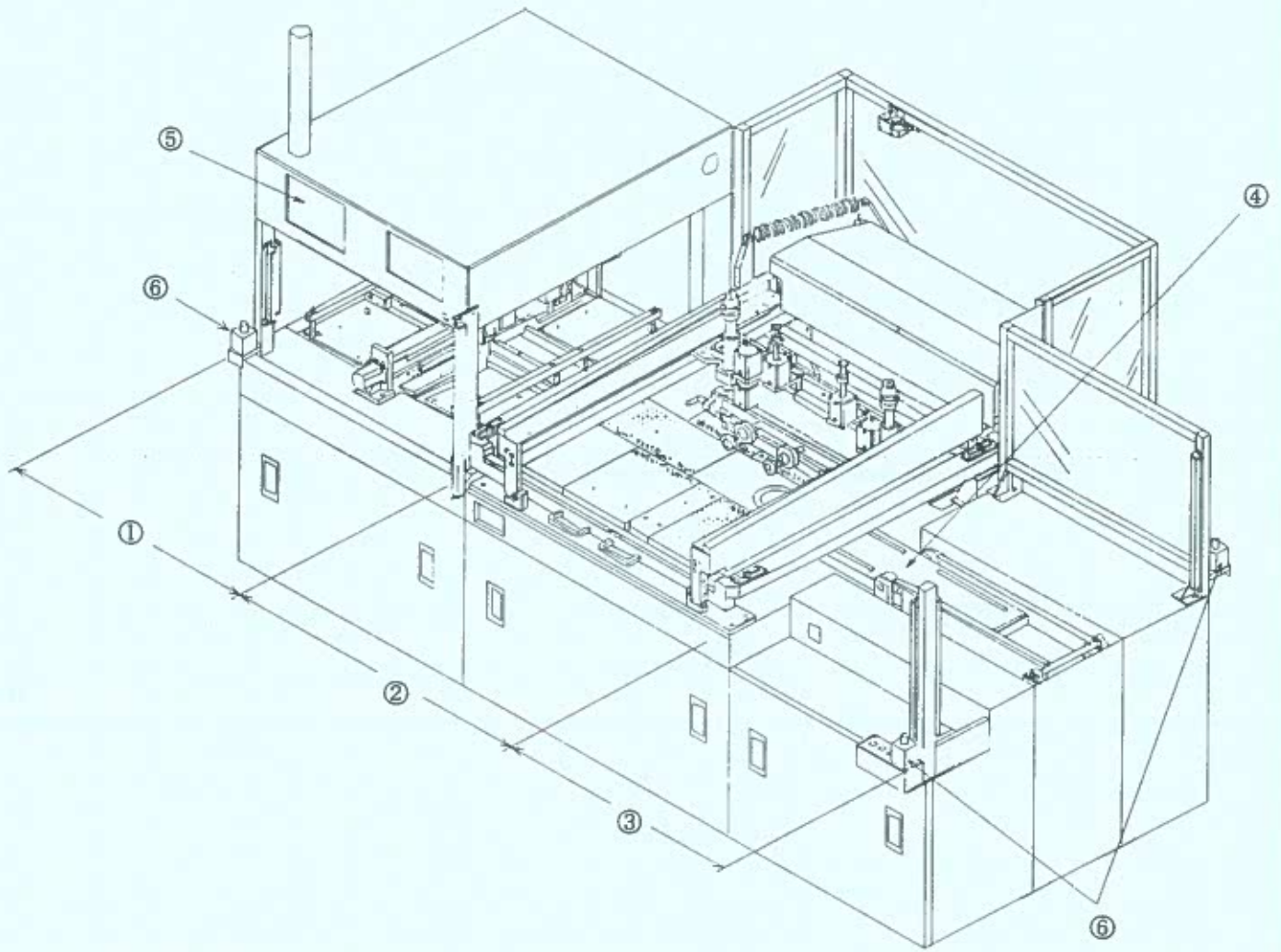
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1-1 Outline of CP-15

- ① ALIGNMENT SECTION ——— set inserted PCB on correct position
- ② PRINTING SECTION ——— print on PCB (detailed on 1-2-2)
- ③ CARRY-OUT SECTION ——— carry out printed PCB (detailed on 1-2-3)
- ④ CARRIER ——— carry PCB from ALIGNMENT SECTION, PRINTING SECTION, to CARRY- OUT SECTION .
- ⑤ OPERATING SECTION ——— have touch panels and each kind of switches for operating this machine
- ⑥ EMERGENCY STOP SWITCH——— stop all movement in an emergency

ft.) In this chapter, all directions and figures are considered that the flow on machine is from left to right (as standard).



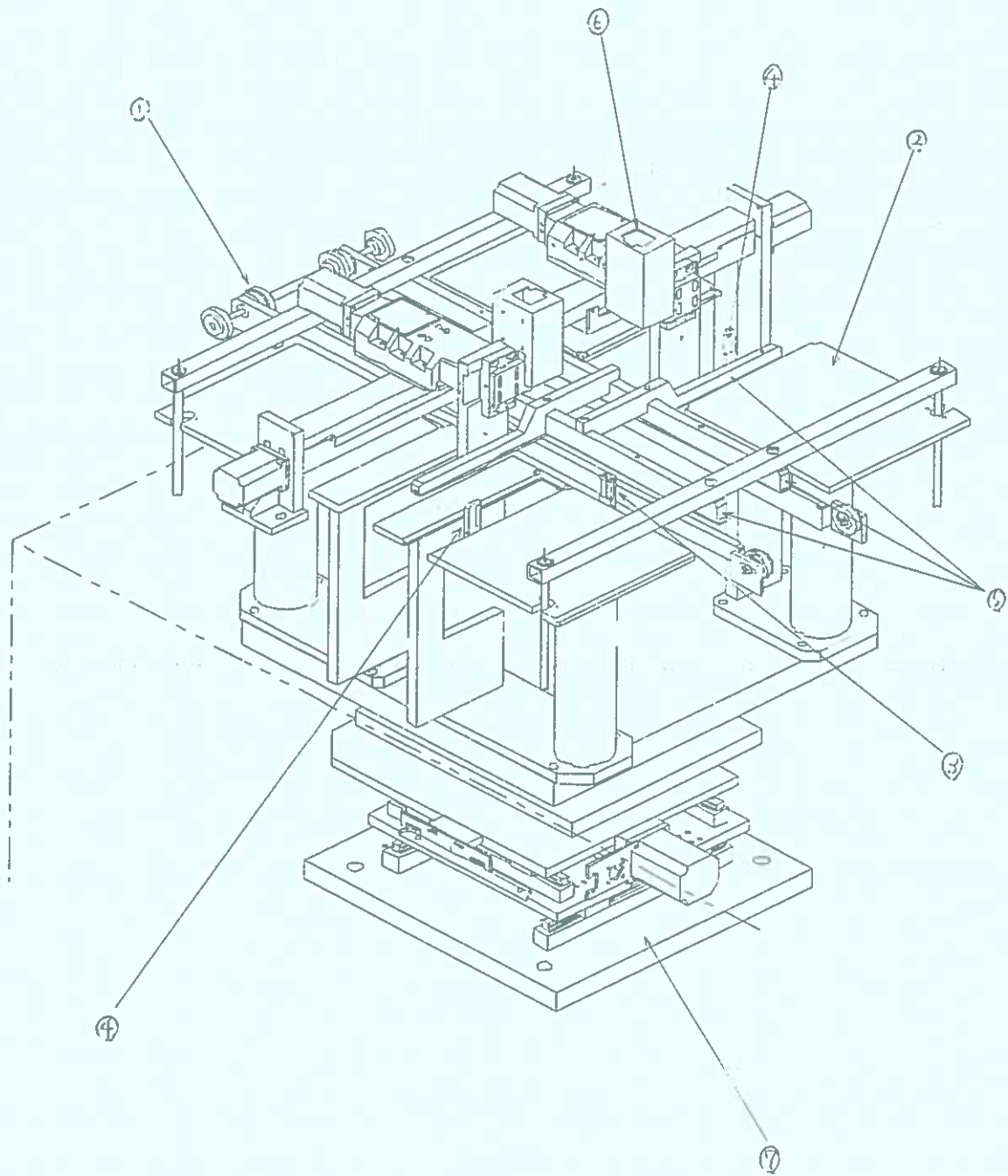
Overview of CP-15

1-2 Explanation of each section

1-2-1 ALIGNMENT SECTION

- ① Carry-in Conveyor ——— carry in a PCB to Alignment Table.
- ② Alignment Table ——— set PCB on the correct positioning
(pre-positioning and alignment- positioning) on
this Table.
- ③ Siding Pin (Flowing direction) }
④ Siding Pin (Squeeging direction) }
- pre-set PCB position in all directions by 6 pins.
- (Right reference mode·····PCB is set based on 2 siding front pins
and right side pin.
Left reference mode····· PCB is set based on 2 siding front pins
and left side pin.)
- ⑤ Board Clamp ——— fix PCB on the Alignment Table to make
alignment.
- ⑥ CCD Camera }
⑦ 3-axis Table } ——— align of PCB on correct position.
detect marks in both sides of PCB by 2 CCD
Cameras. According to the mark data, 3-axis
Table moves to make alignment.

※Flowing side unit have pins on the left and right side. In case , the right pin would be chosen as the stop pin, it called right reference mode. On the other hand, the left pin would be chosen, it called left reference mode.



Alignment Section

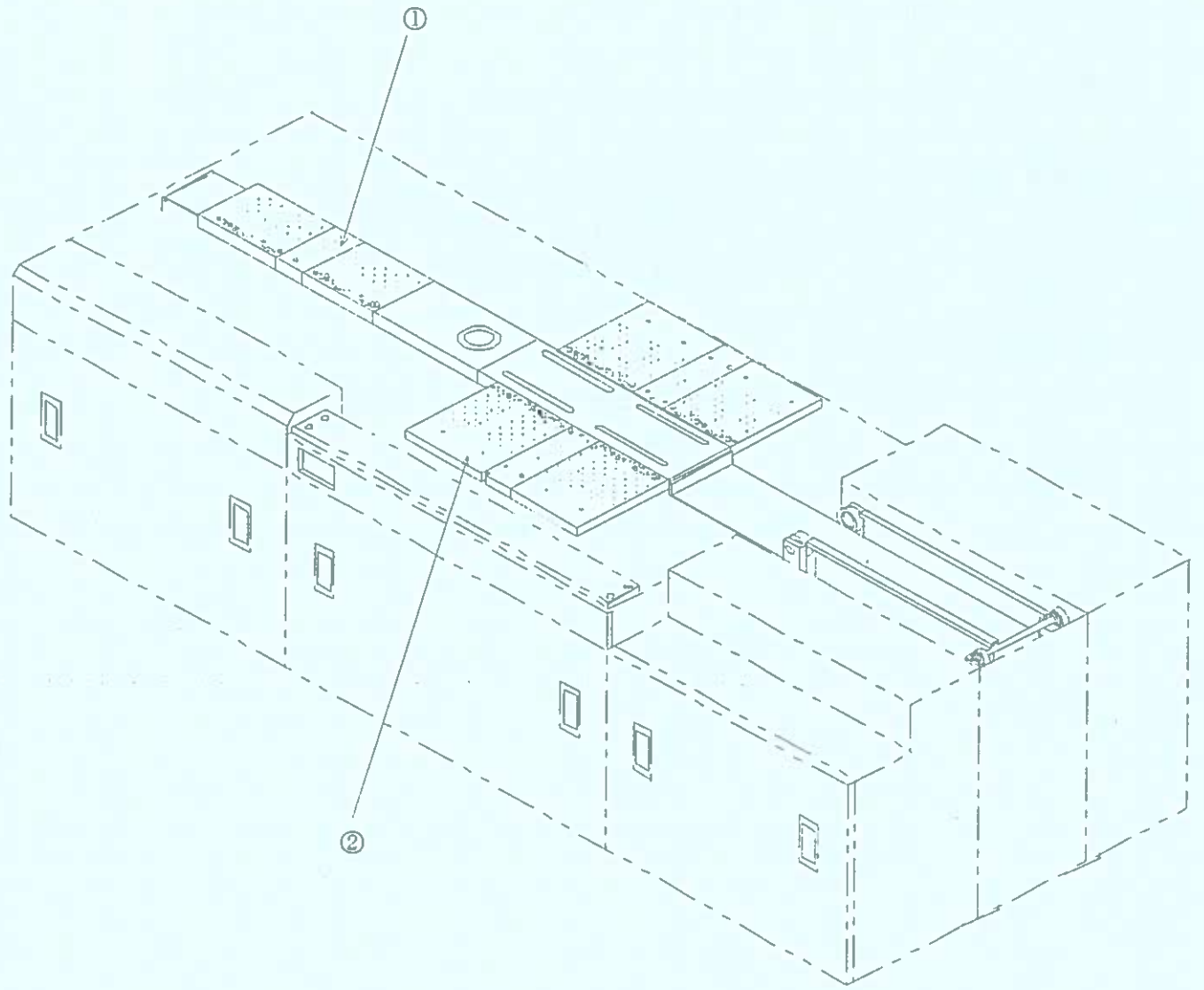
1-2-2 Printing section

- ① CARRIER ——— carry PCB to Printing section. Alignment positioned PCB is fixed on Carrier by vacuum.

- ② PRINTING TABLE
————— fix PCB by vacuum in printing
The surface of Printing section has holes.

- ③ SCREEN FRAME
————— clamp Screen (detailed on 1-2-2-1)
Adjust Screen position by Micro-adjuster on Sub-clamping.
Then clamp completely by Main-clamp. (There are 4 cylinders for each)

- ④ SQUEEGEE ——— print Screen pattern on PCB.
Printing direction is from front to rear.(detailed on 1-2-2-2)



Printing Section

1-2-2-1 Screen Frame — This is the unit for Screen positioning and clamping.

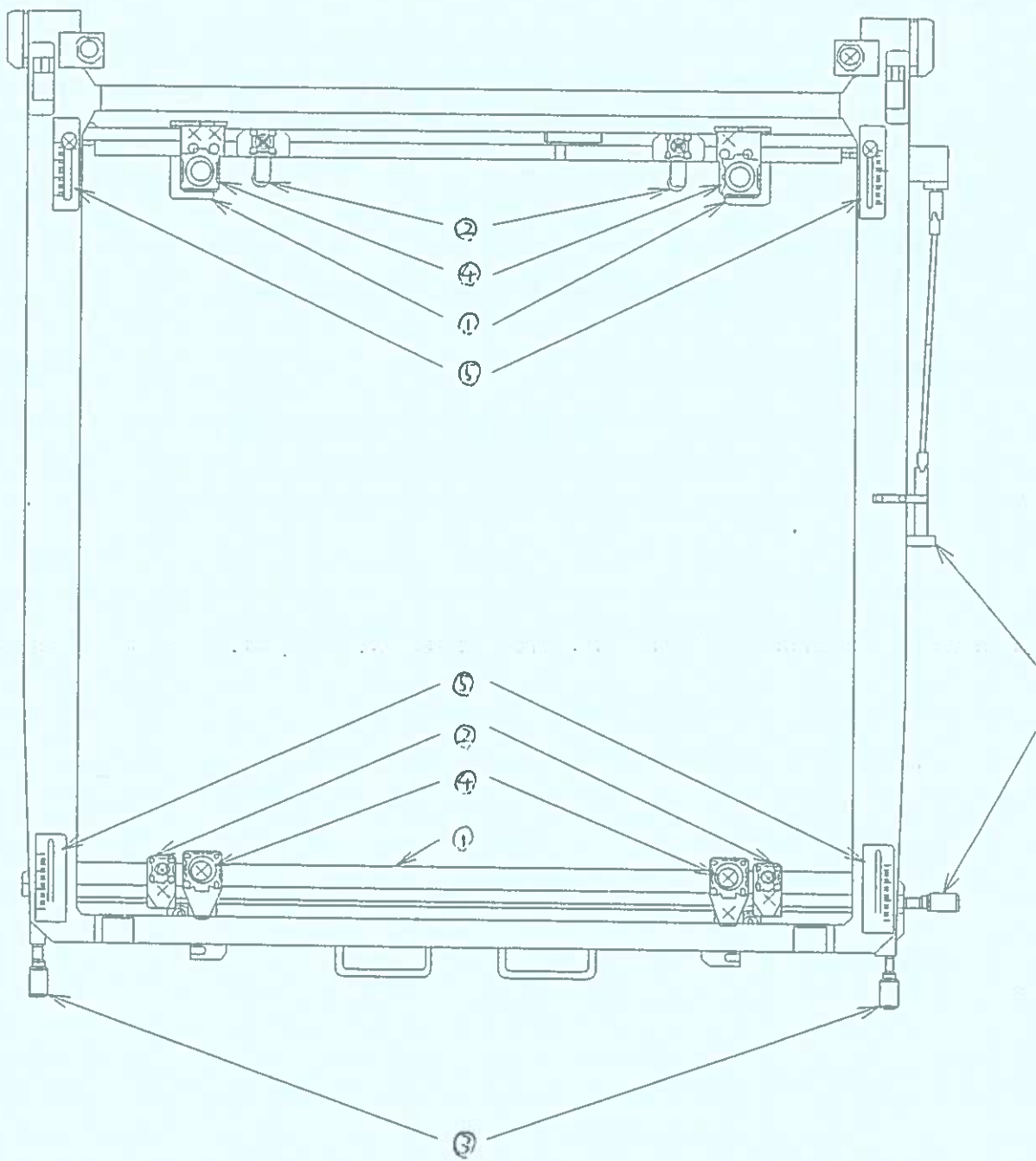
① Screen Guide ——— put Screen on Screen Guide.

② Sub-clamp ——— clamp Screen on Frame temporarily.
There are 2 clamp cylinders each in front and back.
They clamp Screen on Frame.

③ Screen Micro-adjuster
————— Screen sub-clamped on Frame can be micro-
adjusted in all directions.

④ Main-clamp ——— clamp Screen on Frame completely. There are 2 clamp
cylinders each in front and back after adjustment of Screen.

⑤ Screen Size Gauge
————— adjust Frame size depending on the screen size



Screen Frame

1-2-2-2 Squeegee Unit

———— This Unit is for squeegee out ink from screen and making pattern on PCB. And it has scooper function that carry ink to squeegee start position after printing.

① Squeegee angle adjuster

———— adjust Squeegee angle against Screen Frame

② Squeegee lowest point adjuster

———— adjust Squeegee lowest point on Squeegee is down position in case of printing by down stroke.

In case of printing by pressure, the scale should be set 0.

③ Squeegee parallel adjuster

———— adjust parallel degree of Squeegee against Screen

④ Squeegee height on scooping adjuster

———— adjust the height of Squeegee on scooping ink

⑤ Scooper height adjuster

———— adjust the height of Scooper on scooping

⑥ Scooper moving amount adjuster

———— adjust Scooper moving amount on scooping

⑦ Squeegee Unit bias adjuster

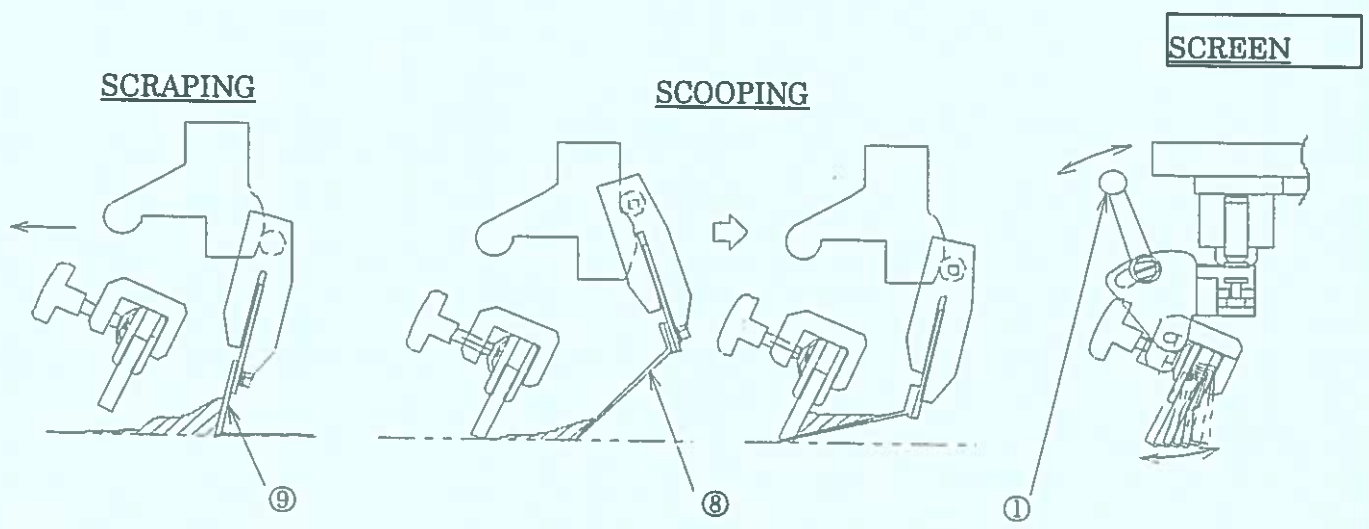
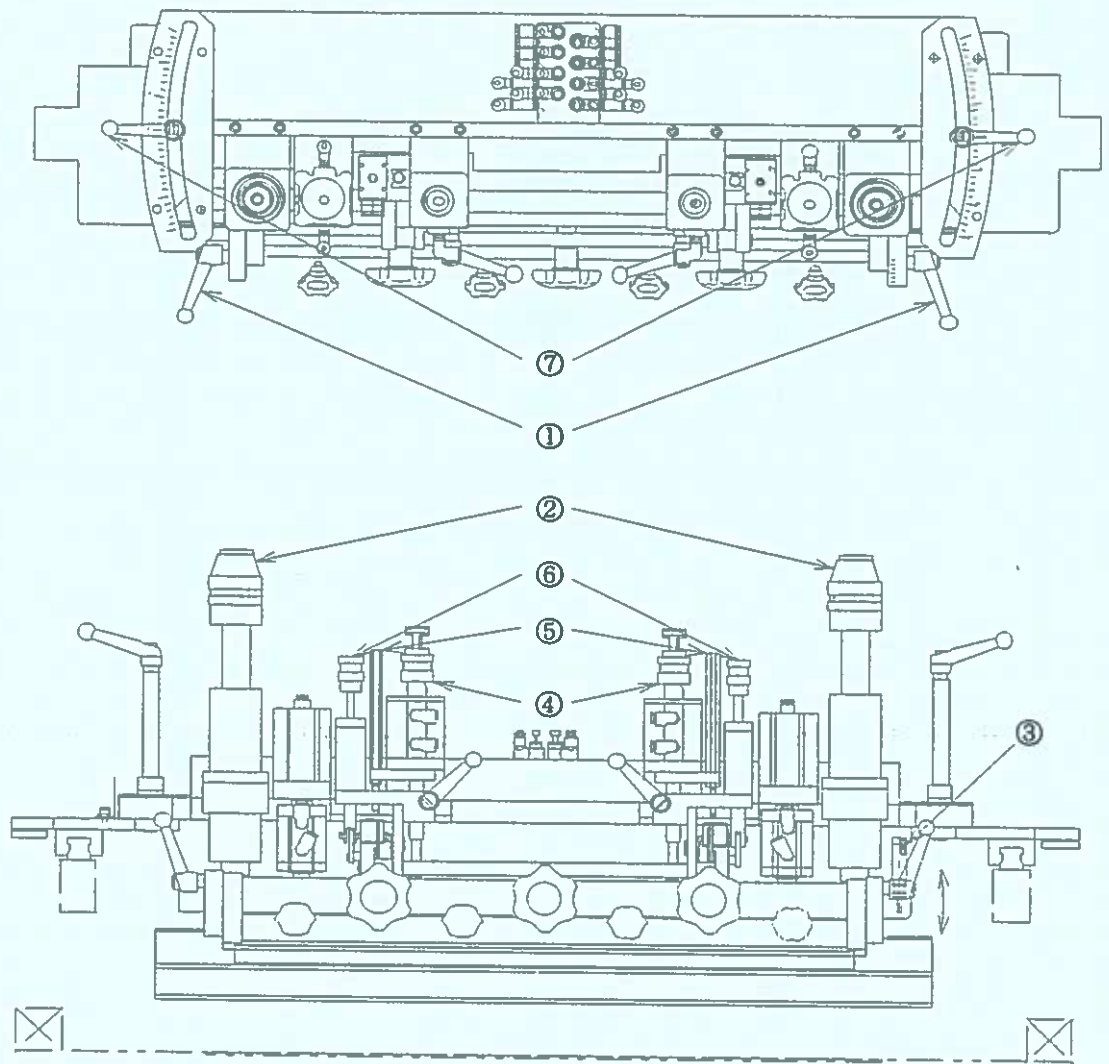
———— adjust bias of the Squeegee Unit

⑧ Scooper

———— bring ink back to start position without touch Screen.

⑨ Scraper

———— scrape ink back to start position after printing

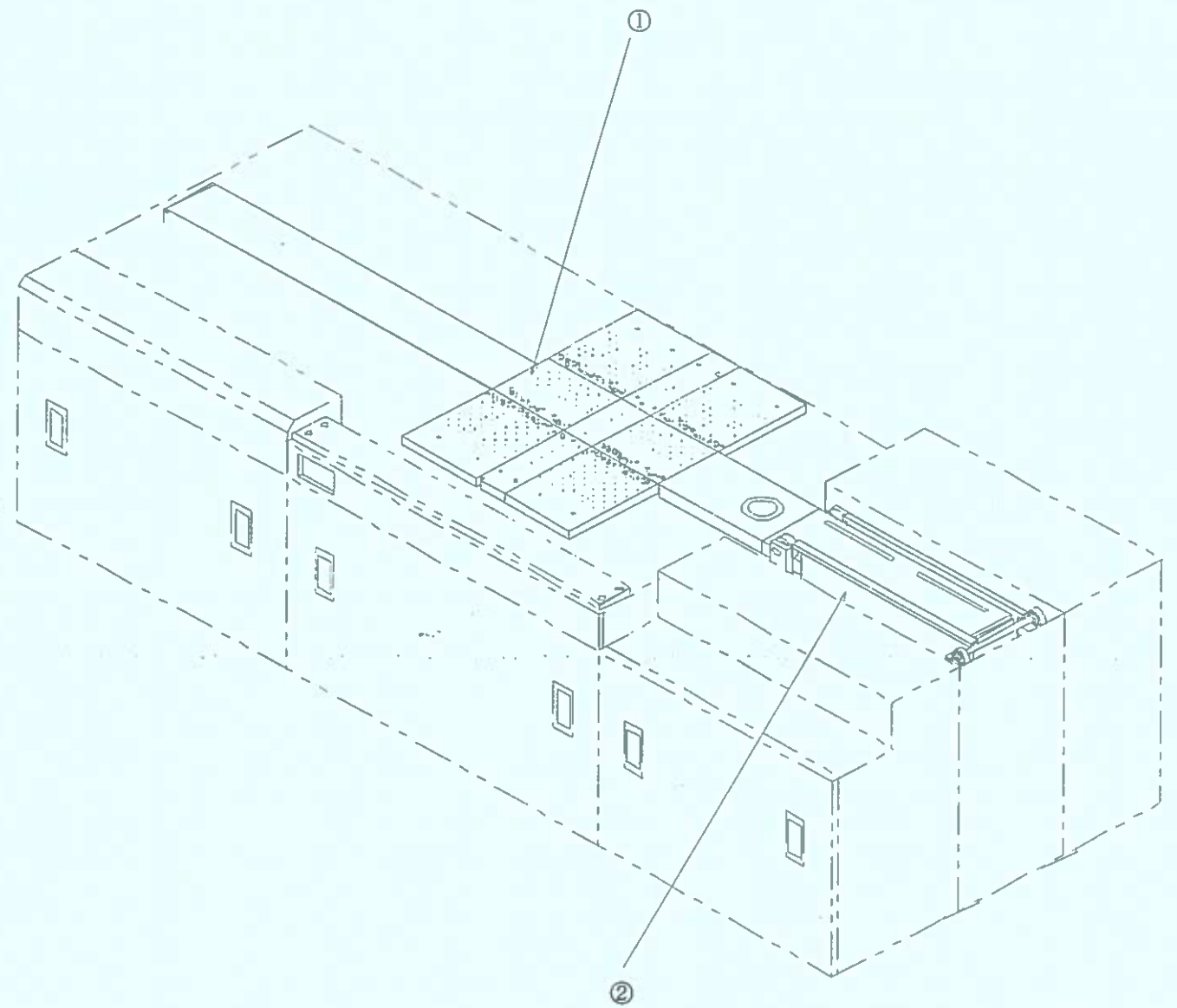


Squeegee Section

1-2-3 Carry-out section

① Carrier carry PCB from Alignment section, printing section, to Carry-out section
Carrier is separated from left and right part.
The left part carries PCB from Alignment section to Printing section,
the right part carries PCB from Printing section to Carry-out section.

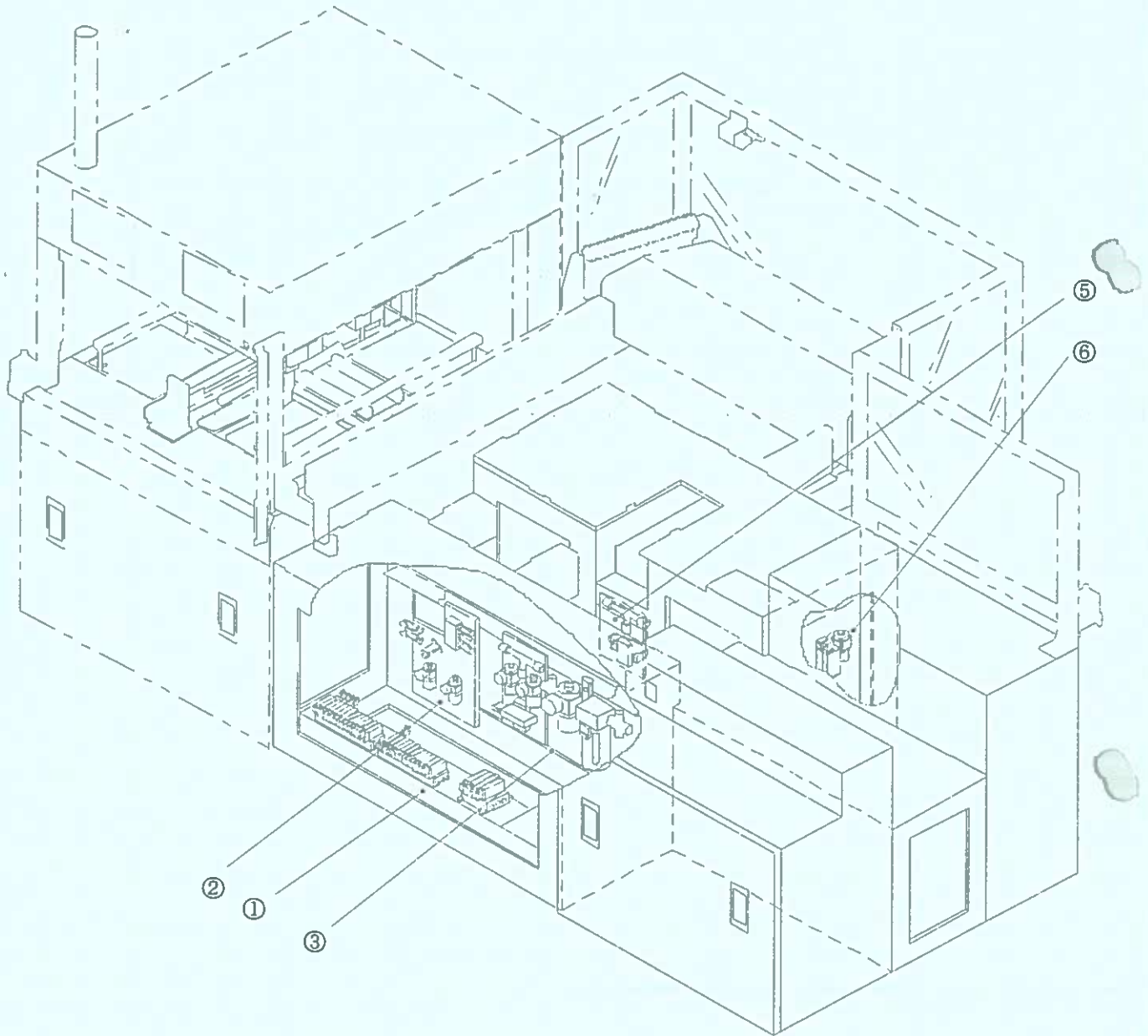
② Carry-out Conveyor
After finished printing, PCB that is carried by Carrier is conveyed out
to the next machine.



Carry-Out Section

1-3 Air Apparatus

1-3-1 Overview Drawing



Overview Drawing

1-3-2 Detailed drawing of ①

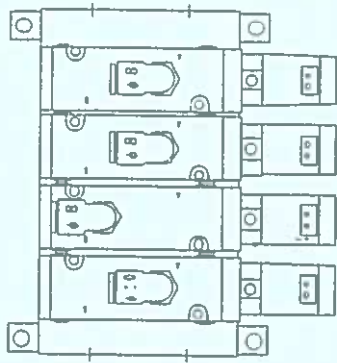
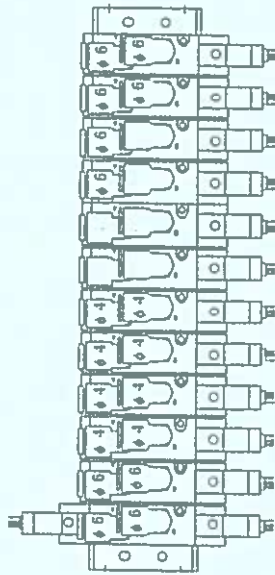


TABLE VACUUM

CARRIER VACUUM

SQUEEGEE PRESS

VACUUM REVERSE



SCOOPING POSITION

SCOOPER MOVE

BALANCING CYLINDER (4kgf/c m²(0.4MPa))

BALANCING CYLINDER (2kgf/c m²(0.2MPa))

SPARE VALVE

SPARE VALVE

SIDING LOCK(FRONT)

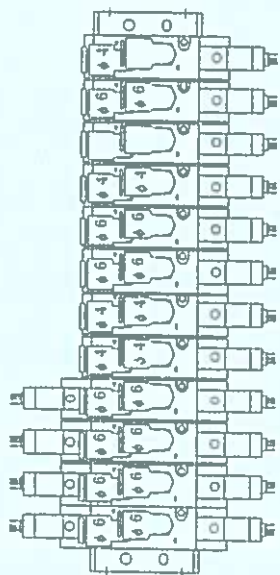
SIDING LOCK(RIGHT)

SIDING LOCK(LEFT)

EJECT PIN UP/DOWN

EXHAUST BALANCING CYLINDER

CARRIER (PCB GUIDE PIN) UP/DOWN



BOARD CLAMP

BOARD CLAMP MIDDLE POSITION

SPARE VALVE

F.SIDING PIN FORWARD

R.SIDING PIN UP

L.SIDING PIN UP

SQUEEGEE FRAME HOOK

SPARE VALVE

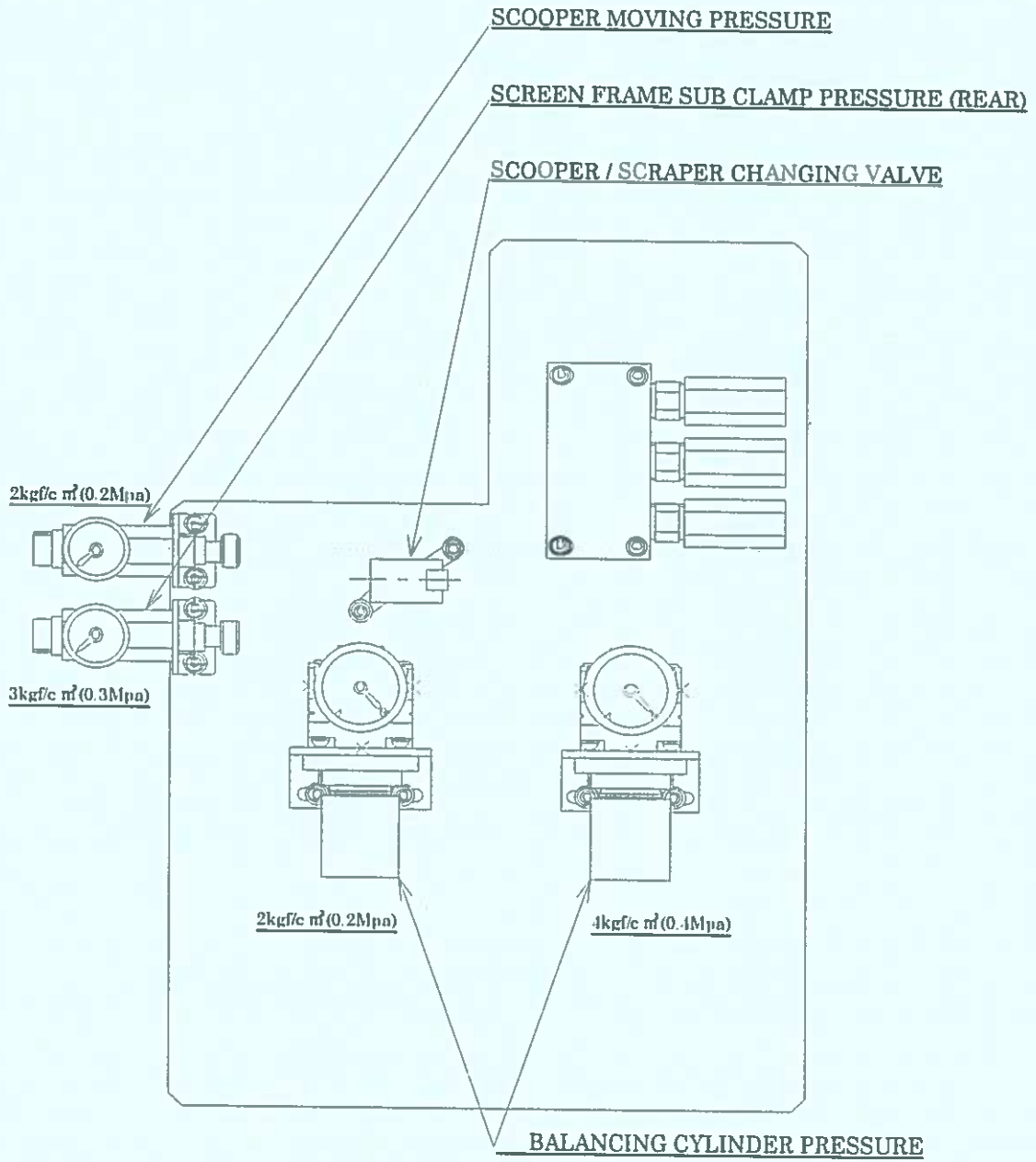
ALIGNMENT TABLE UP/DOWN

SCREEN FRAME UP/DOWN(FRONT)

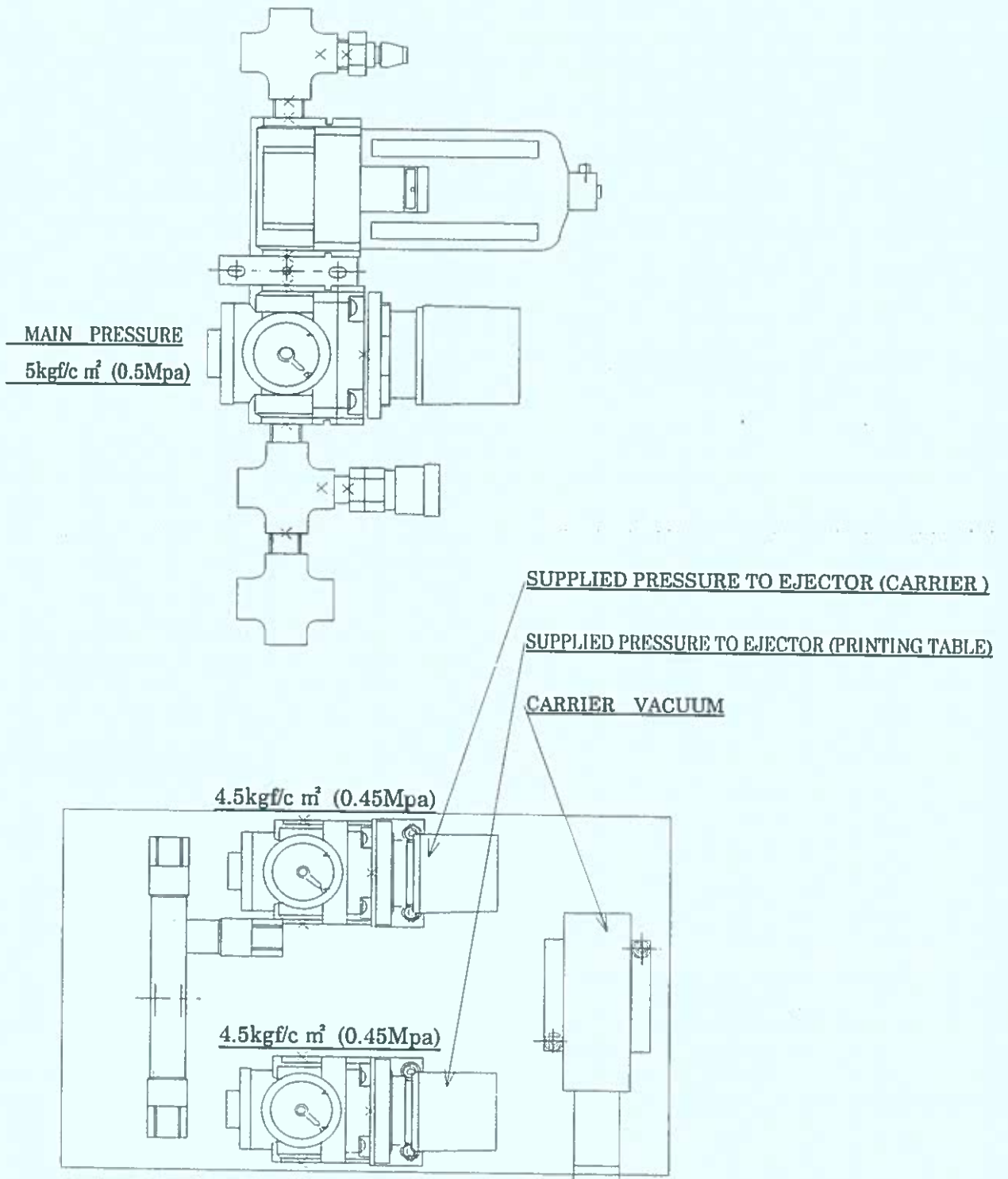
SCREEN FRAME UP/DOWN(REAR)

SQUEEGEE FRAME UP/DOWN

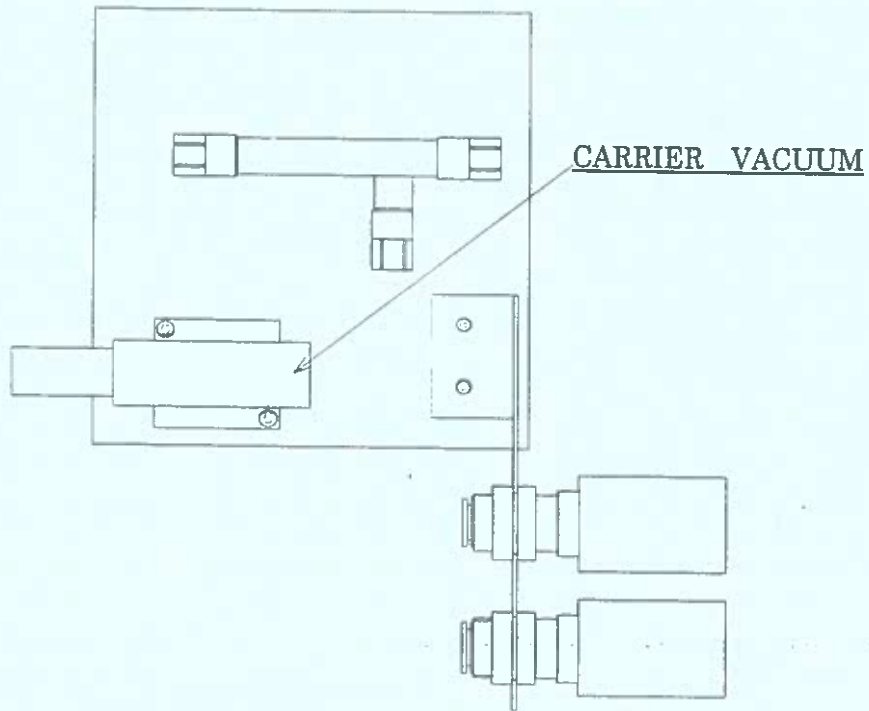
1-3-3 Detailed drawing of ②



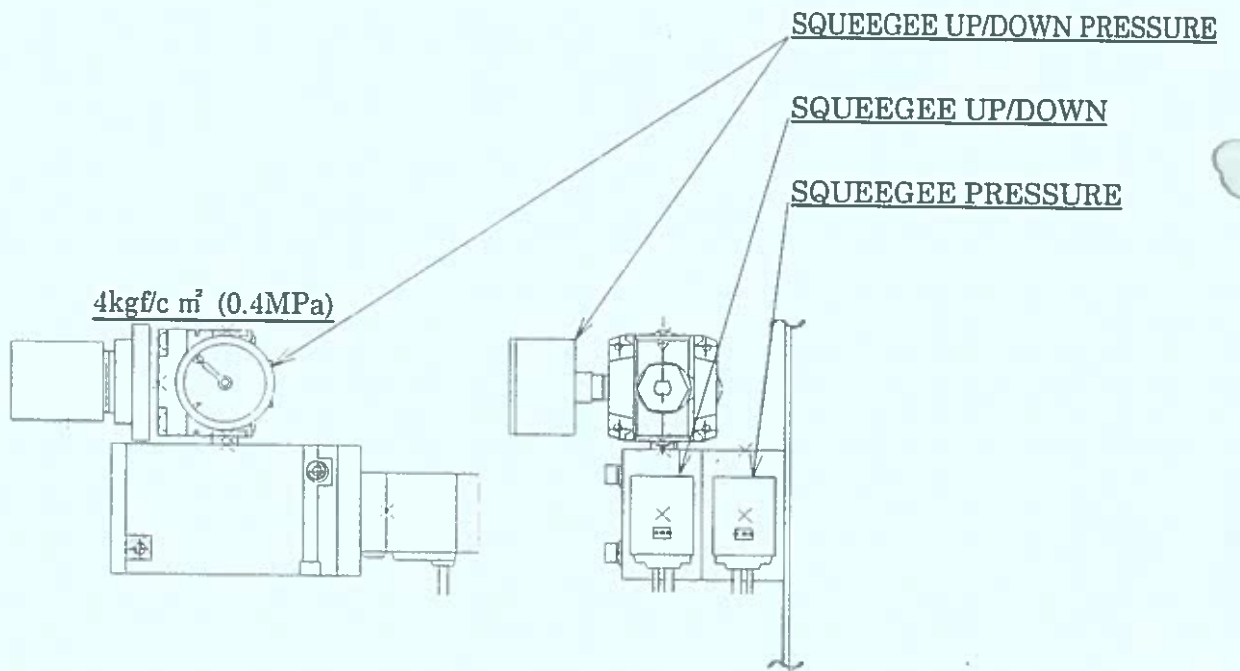
1-3-4 Detailed drawing of ③



1-3-5 Detailed drawing of ④



1-3-6 Detailed drawing of ⑤



Chapter2 Operation

2-1. Supplied electricity and air

2-1-1. Installation in Japan

Electricity AC200~220V, 3phase, 20A

2-1-2. Installation abroad

When CP-15 is installed in your country, put a transformer on it to adjust to Japanese supplied electricity.

Let us know the voltage in your country.

We will attach an appropriate transformer to CP-15.

- fn. 1 Keep the cause of noise away from CP-15.
- 2 Make sure that CP-15 is connected to the earth. (ϕ 4 or more)
- 3 The changing rate of supplied voltage must be within $\pm 15\%$.

2-1-3. Air supply

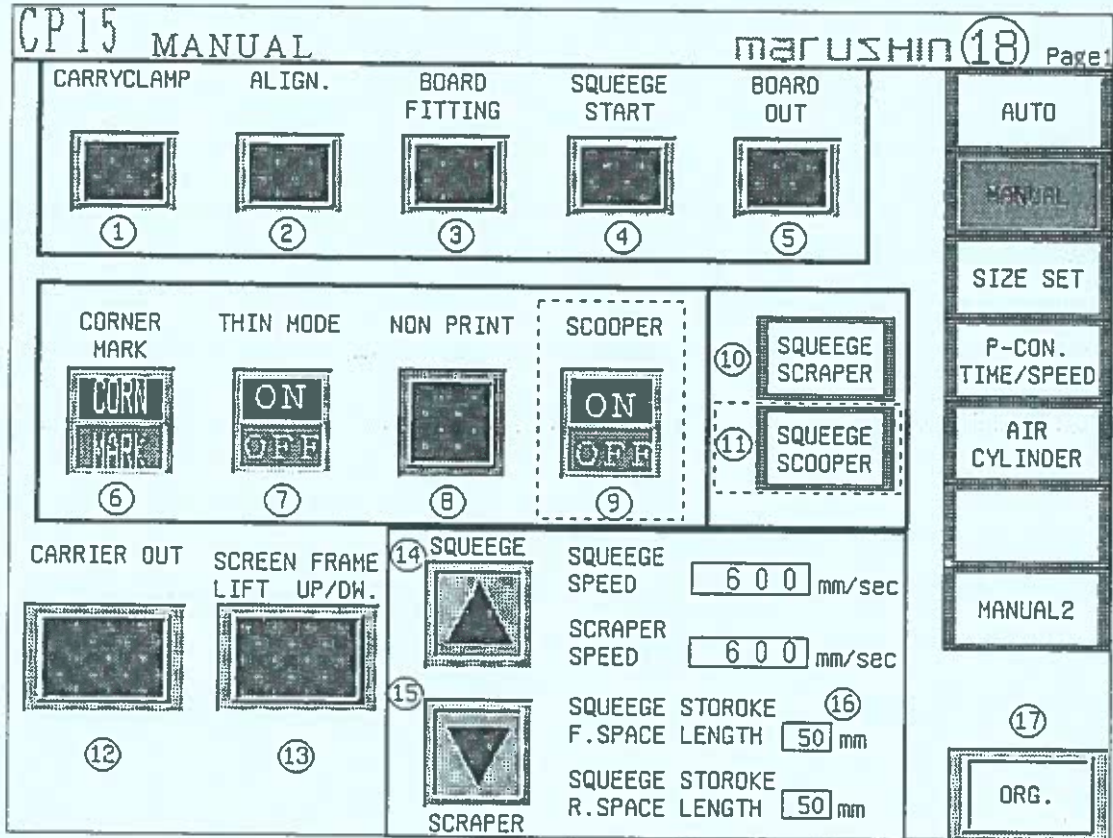
5kg/cm², 540nl/min

- fn. The changing rate of supplied air pressure must be within $\pm 15\%$, otherwise CP-15 could make an air-presser-down error and stop operation immediately.

2-2 How to operate Touch Panel(MANUAL)

2-2-1. How to operate Touch Panel

When CP-15 gets to turn on, the image below shows up on Operation Touch Panel.



For detailed explanation of the above keys, please refer each section as below.

①: M1

②: M2

③: M3

.....

⑰: M17

⑱: M18

Functions of all the keys of MANUAL image screen are as follows.

M1. **CARRY CLAMP** /Manual set up mode

Press **ORG** (⑰) to complete to return the cylinders and motors to the original positions, and press this key **CARRY CLAMP**. When this key gets pressed 3- axis Table moves to the original position and Carry-in Conveyor starts rotating to wait for PCB.

Siding and board-clamping are done after a PCB is carried in and stops at the center of Alignment Section (Carry-in Conveyor is stopped).

ALIGN key blinks in green after the movements are completed.

fn. Before pressing this key, **ORG** key (⑰) should be pressed to return cylinders and motors to the original position.

Carry-clamp/manual set-up mode is not available unless the original positions are returned.

Warning below is shown if this key is pressed without the return to the original position.

WARNING
NOT CYLINDER
ORIGINAL POSITION !
PUSH **ORG** KEY

M2. ALIGN.

When the movements of CARRY CLAMP are finished, this key ALIGN gets to blink in green.

Press the blinking key, so 3-axis Table aligns PCB within the limits of "Alignment allowance".

The movements are finished after a PCB is completed to align, BOARD-FITTING (③) blinks in green.

For the explanation of image processing on Touch Panel, refer to ch.2 § 4.

M3. BOARD FITTING

The movements of ALIGN are finished, and then this BOARD-FITTING gets to blink in green after alignment is completed..

If the blinking key is pressed, Carrier goes up to fix an aligned PCB by vacuum and carries it into PRINTING SECTION.

Use Micro-adjuster to adjust the position of Screen.

When the movements of BOARD-FITTING are completed, SQUEEGE-START (④) blinks in green.

M4. SQUEEGE START

This key, SQUEEGE-START gets to blink in green after board-fitting is completed. is completed.

Press the blinking key so that Screen Frame goes down and printing start .

BOARD OUT (⑤) blinks in green when the movements of SQUEEGE-START are completed.

M5. BOARD OUT

This **BOARD OUT** starts to blink in green when the movements of **SQUEEGE START** are completed.

Carrier carries out a printed PCB to Carry-out Conveyer when this blinking key gets pressed.

Carry-out Conveyer stops to check out the board.

Touch keys M1~M5 must be used on manual set-up.

fn. The keys (M1~M5) are used on manual set-up. These keys are not for auto-running. For auto-running, refer to ch.2 § 6.

M6. CORNER MARK

This key has below two modes. This key turns green from white when either mode gets chosen.

M6-1. CORNER

In this mode, PCB gets printed without alignment by camera.

If a PCB has no target mark or hole, use this mode.

M6-2. MARK

In this mode, PCB gets to be printed after alignment by camera.

fn. 1. This mode is available only on MANUAL mode, not on AUTO mode.

M7. THIN MODE

This key has below two modes. The key turns green from white when either mode gets chosen.

M7-1. 「ON」side ----- THIN MODE ON mode

This side is to be chosen for PCB thickness from 0.3 to 0.5mm.

When this mode is chosen, Step Action gets slow, so the tact time gets 20% longer than thicker board because of protection against edge-down.

M7-2. 「OFF」side ----- THIN MODE OFF mode

Turn this off when the board thickness is more than 0.5mm.

fn. This mode is available only on MANUAL mode, not on AUTO mode.

M8. NON PRINT

This key is used not to print PCB.

When this mode is on, the key turns green from white.

fn. 1. This mode is available only on MANUAL mode, not on AUTO mode.

M9. **SCOOPER** <option>

This key has below two modes to choose.

The key turns green from white when either On mode or OFF mode is chosen.

M9-1. 「ON」side ----- Scooper mode

Scooper carries printing ink to the front of Screen Frame.

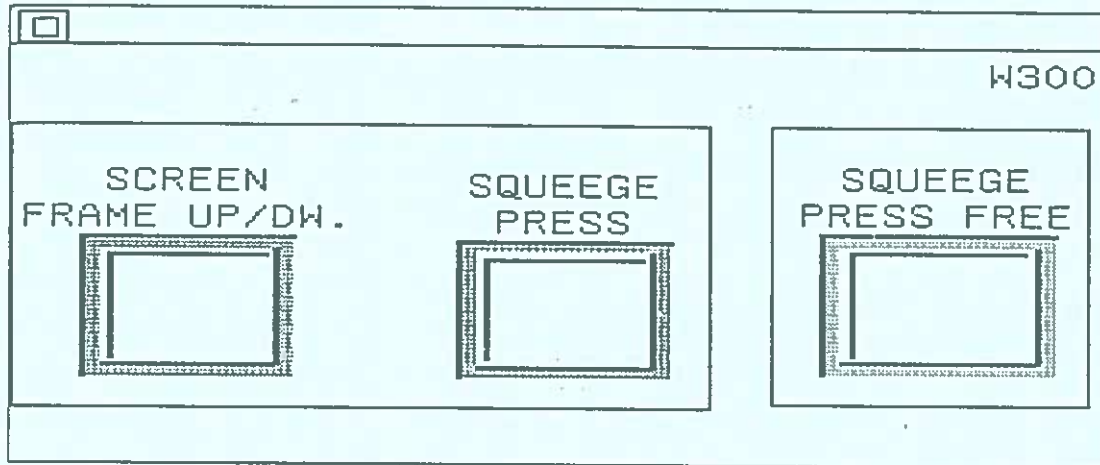
M9-2. 「OFF」side ----- Scraper mode

Scraper carries printing ink to the front of Screen Frame.

- fn.
1. This mode is available only on MANUAL mode, not on AUTO mode.
 2. Whenever the mode gets changed, mechanical part, Scraper or Scooper, also should be changed.
- If not, it causes mechanical damage or the tear of Screen.

M10. **SQUEEGE SCRAPER** ----- Scraper mode

This key is available when **SCOOPER** key is OFF.
Manual keys on Scraper mode are shown as below.



SCREEN FRAME UP/DW.

This key is used to move Screen Frame up/down.
Screen Frame goes up when this key gets pressed.
Screen Frame goes down when this key gets pressed again.

SQUEEGE PRESS

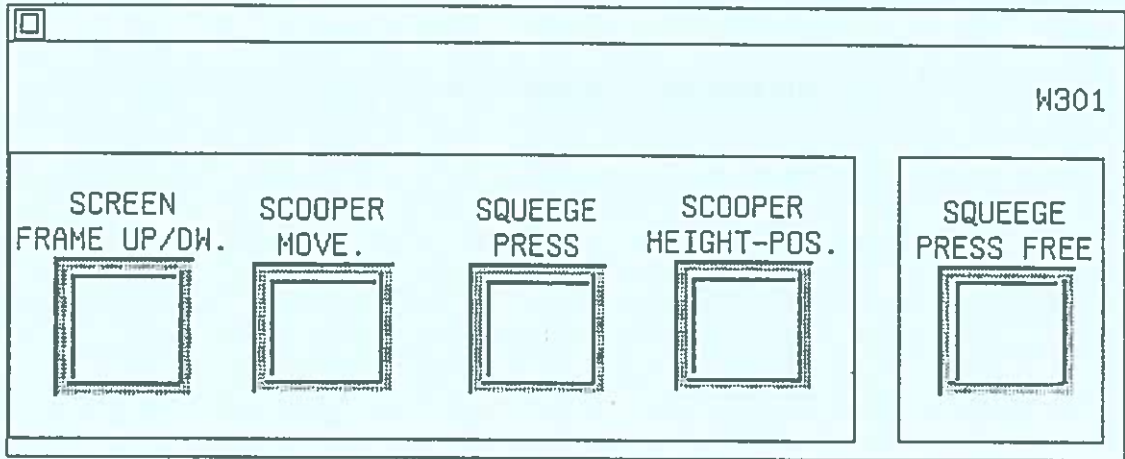
This key is to get Squeegee up and down.
This is used to make appropriate attach condition of Squeegee Rubber with Screen,
and check the squeegeing pressure.

SQUEEGE PRESS FREE

This key is used to cut off air pressure and to check a parallel between Squeegee Rubber
and Screen.

M11. **SQUEEGE SCOOPER** ----- Scooper mode

Scooper is available when **SCOOPER** key is on..
Manual keys on Scooper mode are shown as below.



SCREEN FRAME UP/DW.

This key is used to move Screen Frame up/down.
Screen Frame goes up when this key gets pressed. Screen Frame goes down when it gets pressed again..

SCOOPER MOVE

This key is to used to make Scooper scoop up and down..

SQUEEGE PRESS

This key is to get Squeegee up and down.
This is used to make an appropriate attach condition of Squeegee Rubber with Screen.
and check the squeegeing pressure.

SCOOPING POS.

This key is to move Squeegee Unit to the scooping position.

This position is to check Scooper and Squeegee Rubber height on scooping.

SQUEEGE PRESS FREE

This key is to cut off air pressure to adjust Screen Rubber parallel with Screen.

M12 **CARRIER OUT**

Carrier conveys out a PCB to Carry-out Section when this key gets pressed.

fn. This key is available only on MANUAL mode, not on AUTO mode.

M13. **SQUEEGEE FRAME UP/DW.**

Squeegee Frame goes up when this key gets pressed, and Squeegee Frame goes down .. when it gets pressed again.

While Squeegee Frame is moving, the key is green and it turns white when the movement is completed.

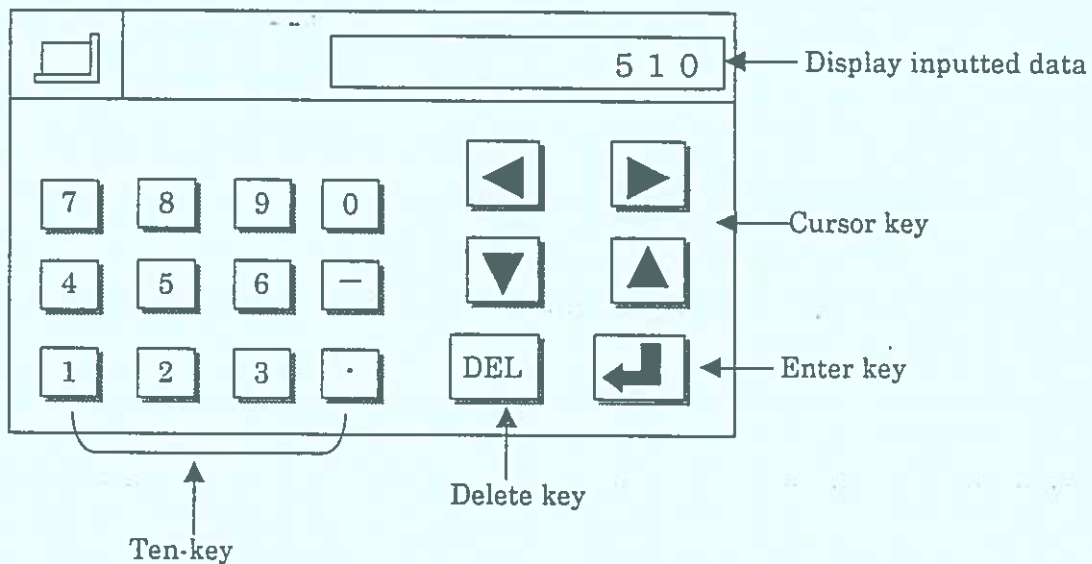
- fn.
- 1.This key is available only on MANUAL mode, not on AUTO mode.
In case of AUTO mode, use **SQUEEGEE FRAME LIFT UP/DW.** key on the image of AUTO mode .
 - 2.Squeegee Frame moves up automatically if anything intercepts Safety Area Sensor while Squeegee Frame is moving down.
Please get out of the space of Safety Area Sensor and press this key to get down Squeegee Frame again.

M14. **SQUEEGE**

Squeegee Unit moves backward while this key is pressed.

It moves at the displayed speed on the image.

To change the squeegee speed, touch " mm/sec" on the image and then, Ten Key Overlap Window shows up as below.



An example of inputting data:

Inputting 5, 1, 0, make the squeegee speed 510 mm/sec.

After the Squeegee speed gets inputted, Ten Key Overlap Window is gone automatically on pressing Enter key.

M15.  SCRAPER

Squeegee Unit moves forward while this key is pressed.

On pressed, this key turns green from white, and turns white back when it released.

It moves at the displayed speed on the image.

To change the squeegee speed, touch " mm/sec" on the image and then, Ten Key Overlap Window shows up.

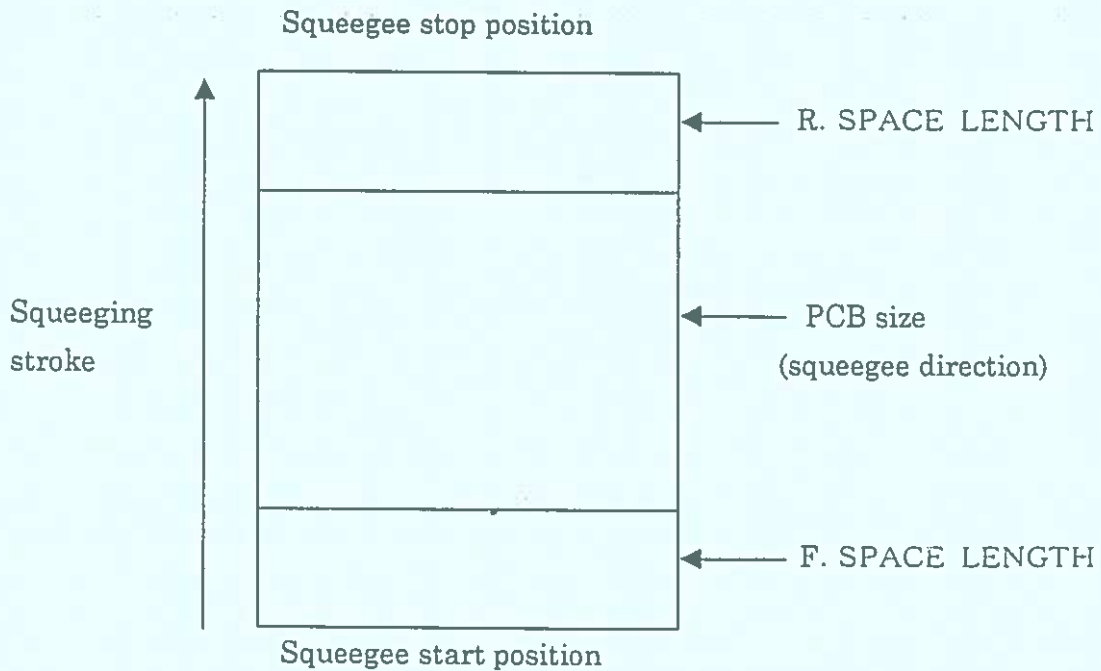
M16

SQUEEGE STROKE
F.SPACE LENGTH

and

SCRAPER SPEED
R.SPACE LENGTH

These are to input Front space length and Rear space length drawn as below.



M17. **ORG**

When this key gets pressed, all the cylinders except Screen Frame cylinder return to the original position and Carrier returns to IN- position.

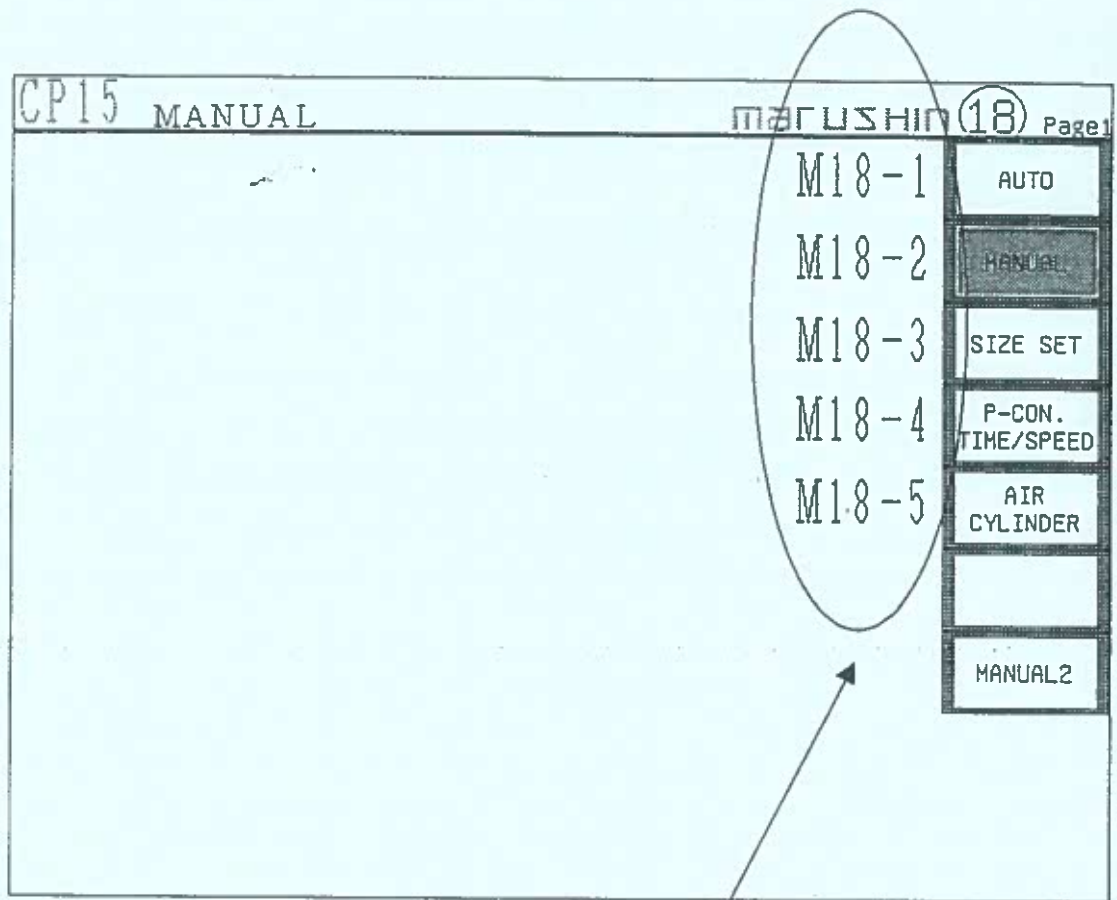
When all movements are completed, this key turns green from white.

If **ORG** key is not blinking in green, the mode can't be changed from **MANUAL** to **AUTO**.

Warning below gets shown on Overlap Window if **AUTO** key gets pressed without pressing **ORG** key.

WARNING
NOT CYLINDER
ORIGINAL POSITION !
PUSH **ORG** KEY

M18. Function key on MANUAL image



The function of each key is explained in these shown sections.

M18-1. **AUTO** key ----- Auto-running image shows up.

For more details, refer to ch.2 § 3 "How to operate Touch Panel(AUTO)"

fn. Make sure to press **ORG** (original position) key to return the cylinders and motors to the original position before turning from **MANUAL** mode to **AUTO** mode.

M18-2. **MANUAL** key ----- Manual image shows up.

When CP-15 turns on, **MANUAL** image shows up after initialization. **MANUAL** image also shows up if CP-15 gets any error or alarm on auto-running.

For more details, refer to ch. 2 § 2 "How to operate Touch Panel(MANUAL)".

M18-3. Explanation of **SIZE SET** key

The image below is shown when this key gets pressed.

On this image , PCB size and printing parameters can be registered.

CP15 SIZE SET		MARUSHIN (6) Page 4	
1	BOARD WIDTH(X) LENGTH(Y) SIZE 500 × 500	1 1	SQUEEGE PRESS 5.0 Kgf/cm ²
2	CAMERA MARK AX 123.456 mm	1 2	
3	CAMERA MARK AY 123.456 mm	1 3	SQUEEGE STROKE F. SPACE LENGTH 50 mm
4	CAMERA MARK BX 123.456 mm	1 4	SQUEEGE STROKE R. SPACE LENGTH 50 mm
5	CAMERA MARK BY 123.456 mm	1 5	
6	P-CON. TIMER (1) 0.1 Sec	1 6	(1)
7	GAP 3.6 mm	1 7	
8	OFF-CONTACT 10 mm	1 8	
9	SQUEEGE SPEED 700 mm/SEC	1 9	
1 0	SCRAPER, SCOOPER SPEED 700 mm/SEC	2 0	REGISTER No 12345678

(2) RECIPE DATA SEARCH NO 50	PC CARD ↓ PLC (3) DATA READ	PC CARD ↑ PLC (4) DATA REGISTER	(5) SIZE SET
---------------------------------	--------------------------------------	--	--------------

P-CON. JOG
SIDING JOG
CAMERA JOG
GAP JOG
CARRIER JOG
SQUEEGE JOG
RETURN

For detailed explanation of the above image, please refer to each section as below.

- ①: SZ1 ②: SZ2 ③: SZ3
- ④: SZ4 ⑤: SZ5 ⑥: SZ6

The touch keys **SIZE SET** and its contents are explained below. .

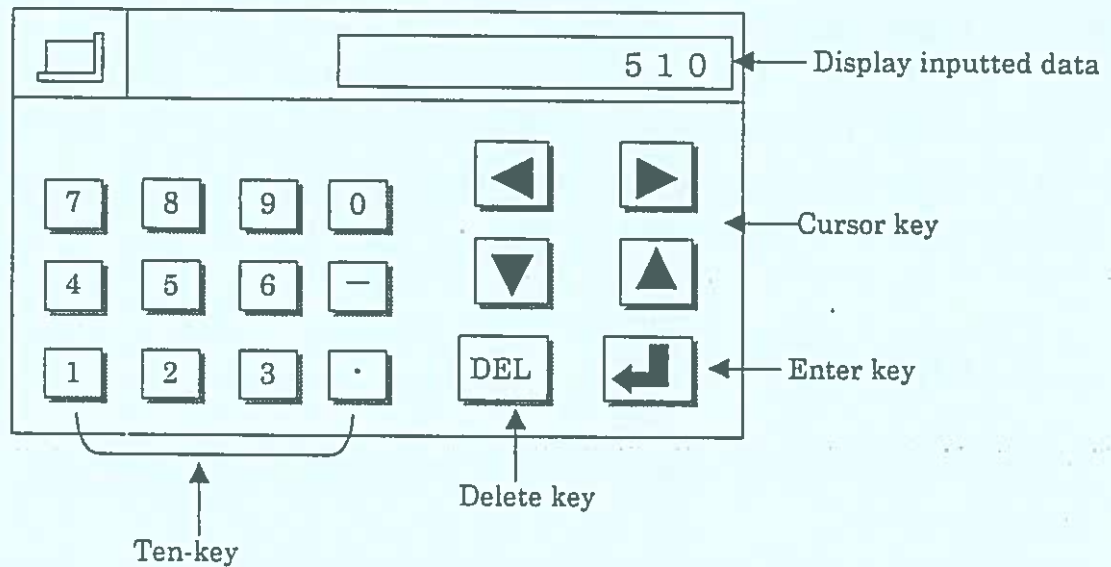
SZ1. PCB size and printing parameters can be registered on this menu.

- 1.BOARD SIZE ----- PCB size(mm).
- 2.CAMERA MARK AX ----- The position of A-CAMERA on X-axis(mm)
- 3.CAMERA MARK AY ----- The position of A-CAMERA on Y-axis(mm).
- 4.CAMERA MARK BX ----- The position of B-CAMERA on X-axis(mm)
- 5.CAMERA MARK BY ----- The position of B-CAMERA on Y-axis(mm)
- 6.P-CON. TIMER ----- Stop timer of Carry-in Conveyor from Board-in sensor is activated.
- 7.GAP ----- The clearance between Printing Table and Screen on printing.(Max. 10mm) .
- 8.OFF CONTACT ----- The pushing up value of Screen Frame on squeegeing (Max. 15mm)
- 9.SQUEEGE SPEED ----- Squeegeing speed (Max.720mm/sec.)
- 10.SCRAPER SCOOPER SPEED ----- Scraping/Scooping speed (Max.720mm/sec.)
- 11.SQUEEGE PRESS ----- The air pressure of squeegeing cylinder (kgf/cm)
- 13.SQUEEGE STROKE F.SPACE LENGTH ----- The front margin in squeegee stroke (mm)
- 14.SQUEEGE STROKE R.SPACE LENGTH ----- The rear margin in squeegee stroke (mm)

-20.REGISTER No.

----- User's product number of PCB
(Max.8 numbers).

To change value of each parameter, press each counter.
And then, Ten key Overlap Window as below turns up.



After each parameter gets inputted, Ten key Overlap Window is gone automatically on pressing Enter key.

SZ2. RECIPE DATA
SEARCH NO.

The present recipe No. is displayed. This display is to search the registered recipe No. or to register new parameters to the recipe No.

SZ3. PC CARD→PLC

This key is PLC reads registered recipe data from PC CARD.

While the data is read, the key is yellow. When the reading is finished, the key turns yellow off and the recipe data is changed.

SZ4. PC CARD←PLC

This key is PLC writes the recipe data in PC- CARD after the size and printing parameters are set.

While the data is written, the key is yellow. When the writing is finished, the key turns yellow off and the recipe data is saved in PC CARD.

- fn.
1. Make sure to write the changed parameters in PC CARD before turning off CP-15. Without the writing, the changed parameter and data get disappeared.
 2. Unwritten Recipe No. has no data.
 3. To change the registered recipe data, input new data and re-write in PC CARD.

SZ5. **SIZE SET**

Press this key to move each unit to the position according to inputted PCB size and printing parameters.

- 1. Writing in INPUT conveyor stop timer
- 2. Setting the position of siding units
- 3. Setting A/B-camera positions
- 4. Setting Squeegee stroke and speed
- 5. Setting GAP amount
- 6. Writing OFF-CONTACT amount

While each unit moves to the position, this key turns green. The key turns white when the position set-up is completed. Over Lap Window below is showed while setting up.

- fn.
1. It takes about 40 seconds to complete the movement.
 2. Please confirm to write in PC-CARD from PLC to register the recipe after setting the size of PCB and printing conditions.
 3. Please confirm to match the read recipe No. to user's management No.

SZ6. **SIZE SET**

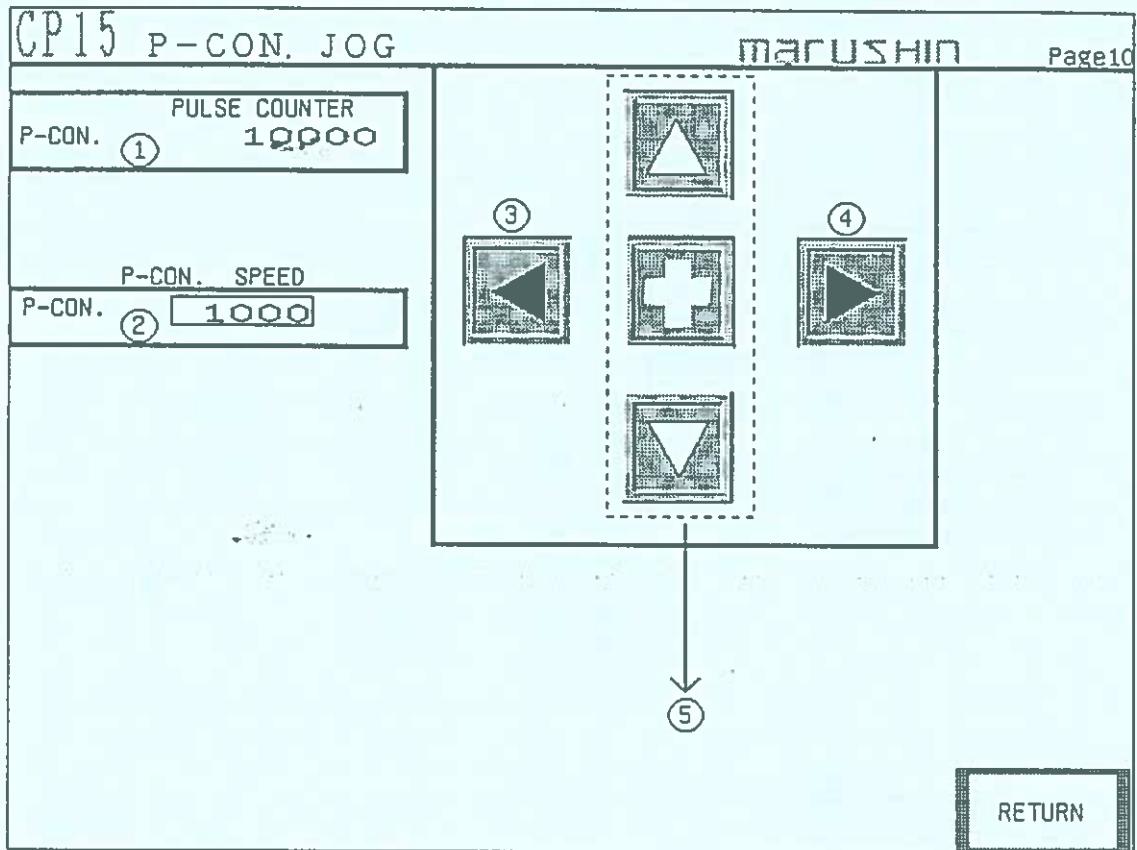
Function keys on **SIZE SET** image are explained next.

CP15	SIZE SET	marUSHIN (6) Page 4
	SZ-6-1	P-CON. JOG
	SZ-6-2	SIDING JOG
	SZ-6-3	CAMERA JOG
In these No. section, the function of each key is explained.	SZ-6-4	GAP JOG
	SZ-6-5	CARRIER- JOG
	SZ-6-6	SQUEEGE JOG
		RETURN

SZ6-1. EXPLANATION OF P-CON. JOG KEY

This is the image of Carry-in Conveyor jog feed.

The image of P-CON.JOG is down as below.



PC 1. P-CON. PULSE COUNTER -----The present value of Carry-in Conveyor is display on this counter. [ex.] 100PULSE=about 45mm

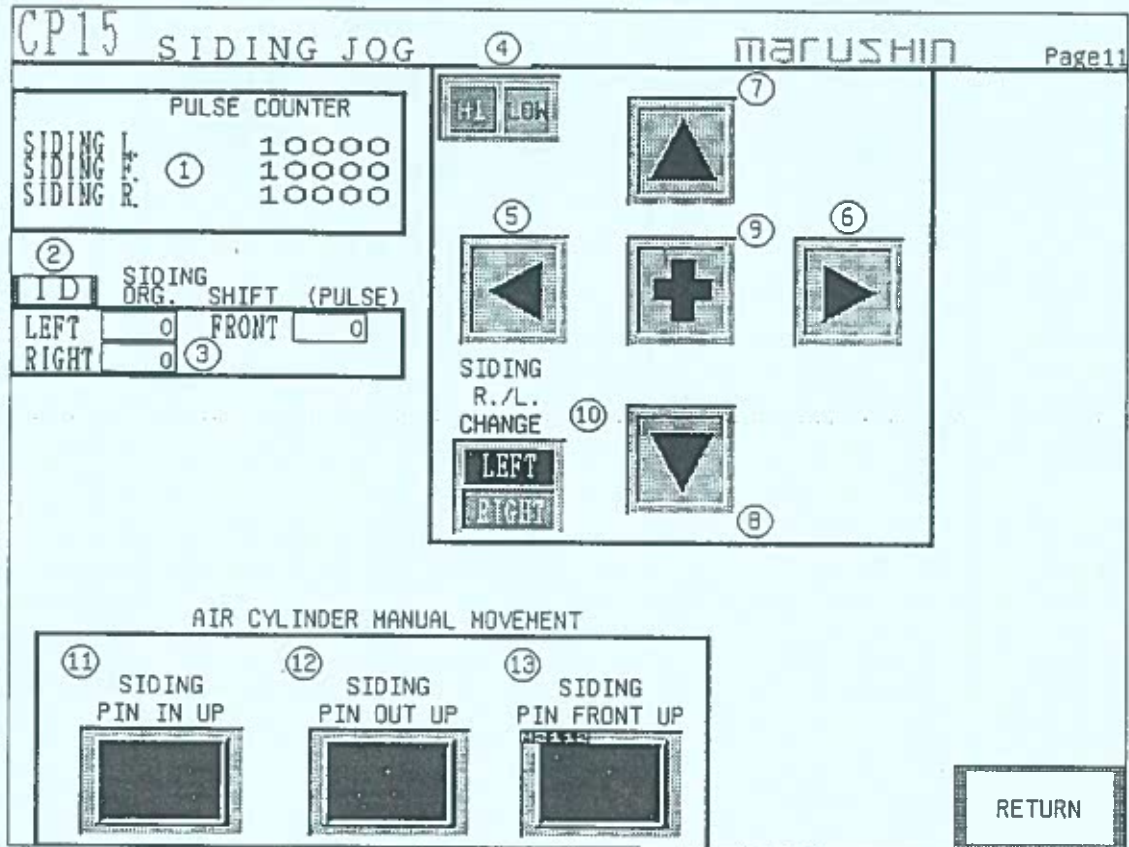
PC2. P-CON. SPEED ----- Setting the speed of Carry-in Conveyor in pulse

PC3.  JOG key ----- This key is to move Carry-in Conveyor leftward on jog feed .

PC4.  JOG key ----- This key is to move Carry-in Conveyor rightward on jog feed.

PC5.    ----- These keys can't be used on this image.

SZ6-2. **SIDING JOG** KEY ----- This is the image of Siding Unit jog feed.
 The image of **SIDING JOG** is drawn as below.



For detailed explanation of the above image, refer to each section as below.

- ① : SD1
- ② : SD2
- ③ : SD3
-
- ⑫ : SD12
- ⑬ : SD13

The image of **SIDING JOG** is explained below..

SD1. **PULSE COUNTER** ----- The present value of each Siding axis is shown in pulse.

SIDING L. ----- The present value of pulse motor for left-reference.

SIDING F. ----- The present value of pulse motor on front.

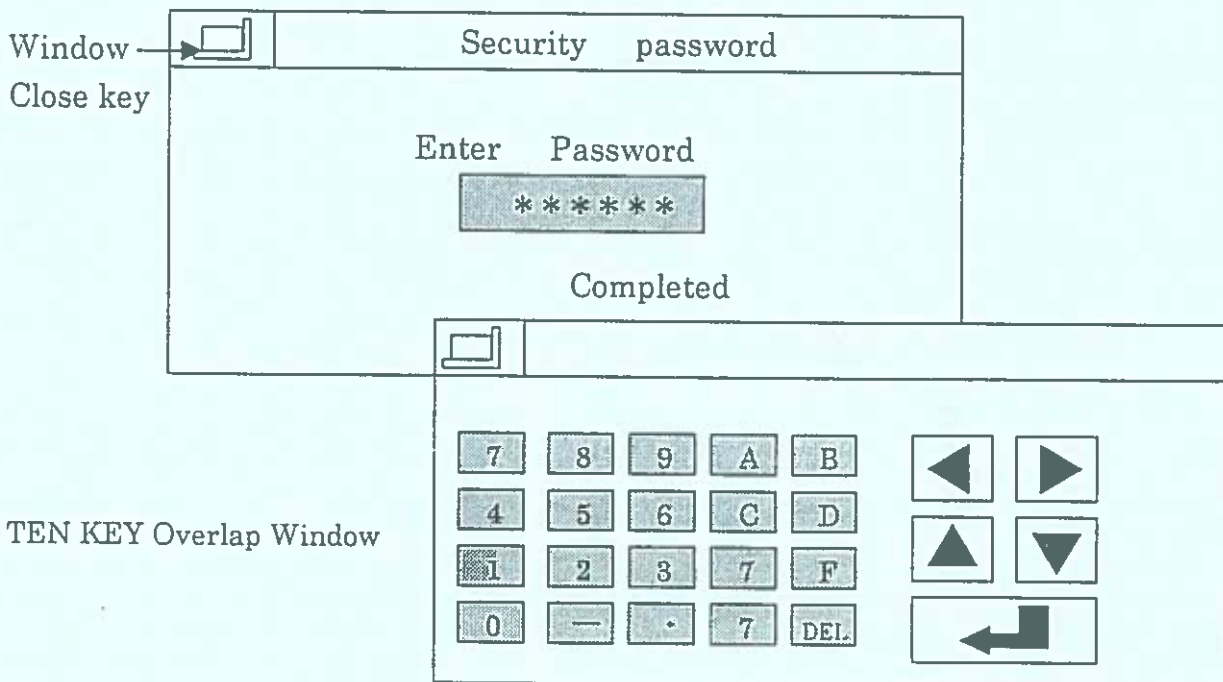
SIDING R. ----- The present value of pulse motor for right-reference.

SD2. **ID**

The original position of stoppers can be changed intentionally. Original position shift is to change the original point of Siding axis electrically.

Before changing the original position, **ID**No. must be inputted to unlock the security.

The inputted number is not shown on Touch Panel.



If the password is incorrect, the message below shows up.

"UNMATCHED PASSWORD"

In this case, delete it by **DEL** key, and input the correct one. After inputting the correct password, press Window close key to get back to **SIDING JOG** image.

SD3. SIDING ORG. SHIFT (PULSE)

Press the counter of each siding, then Ten Key Overlap Window turns up to input original position shift in pulse. For example, 100 pulses equal about 6.3mm. After its completion, turn off CP-15 and turn it on again to Siding to the new original position. And check out that original position is changed.

SD4. SIDING moving speed HI & LOW

This key is to choose HI or LOW speed on jog feed.

HI ----- 126 mm/sec
LOW ----- 6.3mm/sec

SD5. SIDING KEY ◀

This is flowing-direction jog feed key of siding stopper chosen on SD10.
Feeding direction is leftward.

SD6. SIDING KEY ▶

This is flowing-direction jog feed key of siding stopper chosen on No. SD 10.
Feeding direction is rightward.

SD7. SIDING KEY △

This is queeging-direction jog feed key of siding front stopper.
Feeding direction is backward.

SD8. SIDING KEY ▽

This is queeging-direction jog feed key of siding front stopper.
Feeding direction is forward.

SD9. SIDING KEY 

This key is to return all Siding pins to the original position.

SD10. SIDING R./L. CHANGE

It's possible to choose right or left reference on both-reference option. The chosen reference is shown on auto-running image.

LEFT Left reference

RIGHT Right reference

SD11. L.SIDING PIN UP

Left siding pin pops up when this key gets pressed.

This key turns green with the pin up. When this key gets pressed again, the pin goes down and this key turns white back.

SD12. R.SIDING PIN UP

Right siding pin pops up when this key gets pressed.

This key turns green with the pin up. When this key gets pressed again, the pin goes down and this key turns white back.

SD13. F.SIDING PIN FORWARD

Front siding pins move toward the center when this key gets pressed.

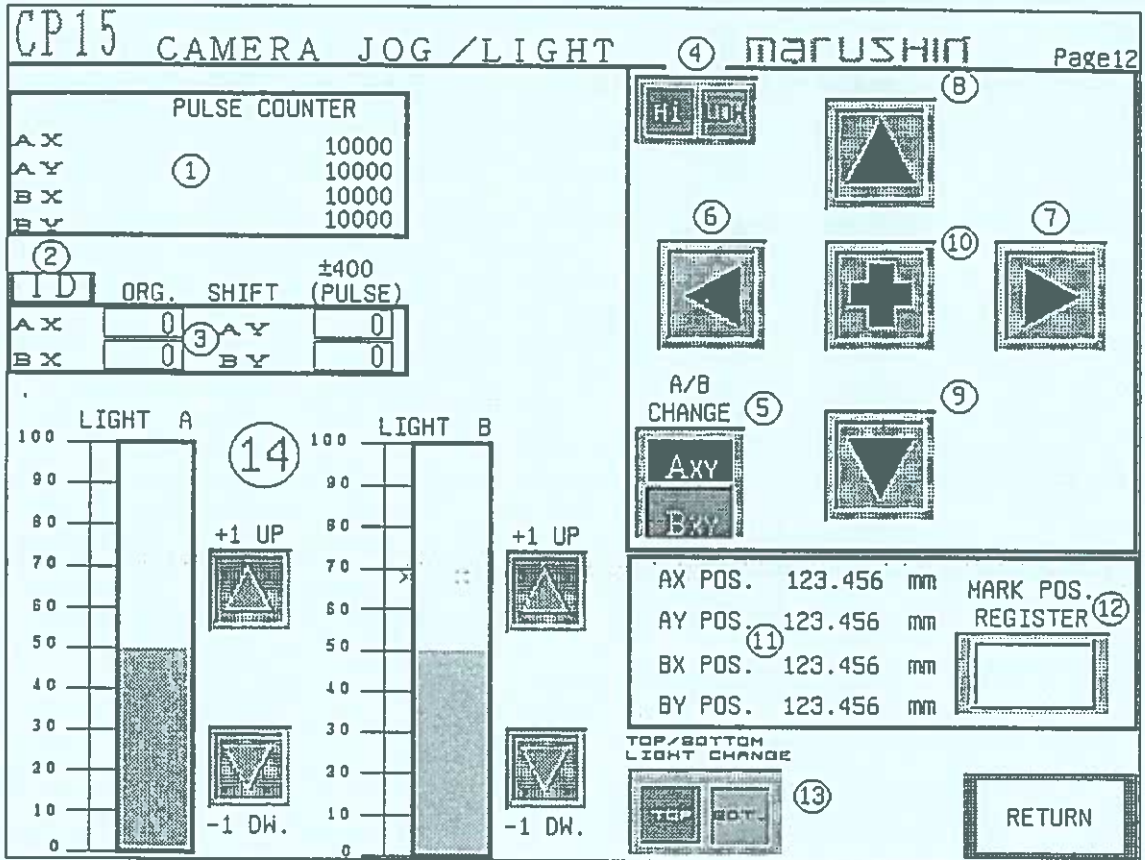
This key is green with the pins moving.

When this key gets pressed again, the pins move away from the center and this key turns white back.

SZ 6-3. CAMERA JOG KEY

The below image turns up when this key gets pressed.

The image of CAMERA JOG/LIGHT is drawn below.



For detailed explanation of the above image, refer to each section as below.

①: CM1

②: CM2

③: CM3

⑬: CM13

⑭: CM14

CM1. PULSE COUNTER

This is the pulse counter of present position of A/B-Camera. (unit:pulse)

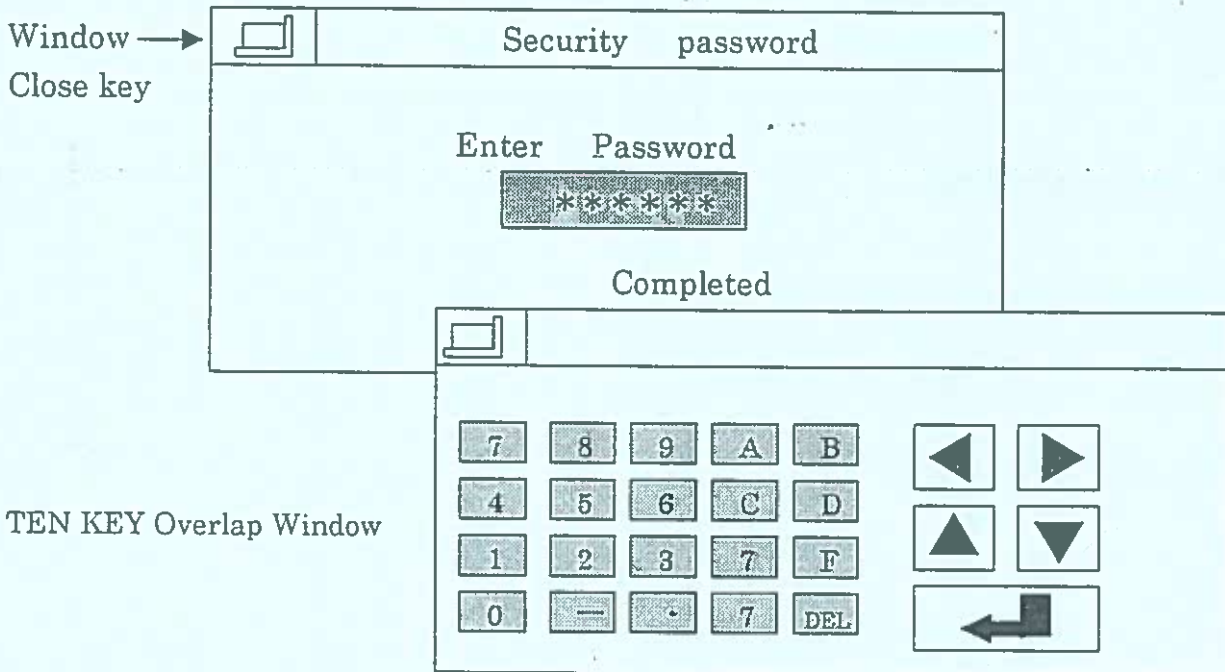
CM2. ID

The position of the origin can be changed intentionally. Origin shift is to change the original point of A/B-Camera electrically.

Before changing the data, ID and NO, *****(6figures) must be pressed.

ID No. is a security password, the inputted number is not shown on touch panel.

Password, Ten Key Overlap Window pops up by pressing this ID key.



Input a security password (6 figures) with Ten Key.

The message below turns up if the inputted password was incorrect.

"UNMATCHED PASSWORD"

In this case, delete it with DEL key and input the correct one.

When the correct password is inputted and Window Close key gets pressed, the image gets back to CAMARA JOG.

CM3. **ORG. SHIFT (PULSE)**

Input the origin shift in pulse on Ten Key Overlap Window.

For example, 100 pulses equal about 0.5mm of origin shift.

After setting is completed, turn off CP15 and turn it on again to set the new original point.

Check the position of the origin is moved.

CM4. **HI** , **LOW** KEY

This key is to choose HI or LOW speed of camera on jog feed .

HI 10 mm/sec.

LOW 0.5mm/sec.

CM5. **A/B CHANGE** KEY

This key is to choose A or B Camera .

AXY Choice of A-Camera

BXY Choice of B-Camera

CM6. CAMERA JOG KEY 

This is X axis jog feed key chosen camera on CM5 key.

The feeding direction is leftward in flowing .

CM7. CAMERA JOG KEY 

This is X axis jog feed key chosen camera on CM5 key.

The feeding direction is rightward in flowing.

CM8. CAMERA JOG KEY 

This is Y axis jog feed key chosen camera on CM5 key.
The feeding direction is backward in squeeing.

CM9. CAMERA JOG KEY 

This is Y axis jog feed key chosen camera on CM5 key.
The feeding direction is forward in squeeing.

CM10. CAMERA JOG KEY 

This is the key to the chosen camera onCM5.to return the original position.

CM11. The present positions of A/B-Camera are shown as below. (unit: mm)

CAMERA AX POS.

The present position of the X axis of A-Camera

CAMERA AY POS.

The present position of the Y axis of A-Camera

CAMERA BX POS.

The present position of the X axis of B-Camera

CAMERA BY POS.

The present position of the Y axis of B-Camera

CM12.

MARK POS. REGISTER

 KEY

This key is used to register the camera position on

SIZE SET

 image after setting A/B-CAMERA by jog feeding.

CM13. TOP/BOTTOM
LIGHT CHANGE KEY

This switch is to choose Top or Bottom light.

TOP. ----- Top light

BOT. ----- Bottom light

CM14. LIGHT A & LIGHT B KEY

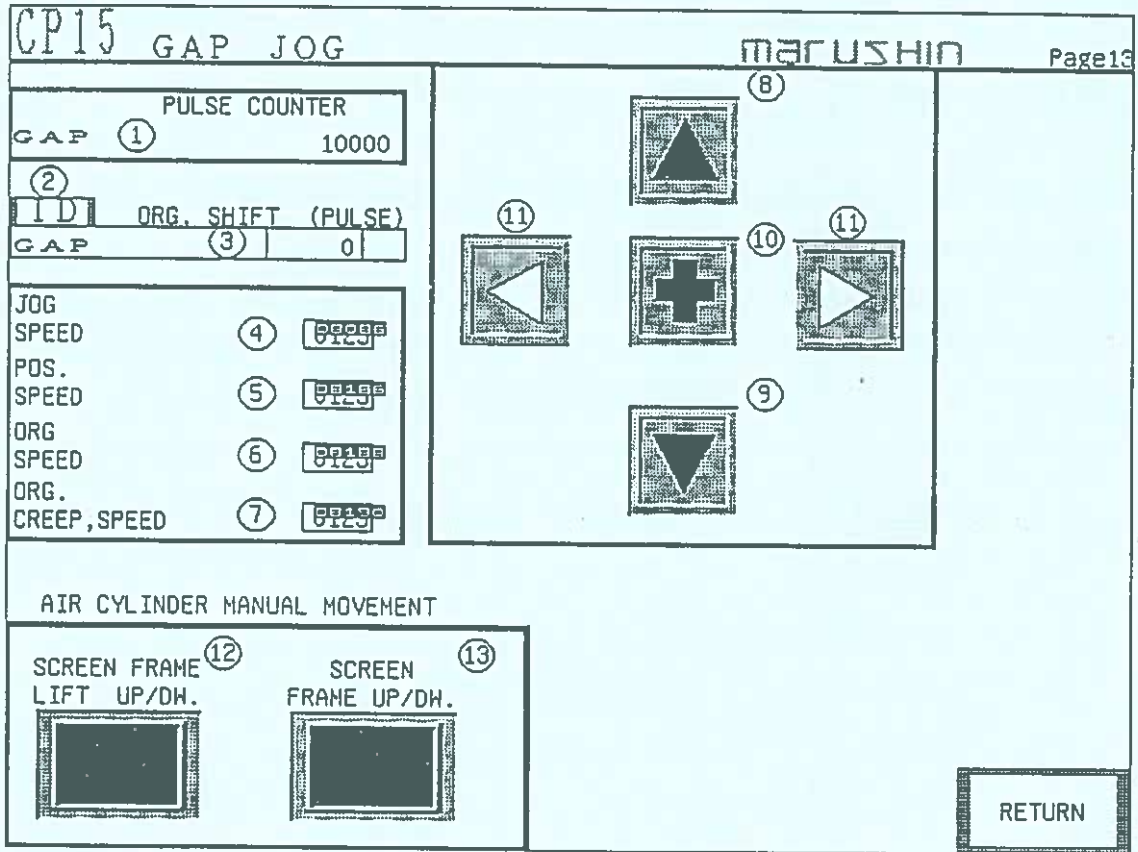
These are to adjust the light level of A/B-Camera.

The bar graphs under LIGHT A&B show the present light level and the range is from 0 % to 100%. On changing the light level greatly, touch this bar graph.

Use △ +1 UP, ▽ -1 DW to change by each percent.

SZ6-4. **GAP JOG** KEY

This is the image of Screen Gap jog feed. The image of **GAP JOG** is drawn below.



For detailed explanation of the above image, refer to each section as below.

- ①: GP1
- ②: GP2
- ③: GP3
- ⋮
- ⑫: GP12
- ⑬: GP13

The image of **GAP JOG** is explained below.

GP1. **PULSE COUNTER** (unit: pulse)

The present value of Screen Gap is showed on this counter.

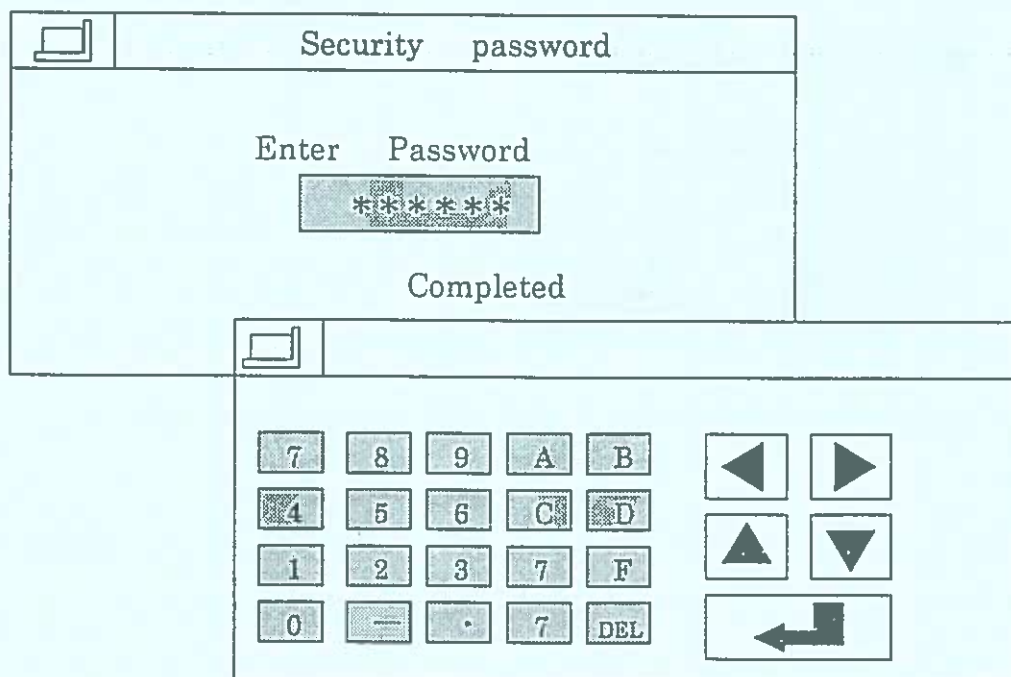
GP2. **ID** (unit pulse)

The original position of Screen Gap can be changed intentionally. Origin shift is to change the original point of Screen Gap unit electrically.

Before changing the data, **ID** and **NO, * * * * *** (6figures) must be pressed.

ID No. is a security password, the inputted number is not shown on touch panel.

Password, Ten Key Overlap Window pops up by pressing this **ID** key:



Input a security password (6 figures) with Ten Key.

The message below turns up if the inputted password was incorrect.

„UNMATCHED PASSWORD„

In this case, delete it with **DEL** key and input the correct one.

When the correct password is inputted and Window Close key gets pressed, the image gets back to **GAP JOG**.

GP3. **GAP ORG. SHIFT(PULSE)**

Input the origin shift in pulse on Ten Key Overlap Window.

For example, 100 pulses equal about 0.005mm of origin shift.

After setting is completed, turn off CP15 and turn it on again to set the new original point.

0.005mm-moved position from the original position turns new original position.

Confirm that the original position is moved.

GP4. **JOG SPEED**

This display shows the present jog feed speed of GAP. To change the speed, touch the present value. Then, Ten Key Overlap Window pops up.

GP5. **POS. SPEED**

This display shows the setting speed to the set position of GAP. To change the speed, touch the present value. Then, Ten Key Overlap Window pops up.

GP6. **ORG. SPEED**

This display shows the returning speed of GAP to the original position.

To change the speed, touch the present value. Then, Ten Key Overlap Window pops up.

GP7. **ORG. CREEP SPEED**

This display shows the creep speed of GAP to return GAP to the original position.

To change the speed, touch the present value. Then, Ten Key Overlap Window pops up.

GP8. SCREEN GAP KEY 

This is the jog key of Screen GAP. It moves upward.

GP9. SCREEN GAP KEY 

This is the jog key of Screen GAP. It moves downward.

GP10. SCREEN GAP KEY 

This is the key to return Screen GAP to the original position mechanically.

GP11. SCREEN GAP KEY  

These keys can't be used on  image.

GP12. 

Squeegee Frame goes up to the limit when this key gets pressed. Squeegee Frame goes down to the lowest point when it gets pressed again. While Squeegee Frame moving, this key remains green. After the moving is completed, this key turns white back.







GP13. 

Screen Frame goes to the down position when this key gets pressed. Squeegee Frame goes to up position when it gets pressed again. While Squeegee Frame moving, this key remains green. After the moving is completed, this key turns white back.

SZ6-5. **CARRIER JOG** KEY

This is the image of the jog feed of Carrier.

The image of **CARRIER JOG** is drawn as below.

CP15 CARRIER JOG		MARUSHIN		Page14
PULSE COUNTER				
CARRIER ①	180000			
CARRIER TORQUE ②		600 mV 60 %		
ID ③				
POS 1(IN) ④	110000			
POS 2(OUT) ⑤	500			
ORG. SHIFT ⑥	0			
CARRIER JOG SP. ⑦	1000			
CARRIER POS. SP. ⑧	350000			
		<div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>⑨</p>  </div> <div style="text-align: center;"> <p>⑫</p>  </div> <div style="text-align: center;"> <p>⑩</p>  </div> </div> <div style="display: flex; justify-content: space-around; align-items: center; margin-top: 10px;"> <div style="text-align: center;"> <p>⑬</p> <p>SERVO TEST START</p>  </div> <div style="text-align: center;"> <p>⑫</p>  </div> <div style="text-align: center;"> <p>⑭</p> <p>SERVO TEST OFF</p>  </div> </div>		
		RETURN		

For detailed explanation of the above image, refer to each section as below.

①: CR1

②: CR2

③: CR3

⑬: CR13

⑭: CR14

The image of CARRIER JOG is explained below.

CR1. PULSE COUNTER

The present value of Carrier position is shown on this counter.

CR2. CARRIER TORQUE

The servo motor torque of Carrier is shown. The appropriate torque ranges is from 50% to 80%.

fn.1. If the torque gets over 100%, CP- 15 makes a servo-motor-overloaded alarm. Make sure to keep it from 50% to 80%.

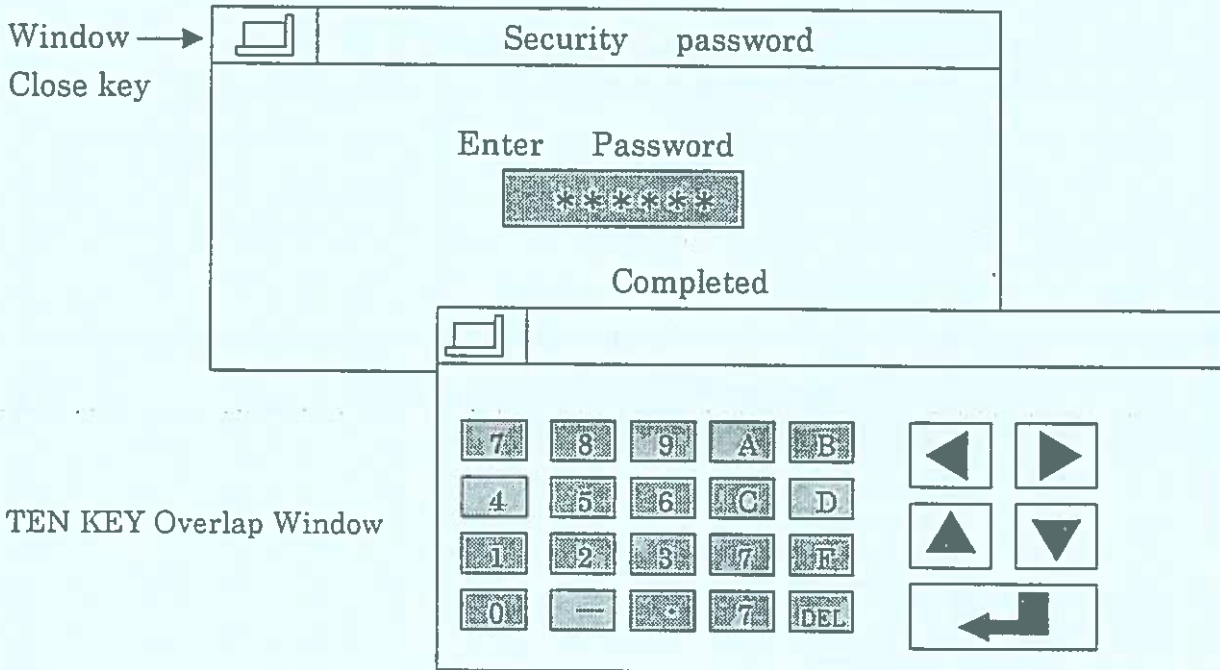
CR3. ID

The position of the origin can be changed intentionally. Origin shift is to change the original position of Carrier electrically.

Before changing the data, ID and NO, ***** (6figures) must be pressed.

ID No. is a security password, the inputted number is not shown on touch panel.

Password, Ten Key Overlap Window pops up by pressing this ID key.



Input a security password (6 figures) with Ten Key.

The message below turns up if the inputted password was incorrect.

"UNMATCHED PASSWORD"

In this case, delete it with DEL key and input the correct one.

When the correct password is inputted and Window Close key gets pressed, the image gets back to CARRIER JOG.

CR4. POS 1 (IN)

This is the position pulse data of Carrier servo motor at IN-side.

To change it, input IDNo. surely. For details how to input IDNo., refer to CR3.

CR5. POS 2 (OUT)

This is the position pulse data of Carrier servo motor at OUT-side.

To change it, input IDNo. surely. For details how to input IDNo., refer to CR3.

CR6. ORG. SHIFT

Press the counter of the key, so Ten key Overlap Window turns up to input origin shift in pulse. For example, 100 pulses equal about 0.478 mm. After its completion, turn off CP-15 and turn it on again to set the new original position.

And check out the origin is moved.

CR7. CARRIER JOG SP.

This display shows the jog feed speed of Carrier.

To change the speed, touch the present value. Then, Ten Key Overlap Window pops up.

CR8. CARRIER POS. SP.

This key shows the speed of setting the position of Carrier.

To change the speed, touch the present value. Then, Ten Key Overlap Window pops up.

CR9. CARRIER JOG KEY 

This is the jog feed key of Carrier. It moves leftward.

When the key No. CR14 SERVO TEST is on, this key gets Carrier to the IN-position.

CR10. CARRIER JOG KEY 

This is the jog feed key of Carrier. It moves rightward.

When the key No. CR14 SERVO TEST is on, this key gets Carrier to the OUT-position.

CR11. CARRIER JOG KEY 

This key returns Carrier to the original position mechanically.

CR12. CARRIER JOG KEY  

These keys can't be used on CARRIER JOG .

CR13. SERVO TEST START KEY

Press this key to test-run Carrier IN and OUT automatically. Make sure to turn on No. CR14 SERVO TEST is ON, otherwise test-running of Carrier can't start.

CR14. SERVO TEST

This key is to choose moving Carrier by jog feed or by each set position data.

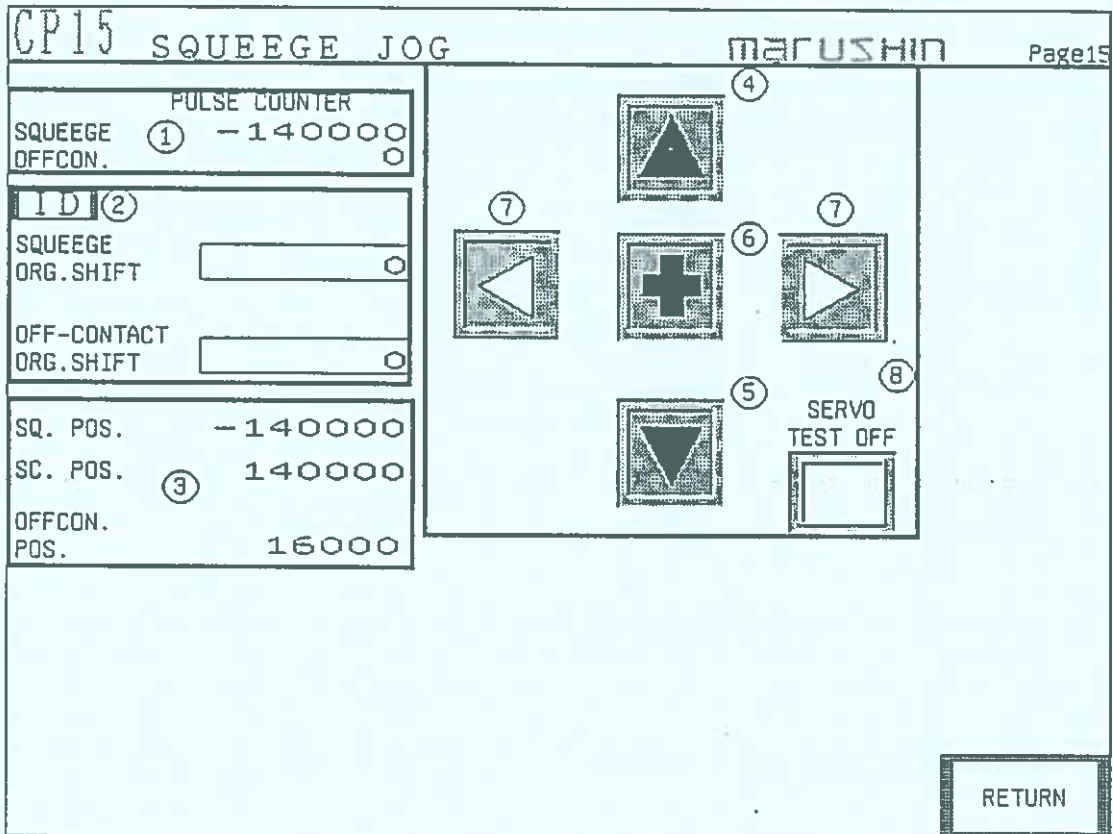
ON -----By set position data

OFF -----By jog feed

SZ6-6. SQUEEGE JOG KEY

This is the image of Squeegee and Off-Contact axis.

The image of SQUEEGEE JOG is drawn below



For detailed explanation of the above image, refer to each section as below.

①:SE1

②:SE2

③:SE3

⑦:SE7

⑧:SE8

The image of **SQUEEGEE JOG** is explained below.

SE1. **PULSE COUNTER**

The present position of Squeegee and Off-Contact are shown on this pulse counter.

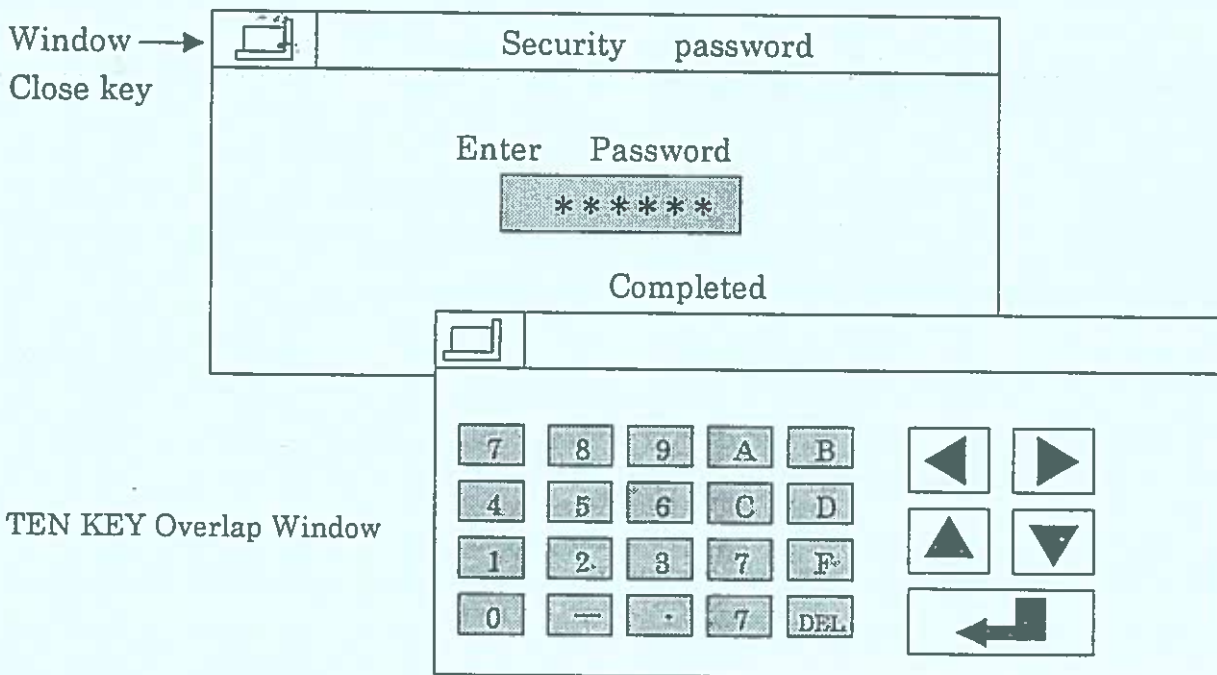
SE2. **ID**

The position of the origin can be changed intentionally. Origin shift is to change the original position of Squeegee and Off-Contact electrically.

Before changing the data, **ID** and **NO, ***** (6figures)** must be pressed.

ID No. is a security password, the inputted number is not shown on touch panel.

Password, Ten Key Overlap Window pops up by pressing this **ID** key.



Input a security password (6 figures) with Ten Key.

The message below turns up if the inputted password was incorrect.

"UNMATCHED PASSWORD"

In this case, delete it with **DEL** key and input the correct one.

When the correct password is inputted and Window Close key gets pressed, the image gets back to **SQUEEGEE JOG**.

SQUEEGE ORG. SHIFT

Press the counter, so Ten key Overlap Window turns up to input origin shift in pulse.
For example, 100 pulses equal about 0.245 mm. After its completion, turn off CP-15 and turn it on again to set the new original position.
And check out the origin is moved.

OFF-CONTACT ORG. SHIFT

Press the counter, so Ten key Overlap Window turns up to input origin shift in pulse.
For example, 100 pulses equal about 0.06 mm. After its completion, turn off CP-15 and turn it on again to set the new original position.
And check out the origin is moved.

SE3. SQ. POS., SC. POS., OFFCON. POS.

SQ. POS. ----- The display of starting position of Squeegee
SC. POS. ----- The display of ending position of Squeegee
OFFCON. POS. --- The display of the amount of Off-Contact

fn. The displays above can't be changed deliberately. These are automatically changed by setting the size of PCB and the amount of Off-Contact in SIZE SET image.

SE4. SQUEEGE JOG KEY 

This is the jog feed key of Squeegee and Off-Contact.

Squeegee ----- backward direction

Off-Contact ----- up direction

When **SERVO TEST** is ON, Squeegee and Off-Contact simultaneously move to the set position.

SE5. SQUEEGE JOG KEY 

This is the jog feed key for Squeegee and Off-Contact.

Squeegee ----- forward direction

Off-Contact ----- down direction

When **SERVO TEST** is ON, Squeegee and Off-Contact simultaneously move to the set position.

SE6. SQUEEGE JOG KEY 

This key returns Squeegee and Off-Contact to the original position mechanically.

SE7. SQUEEGE JOG KEY  

These keys can't be used on **SQUEEGE JOG**.

SE8. SERVO TEST

This key is to choose moving Squeegee and Off-Contact by jog feed or by each set position data.

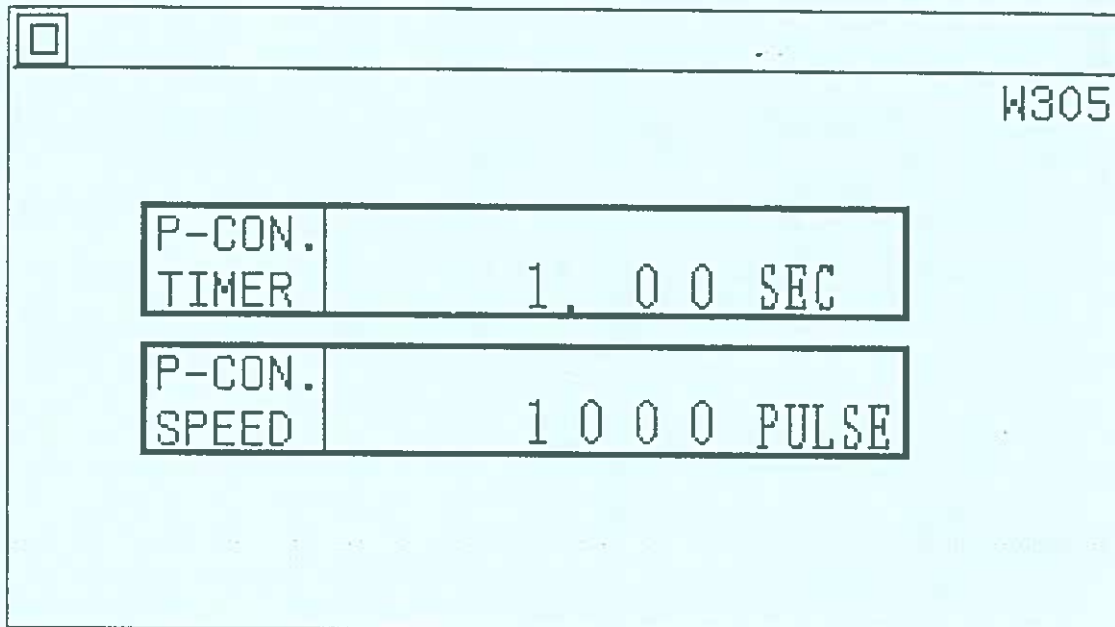
ON -----By set position data

OFF -----By jog feed

M18-3. **P-CON. TIME/SPEED** KEY

Setting the rotating time and the speed of Carry-in Conveyor .

When this key gets pressed, the below window pops up.



P-CON. TIMER (unit: sec.)

This timer is to stop Carry-in Conveyor from the Board-in sensor gets activated.

Press the counter to input a new value. Then, Ten-Key Overlap Window pops up.

P-CON. SPEED (unit: pulse)

This display shows Carry-in Conveyor speed (Unit pulse)

Press the counter to input a new value. Then, Ten-Key Overlap Window pops up.

M18-5. AIR CYLINDER KEY

On this image, each cylinders can gets moved separately.

It is used to check the movement.

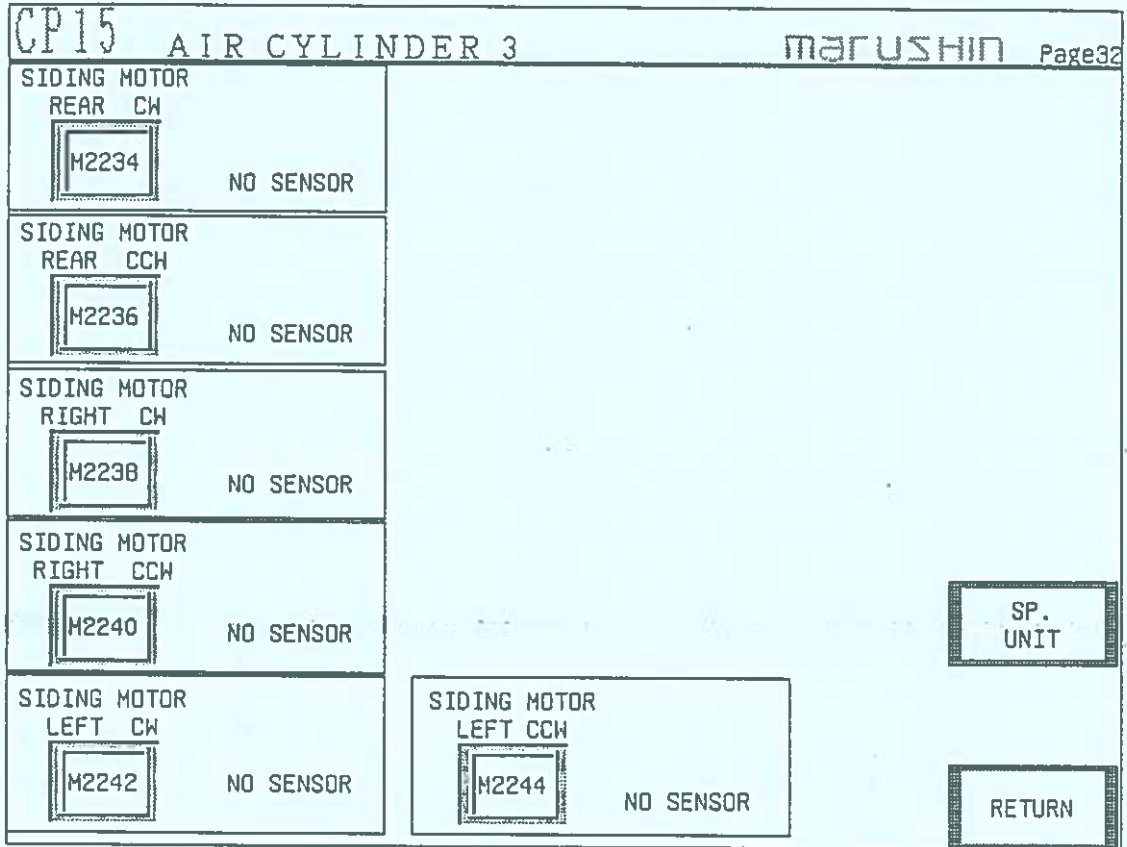
The below image is AIR CYLINDER 1

CP15 AIR CYLINDER 1		MARUSHIN Page30	
<p>SCREEN FRAME LIFT UP/DW.</p> <p>M2052</p> <p>X04F UP SENSOR</p> <p>X04E DW. SENSOR</p>	<p>SCREEN FRAME UP/DW.</p> <p>M2064</p> <p>X050 (REAR) UP SENSOR</p> <p>X051 (REAR) DW. SENSOR</p> <p>X059 (FRONT) UP SENSOR</p> <p>X05A (FRONT) DW. SENSOR</p>		
<p>SCREEN HOOK ON</p> <p>M2216</p> <p>NO SENSOR</p>	<p>SQUEEGE PRESS</p> <p>M2062</p> <p>NO SENSOR</p>		
<p>ALIGNMENT TABLE/UP/DW.</p> <p>M2202</p> <p>X040 UP SENSOR</p>	<p>SCOOPER</p> <p>M2070</p> <p>NO SENSOR</p>		<p>SP. UNIT</p>
<p>BOAR/CLAMP UP/DW.</p> <p>M2204</p> <p>X041 DW. SENSOR</p>	<p>SCOOPER MOVE</p> <p>M2068</p> <p>NO SENSOR</p>		<p>NEXT Page31</p>
<p>BOAR/CLAMP MIDDLE UP/DW.</p> <p>M2206</p> <p>NO SENSOR</p>			<p>RETURN</p>

The image of **AIR CYLINDER 2** is drawn as below.

CP15 AIR CYLINDER 2		MARUSHIN Page31	
SIDING/ST. PIN (IN) <input type="checkbox"/> M2108 <input checked="" type="checkbox"/> X047 SIDING PIN	SIDING LOCK (FRONT) <input type="checkbox"/> M2222 <input checked="" type="checkbox"/> X04D SENSOR SIDING LOCK	CARY/VACUUM REVERSE <input type="checkbox"/> M2228 NO SENSOR	
SIDING/ST. PIN (OUT) <input type="checkbox"/> M2110 <input checked="" type="checkbox"/> X048 SIDING PIN	CARRIER UP/DW. <input type="checkbox"/> M2200 <input checked="" type="checkbox"/> X045 UP SENSOR <input checked="" type="checkbox"/> X058(OUT POS) DW.SENSOR	TABLE/VACUUM REVERSE <input type="checkbox"/> M2230 NO SENSOR	
SIDING/ST. PIN (FRONT) <input type="checkbox"/> M2112 <input checked="" type="checkbox"/> X049 SIDING PIN <input checked="" type="checkbox"/> X04A SIDING PIN	EJECT PIN UP/DW. <input type="checkbox"/> M2208 NO SENSOR	OUT CONVEAR ON <input type="checkbox"/> M2232 NO SENSOR	
SIDING LOCK (IN) <input type="checkbox"/> M2218 <input checked="" type="checkbox"/> X04B SENSOR SIDING LOCK	CARRIER VACUUM <input type="checkbox"/> M2224 <input checked="" type="checkbox"/> X063 SENSOR CARR. VACUUM	<input type="checkbox"/> SP. UNIT	
SIDING LOCK (OUT) <input type="checkbox"/> M2220 <input checked="" type="checkbox"/> X04C SENSOR SIDING LOCK	TABLE VACUUM <input type="checkbox"/> M2226 NO SENSOR	<input type="checkbox"/> NEXT Page32	
		<input type="checkbox"/> RETURN	

The image of AIR CYLINDER 3 is drawn below.



A signal lamp of the device turns on if the key of the cylinder with the sensor gets pressed.

2-3. How to operate Touch Panel (AUTO)

The image below shows up when **AUTO** key gets pressed.

The screenshot shows the CP15 AUTO touch panel interface. At the top left, it displays 'CP15 AUTO' and 'marUSHIN'. At the top right, it says 'Page2'. The interface is divided into several sections:

- Mode Selection:** BOARD MARK/CORNER MODE, BOARD THIN MODE, SCRAPER/SCOOPER MODE, NON PRINT MODE, PCB WAIT (11), TOP/BOTTOM CAMERA.
- Parameters:** CARRIER TORQUE 70 %, PRODUCT TACT 5.0 SEC, ALIGN.PLACE 3.0 SEC, PRINT PLACE 3.0 SEC, SQUEEGING 1.0 SEC.
- Displays:**
 - ① TOTAL/CN: 99999
 - ③ PRISET/SET: 99999
 - ④ PRISET/CN: 98765
 - ⑥ BOARD OUT: [Image]
 - ⑦ SCREEN FRAME LIFT UP/DH.: [Image]
- Buttons:** ② TOTAL RESET, ⑤ PRISET RESET, ⑧ (circle), ⑨ (circle), ⑩ (circle), T.STOP.
- Bottom Section:**

PCB	500 x 500	P.TIMER	0.1	SQ.PRESS	5.0
AX POS.	123.456	GAP	3.6		
AY POS.	123.456	OFFCON.	10	SQ.LANGTH F.	50
BX POS.	123.456	SQ.SPEED	700	SQ.LANGTH R.	50
BY POS.	123.456	SC.SPEED	700	REGI.No	12345678

For detailed explanation of the above image, refer to each section as below.

①:A1

②:A2

③:A3

⑩:A10

⑪:A11

Functions of all the keys of **AUTO** image are as follows.

A1. **TOTAL/CN**

This counter shows the total of boards printed on auto- running.
The maximum count is 99, 999.

A2. **TOTAL RESET**

The counted number on **TOTAL/CN** turns 0 if this key gets pressed.

A3. **PRISSET/SET**

This key is to stop auto-running at the set total.
To change the number, touch the counter, and then Ten Key
Overlap Window shows up.

A4. **PRISSET/CN**

This is the up-counter. If the number on **PRISSET/CN** turns number of
PRISSET/SET exactly, CP-15 stops carrying in a PCB to clean Screen.
Press Start switch to re-start CP-15, and the counter of **PRISSET/CN** gets to
clear 0.

fn. 1. CP-15 doesn't re-start unless it's on AUTO mode. Make sure to press Entry
switch and get an OK when you enter the space of Area Sensor. If you enter there
without this deed, the motors and air get to be cut off.

A5. **PRISER RESET**

This key is used to clear **PRISER/CN**.

It's possible to make the figure of Priser Counter0 while running.

A6. **BOARD OUT**

If this key gets pressed on auto-running, CP-15 carries a remaining board onto Carry-out Conveyor after alignment and printing.

While this function is on, another board is not carried in to CP-15 and **BOARD OUT** blinks in green.

BOARD OUT turns white back if **START** get pressed to release this function.

A7. **SQUEEGEE FRAME UP/DW**

Squeegee Frame goes up if this key gets pressed with Squeegee Frame down on auto-running. Squeegee Frame doesn't move on squeegeeing even if this key is pressed. Squeegee Frame starts to move after squeegeeing is completed

fn. 1. Make sure to press Entry switch and get an OK when you enter the space of Area Sensor to clean Screen Mask. If you enter the space without this deed, the motors and air turn cut off.

A8. Displaying selected printing conditions of CP-15

These are displayed based on **RECIPE** in **SIZE SET** which are explained ahead.

PCB 610×510	board size (flowing direction × squeegeeing direction)
AX POS. 123.456	X axis position of A-Camera
AY POS. 123.456	Y axis position of A-Camera
BX POS. 123.456	X axis position of B-Camera
BY POS. 123.456	Y axis position of B-Camera
P. TIMER 0.1	Carry-in Conveyor Stop timer
GAP 3.6	The amount of Screen Gap
OFFCON. 10.0	The amount of Off-Contact
SQ. SPEED 700	Squeegeeing speed
SC. SPEED 700	Scraper/Scooper speed
SQ. PRESS 5.0	Squeegeeing pressure
SQ. LENGTH F. 50	Squeegee front blank length
SQ. LENGTH R. 50	Squeegee back blank length
REGI. NO 12345678	User's registered number (maximum 8 figures)

For more details, refer to M18-3 **SIZE SET** key.

A9. **RESET**

If this key gets pressed on auto-running, PLC program turns reset.

All the movements come to a stop as soon as this key is pressed. Moving parts come to a stop after the moving is completed. Take away a remaining board to re-start, press **START** switch after returning all the units and motors to the original position.

fn. 1. This key is to reset PLC program, not for an emergency stop.

An emergency stop not only resets PLC program but cuts off the supply of electricity to the motors and the air-actuators .

A10. **T. STOP**

CP-15 comes to a temporary stop **T. STOP** gets pressed. But moving parts come to a stop after the moving is completed.

Signal tower turns yellow and **START** switch blinks in green to let you know a temporary stop. Press **START** switch to re-start.

fn.1. Use this key for check-out without taking away a remaining PCB. CP-15 is not guaranteed to run correctly if a remaining PCB gets moved or taken away while running.

A11. Displaying of present chosen mode and tact

The displays are explained below.

**BOARD MARK
/ CORNER MODE**Display of the present chosen alignment mode.

BOARD THIN MODEIn case thin board mode is on, this display shows up.

**SCRAPER
/ SCOOPER MODE**Scraper or Scooper is chosen, either one shows up.

NON PRINT MODEIn case non print mode is on, this display shows up.

For more details of the display above, refer to Ch.2 §2 "How to operate Touch Panel".

PCB WAITThis sign blinks in green if a given time is passed and a PCB is not carried in.

**TOP
/ BOTTOM CAMERA** This shows the choice of Top Camera or Bottom Camera.

CARRIER TORQUEThis shows Carrier pushing torque of Carrier axis at IN/OUT.

PRODUCT TACTThis shows time to produce a PCB from Carry-in to carrying-out, which is tact time per board to produce

ALIGN. PLACE

.....This shows time for a PCB from being carried in onto Carry-in Conveyor to being aligned on auto-running

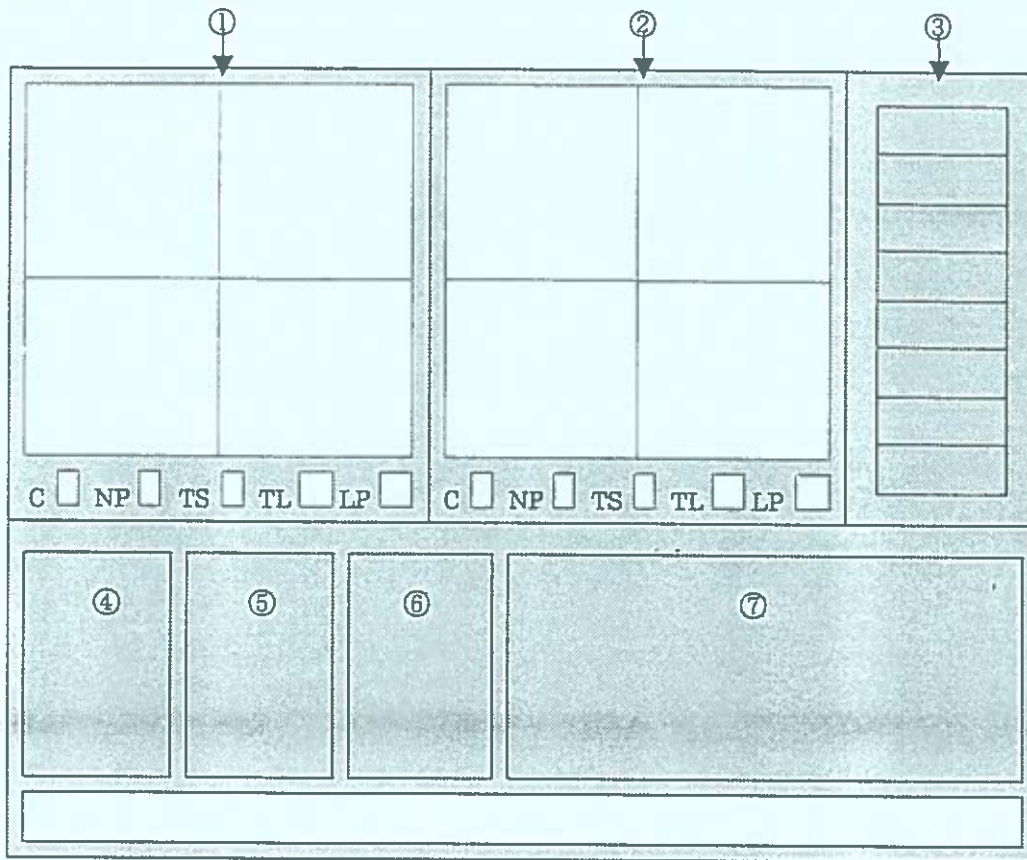
PRINT PLACE

.....This shows time for a PCB to be completed this at Printing Section on auto-running.

SQUEEGING

.....This shows time for Squeegee from starting to stopping.

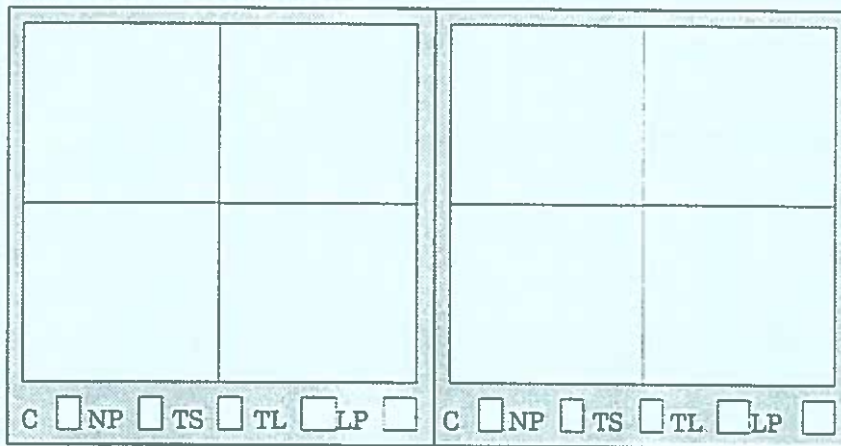
2-4. EXPLANATION OF IMAGE PROCESSING TOUCH PANEL



- ① A-CAMERA MONITOR
- ② B-CAMERA MONITOR
- ③ FUNCTION KEY
- ④ BINARY 1
- ⑤ ALIGNMENT
- ⑥ JUDGEMENT
- ⑦ MEASUREMENT

- display the image of A-CAMERA
- display the image of B-CAMERA
- use for initialization and each single motion
- use for binary setting
- use for alignment setting
- set the alignment allowance
- display measured values

①. ② MONITOR OF A-CAMERA, B-CAMERA



- C—Camera No.
- 1 A-CAMERA (Top)
 - 2 B-CAMERA (Top)
 - 3 A-CAMERA (Bottom)
 - 4 B-CAMERA (Bottom)

* Camera No. can be changed by choosing camera on Operation Touch Panel.

- NP—Conversion of Negative / Positive
- N - set dark part as the mark
 - P - set light part as the mark

* Press **ALIGN** to be able to change this setting.

- TS—Background level
- H - High sensitivity
 - M - Middle sensitivity
 - L - Low sensitivity

* Press **ALIGN** to be able to change this setting.

- TL—Binary level
- Input the value by Ten Key

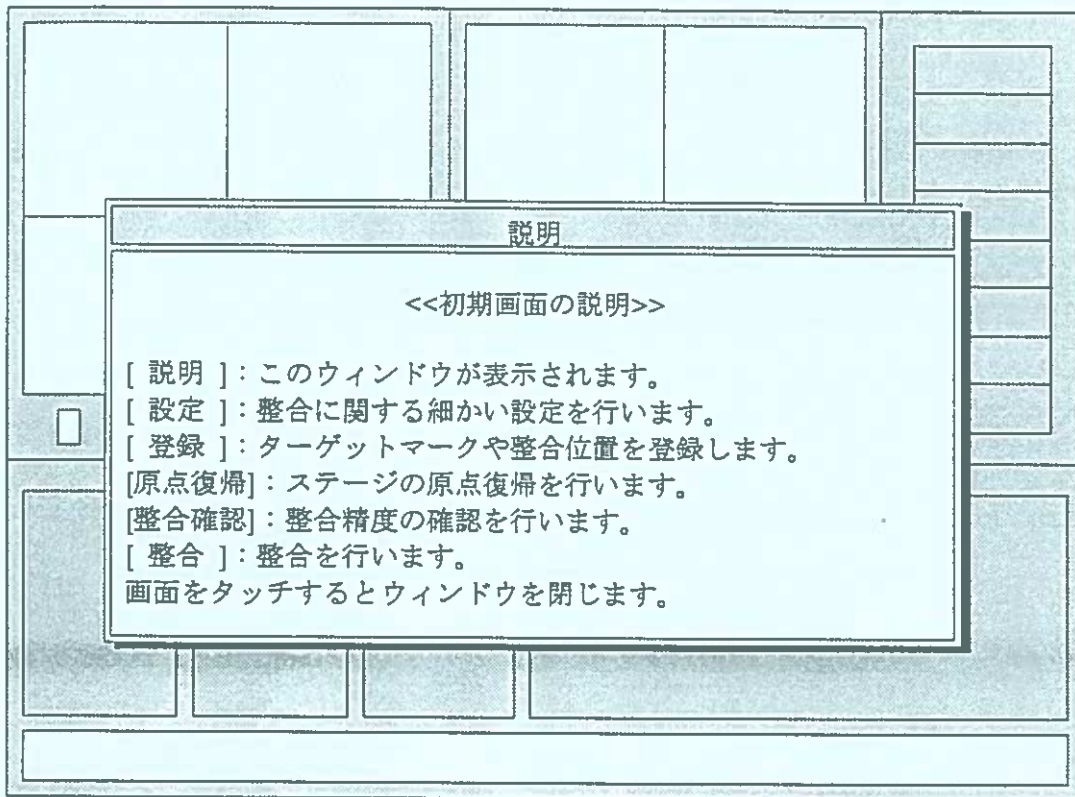
Normal run +20

* Press **ALIGN** to be able to change this setting.

- LP—Light level
- No use for CP-15
 - Set up the light level on Operation Touch Panel.

③ FUNCTION KEY

③-1 EXPLAN. KEY



If **EXPLAN.** is pressed, the above window shows up. However, at this moment, only Japanese is available. The meaning of above Japanese window is as follows.

<<Explanation of initial menu>>

[EXPLAN.] : display this window.

[SET] : set detail parameters about alignment.

[MEMORY] : register target marks and alignment position.

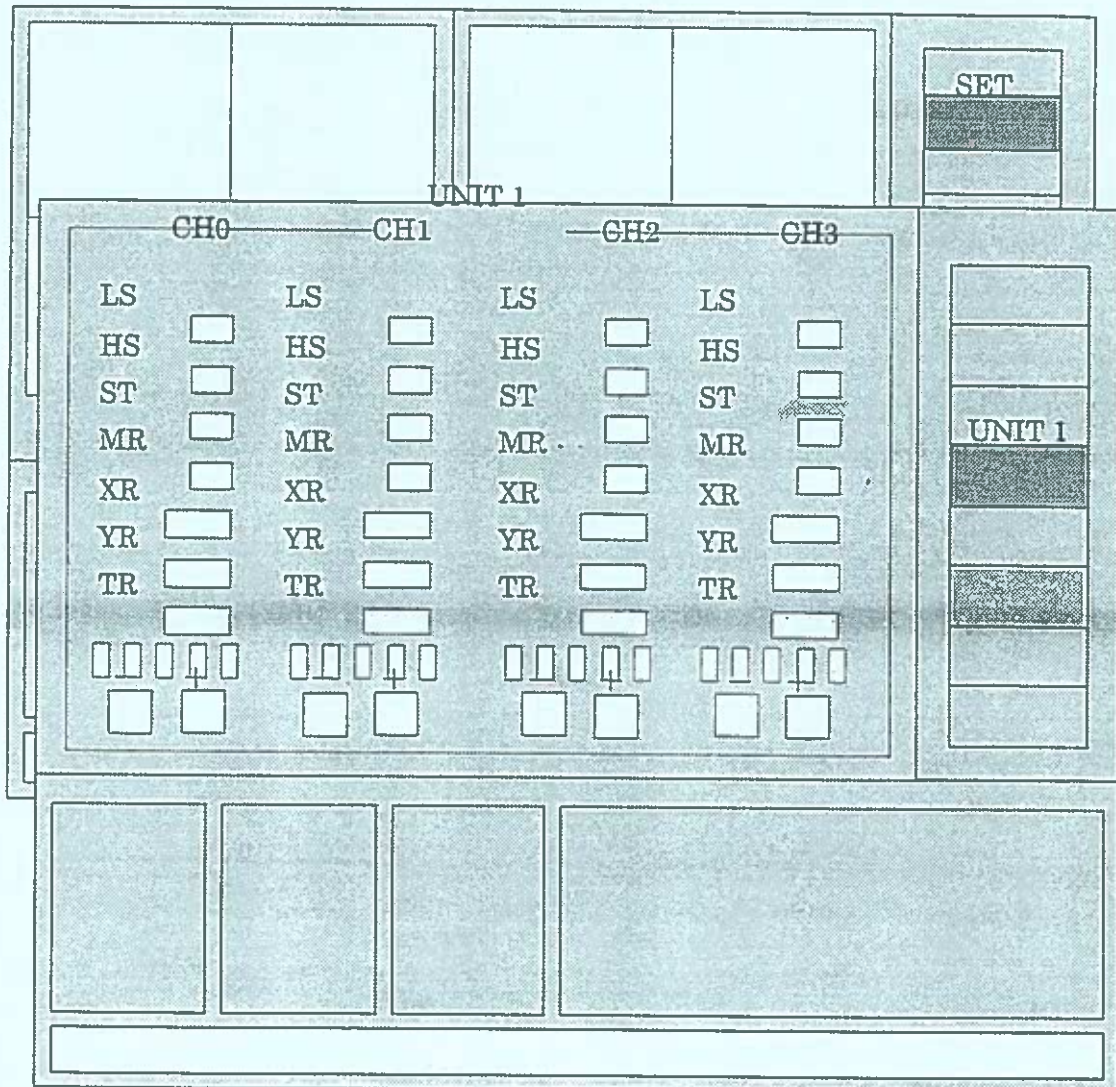
[ORG.] : get 3-axis Table to the original position.

[AL.CHECK] : check the result of alignment.

[ALGN.] : make alignment.

③-2 SET KEY

③-2-1 UNIT 1 KEY

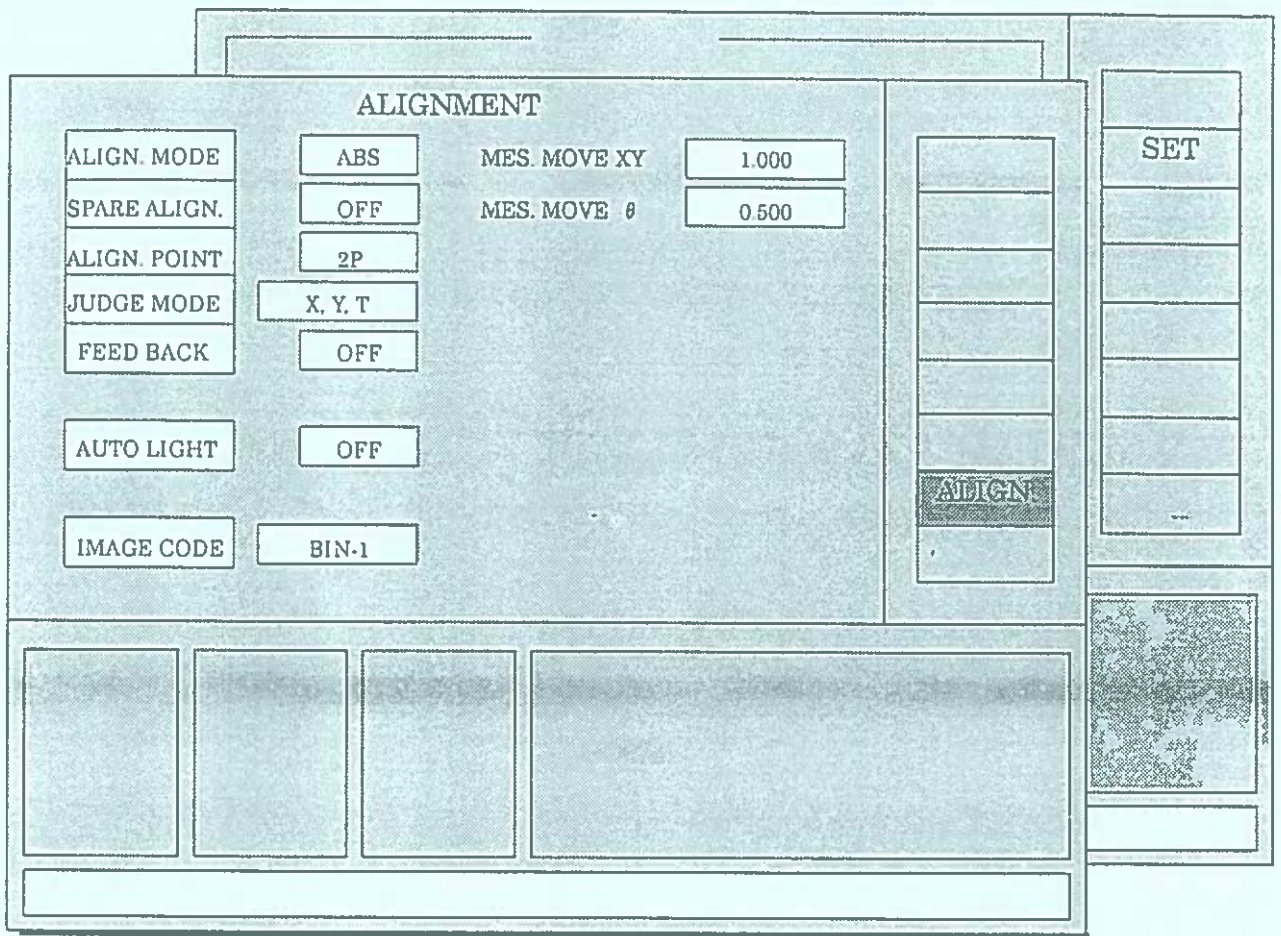


CH0 :X axis of 3-axis table
CH1 :Y axis of 3-axis table
CH2 : θ axis of 3-axis table
CH3 : no use

LS :Low speed (mm/sec.)
HS :High speed (mm/sec.)
ST :Speed up/down time (sec.)
MR :Pulse per 1mm of motor
XR :Pulse per 1mm of X axis
YR :Pulse per 1mm of Y axis
TR :Pulse per 1degree of θ axis
+ :Jog key of +direction
- :Jog key of -direction

ALIGN.

key



ALIGN. MODE

ABS — Absolute alignment
REL — Relative alignment

SPARE ALIGN.

ON — Pre-set alignment ON
OFF— Pre-set alignment OFF

ALIGN. POINT

2P — Alignment based on 2 points
4P — Alignment based on 4 points

JUDGE MODE

X, Y, T — Judge alignment position
DX, DY — Judge measured position

FEED BACK

ON — Automatic revision
OFF— No automatic revision
CLR— Clear the feed back value

AUTO LIGHT

ON — Auto setting of light level
OFF— Manual setting of light level

IMAGE CODE

BIN-1 — Binary processing mode 1
BIN-2 — Binary processing mode 2
PTTRN— Pattern search mode

MES. MOVE

X, Y — Moving amount of X and Y
θ — Moving amount of θ

③-3 MEMORY key

EXPLAN.	No use
AUTO SET	set of light and binary level automatically
MARK ME.	register target marks
CALIBRA.	make calibration and set alignment position
AL.POS.	change alignment position
ORG.	move 3-axis table to the original position
END	get back to the initial menu

③-4 OTHER KEYS

EXPLAN.	
SET	
MANUAL	no use
MEMORY	
AL.CHECK	measure the position after alignment
ALIGN.	make alignment
ORG.	move 3-axis table to the original position

BINARY 1		
	M	M2
C 1 - 2	<input checked="" type="checkbox"/>	<input type="checkbox"/>
C 3 - 4	<input type="checkbox"/>	<input type="checkbox"/>
DISPLAY		
RR		50
DIS.	THRGH	

ALIGNMENT	
OX	0. 000
OY	0. 000
OT	0. 000
AL	10

JUDGE	
X	0. 003
Y	0. 003
T	0. 003
DX	0. 050
DY	0. 050
DT	0. 025
DP	0. 100

BINARY 1

- M1 — Memory 1
- M2 — Memory 2
- C1-2 — Top camera
- C3-4 — Bottom camera
- RR — The mark area allowance against registered area (%)
- DIS. — BINARY display binary image
THRGH display live image

ALIGNMENT

- OX — Offset value of X axis on alignment
- OY — Offset value of Y axis on alignment
- OT — Offset value of θ axis on alignment
- AL — Alignment times limit

JUDGE

- X — Allowance range of X axis on alignment
- Y — Allowance range of Y axis on alignment
- T — Allowance range of θ axis on alignment
- DX — Allowance range of X axis on measurement
- DY — Allowance range of Y axis on measurement
- DT — Allowance range of θ axis on measurement
- DP — Allowance range of distance between marks

MEASUREMENT					
DX1	0.000	DX2	0.000	X	0.000
DY1	0.000	DY2	0.000	Y	0.000
RR1	0	RR2	0	T	0.000
				DP	0.000
DX3	0.000	DX4	0.000	AX	0.000
DY3	0.000	DY4	0.000	AY	0.000
RR3	0	RR4	0	AT	0.000

MEASUREMENT — display alignment data on each time

- DX1 — The shift value of mark position on X axis at CAMERA1
- DY1 — The shift value of mark position on Y axis at CAMERA1
- RR1 — The mark area allowance against registered area at CAMERA1(%)
- DX2 — The shift value of mark position on X axis at CAMERA2
- DY2 — The shift value of mark position on Y axis at CAMERA2
- RR2 — The mark area allowance against registered area at CAMERA2(%)
- DX3 — The shift value of mark position on X axis at CAMERA3
- DY3 — The shift value of mark position on Y axis at CAMERA3
- RR3 — The mark area allowance against registered area at CAMERA3(%)
- DX4 — The shift value of mark position on X axis at CAMERA4
- DY4 — The shift value of mark position on Y axis at CAMERA4
- RR4 — The mark area allowance against registered area at CAMERA4(%)
- X — Average shift value on X axis of CAMERA1 and 2 (or CAMERA3 and 4)
- Y — Average shift value on Y axis of CAMERA1 and 2 (or CAMERA3 and 4)
- T — Average shift value on θ axis of CAMERA1 and 2 (or CAMERA3 and 4)
- DP — MAX. difference of the distance between marks
- DX — Feed back value on X axis
- DY — Feed back value on Y axis
- DT — Feed back value on θ axis

Note: CAMERA1 — A CAMERA (Top)
 CAMERA2 — B CAMERA (Top)
 CAMERA3 — A CAMERA (Bottom)
 CAMERA4 — B CAMERA (Bottom)

*** EXPLANATION OF MARK SETTING ***

- ① Insert PCB with clear target, and clamp it.
- ② Move each camera to make target be centered on the monitor.
* To insert PCB, and move cameras are operated from Operation Touch Panel

③ Press **MEMORY** key

④ Press **AUTO SET** to make the auto setting of alignment condition.

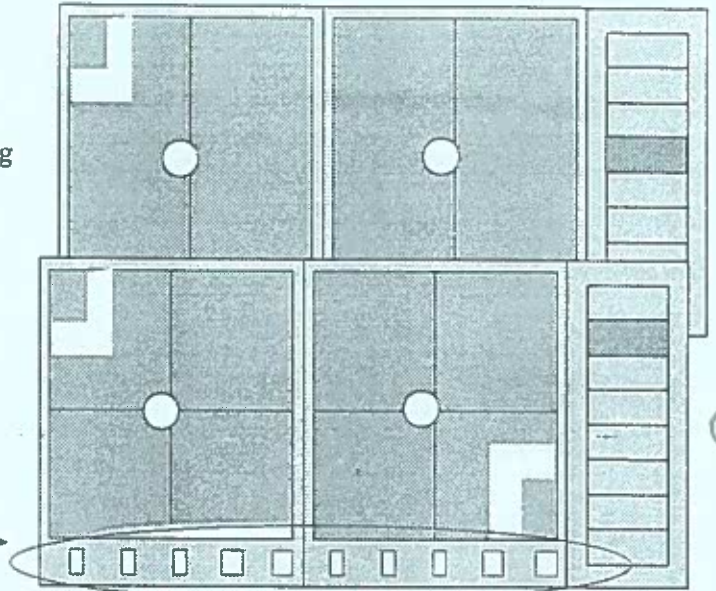
If target mark is not clear, set the alignment condition on manual.

NP-Turn target color from black to white.

TS-Change background level.

TL-Change binary level

Light level can be changed on Operation touch panel.



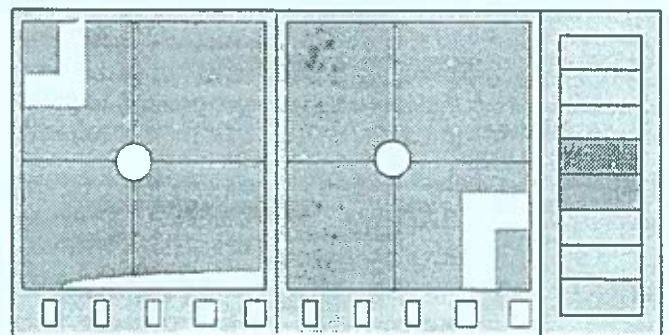
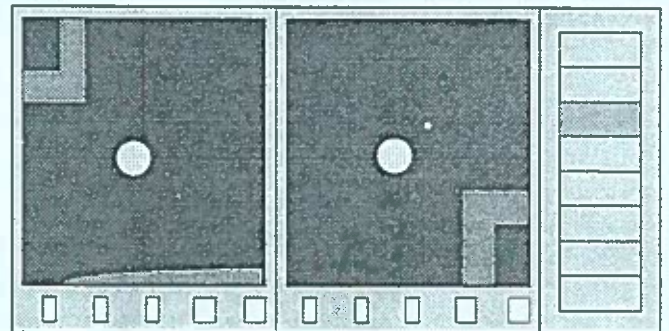
⑤ Press target mark on Touch Panel. The mark turns to be yellow and others to be blue and black.

⑥ Press **MARK ME.** to register marks.

⑦ Press **CALIBRA.** to make calibration.

⑧ Press **AL. POS.** to change alignment position.

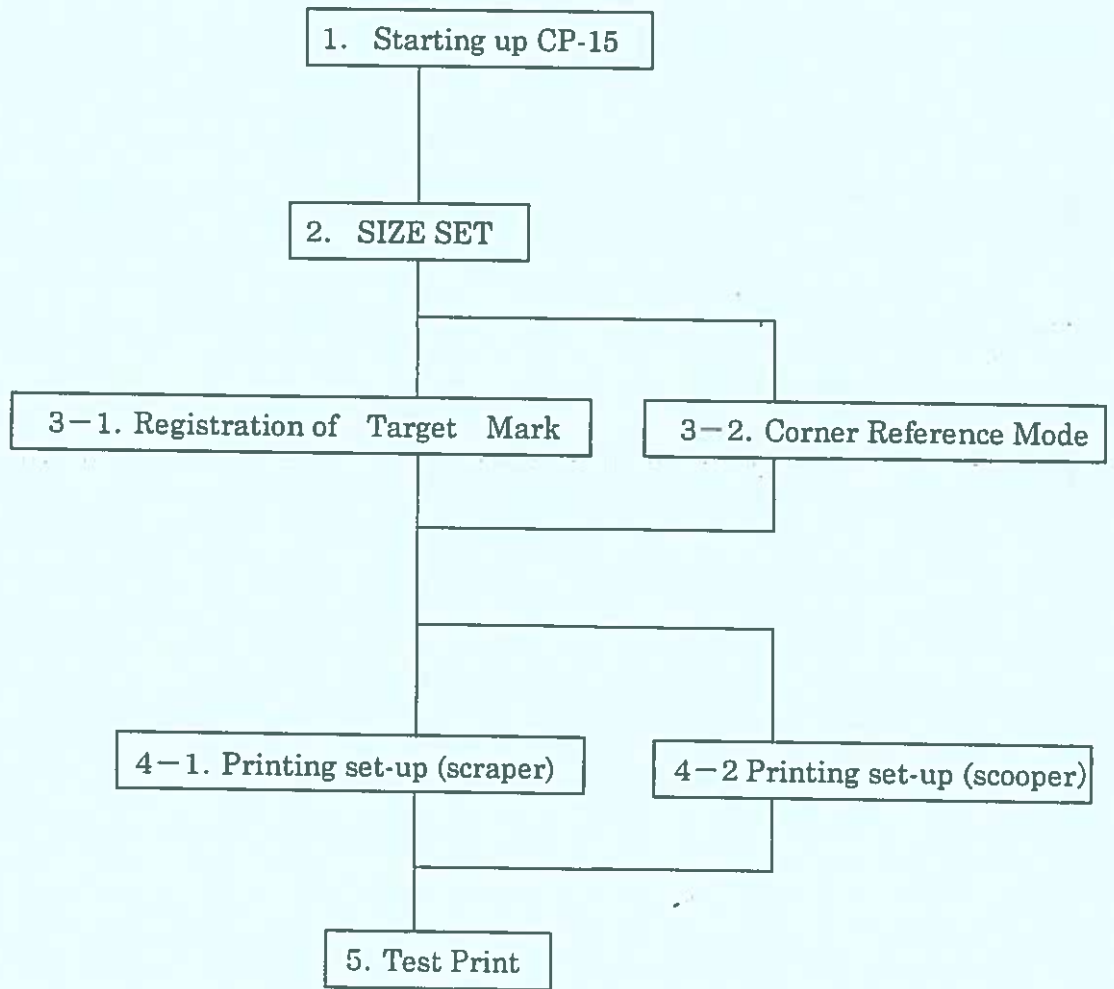
* Please confirm the red lines go through the center of targets.



⑨ After setting alignment position, press **ALIGN.** to confirm the alignment gets to be done correctly.

2-5 Manual set-up

- Overview of the procedure of operation



• The procedure of operation

1. Starting up CP-15

1-1 Turn on CP-15

1-2 Press **ORG**

Operation Touch Panel in drawing 2 ⑰

2. Registration of Target Mark

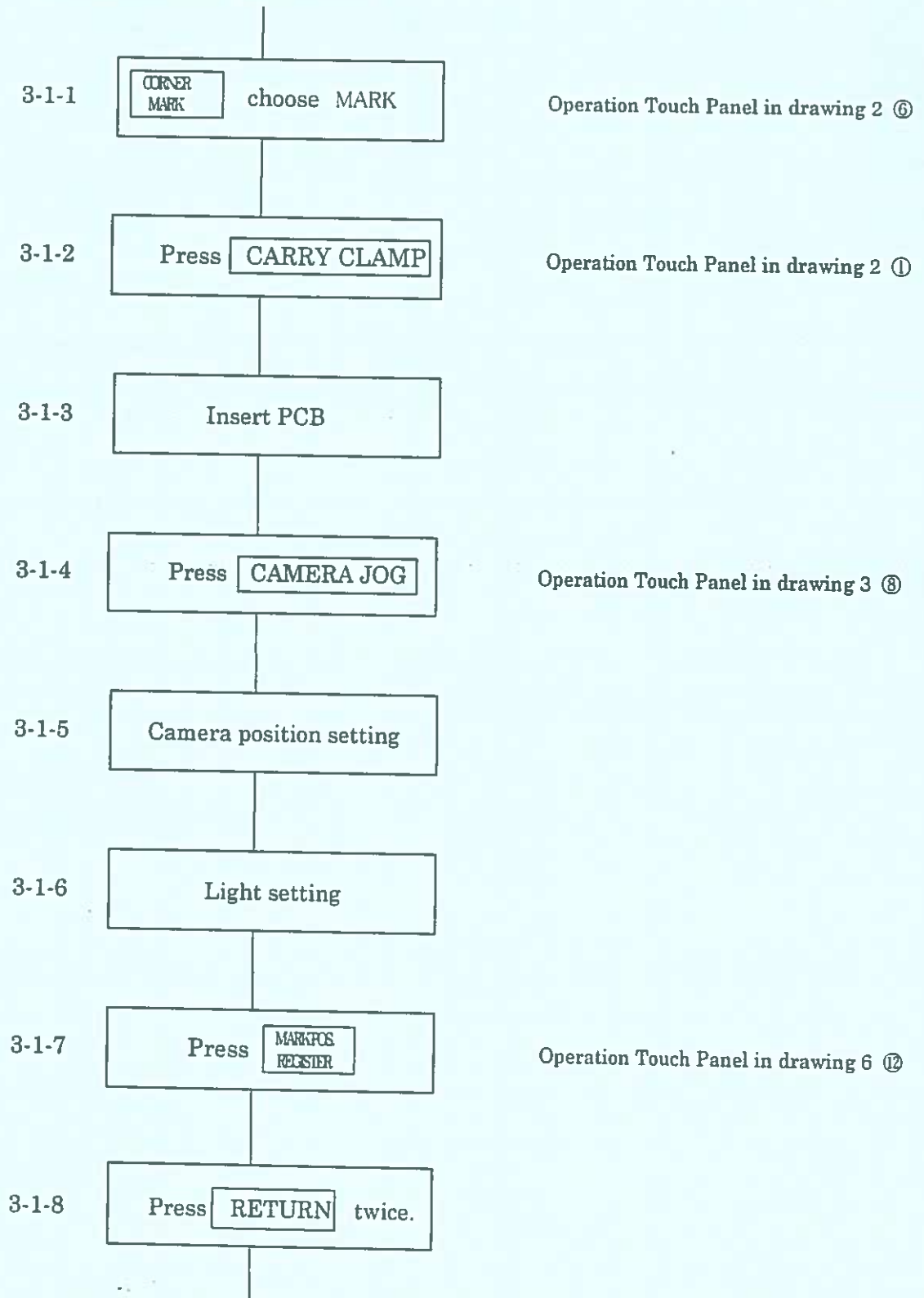
2-1 Press **SIZE SET**

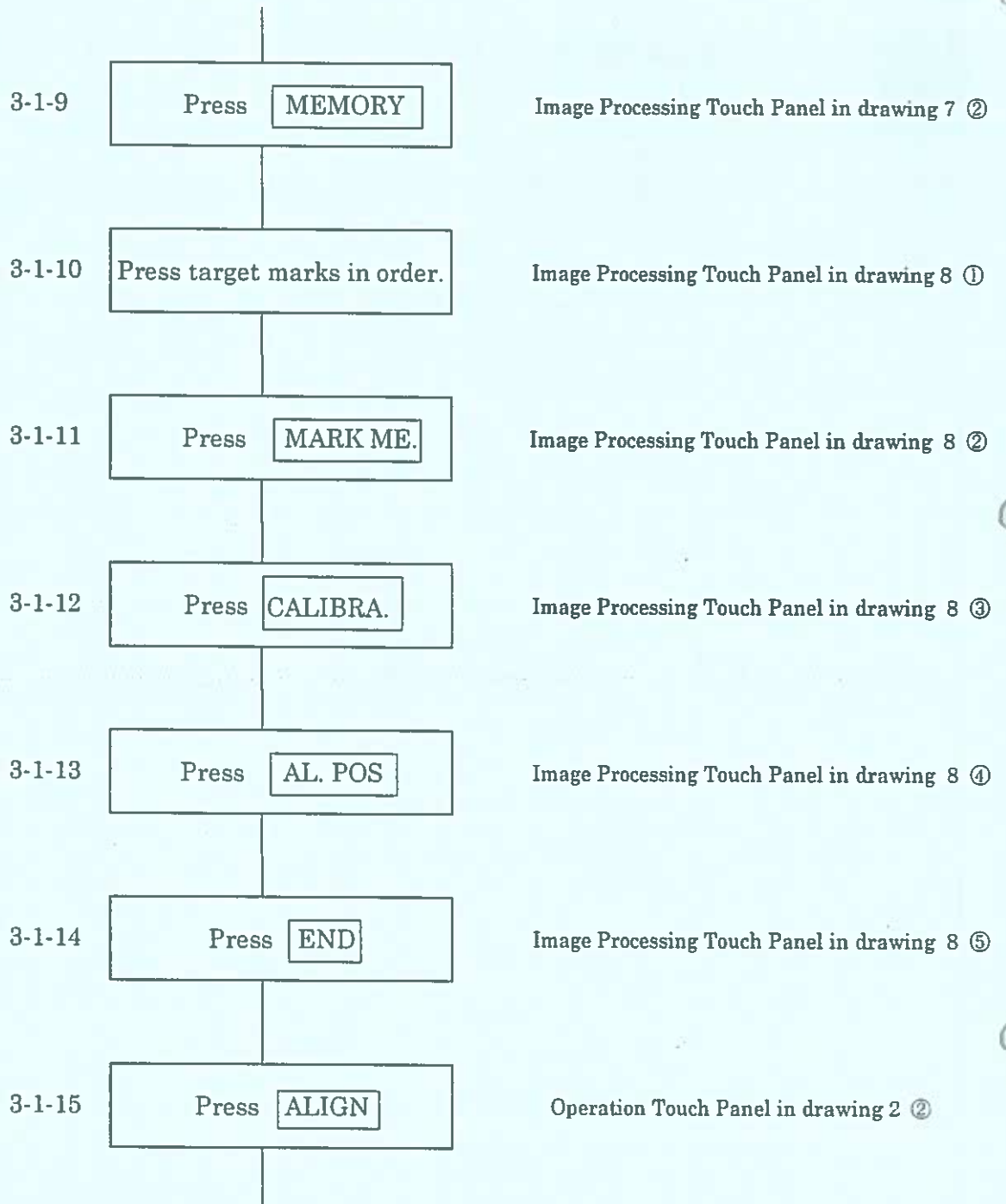
Operation Touch Panel in drawing 2 ⑱

2-2 Input each setting value.

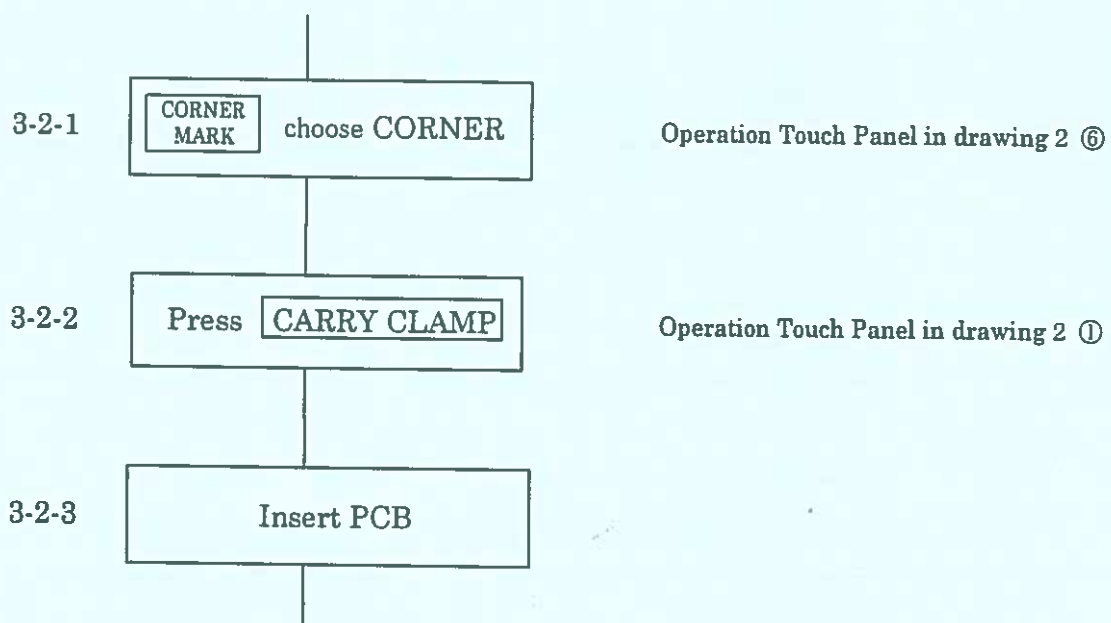
Input the PCB size and parameters etc.

3-1. Registration of Target Mark

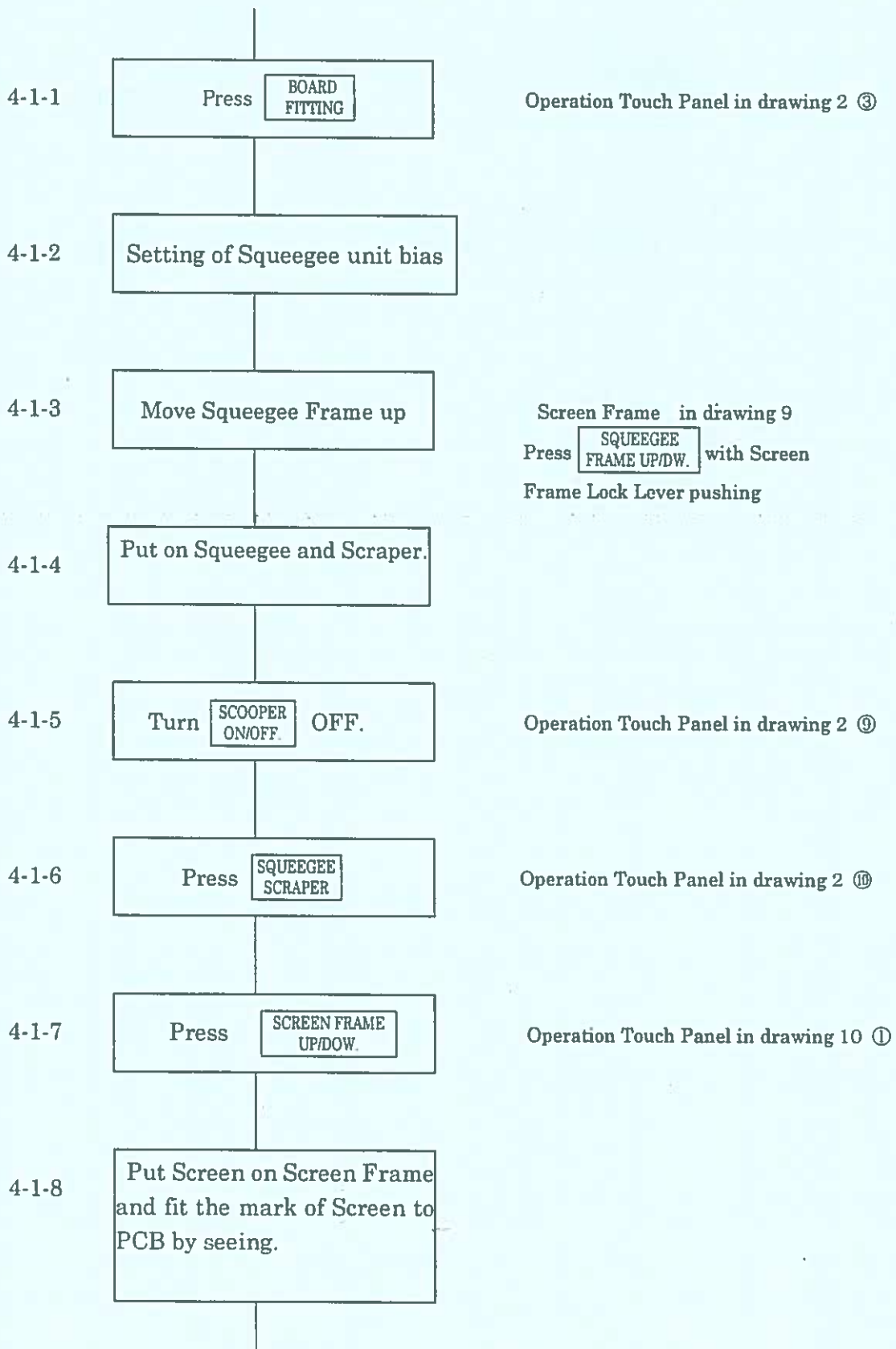


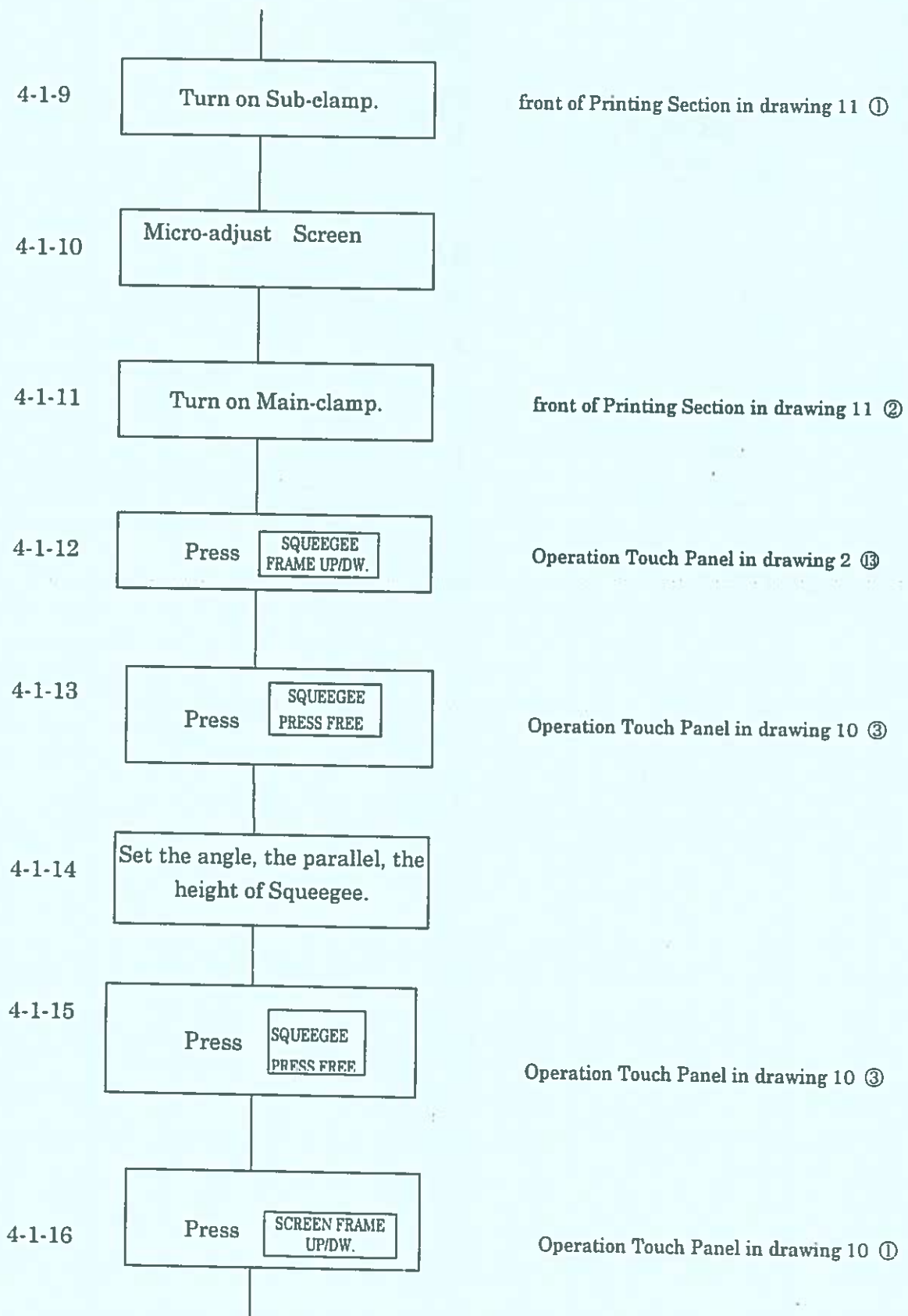


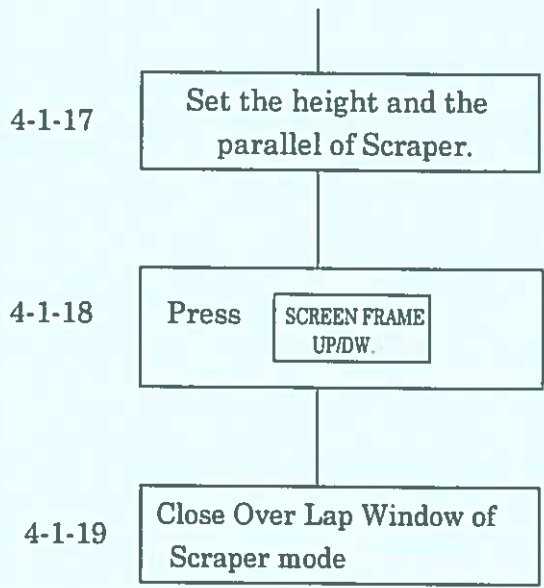
3-2. Corner Reference Mode




4-1. Printing set-up (Scraper)



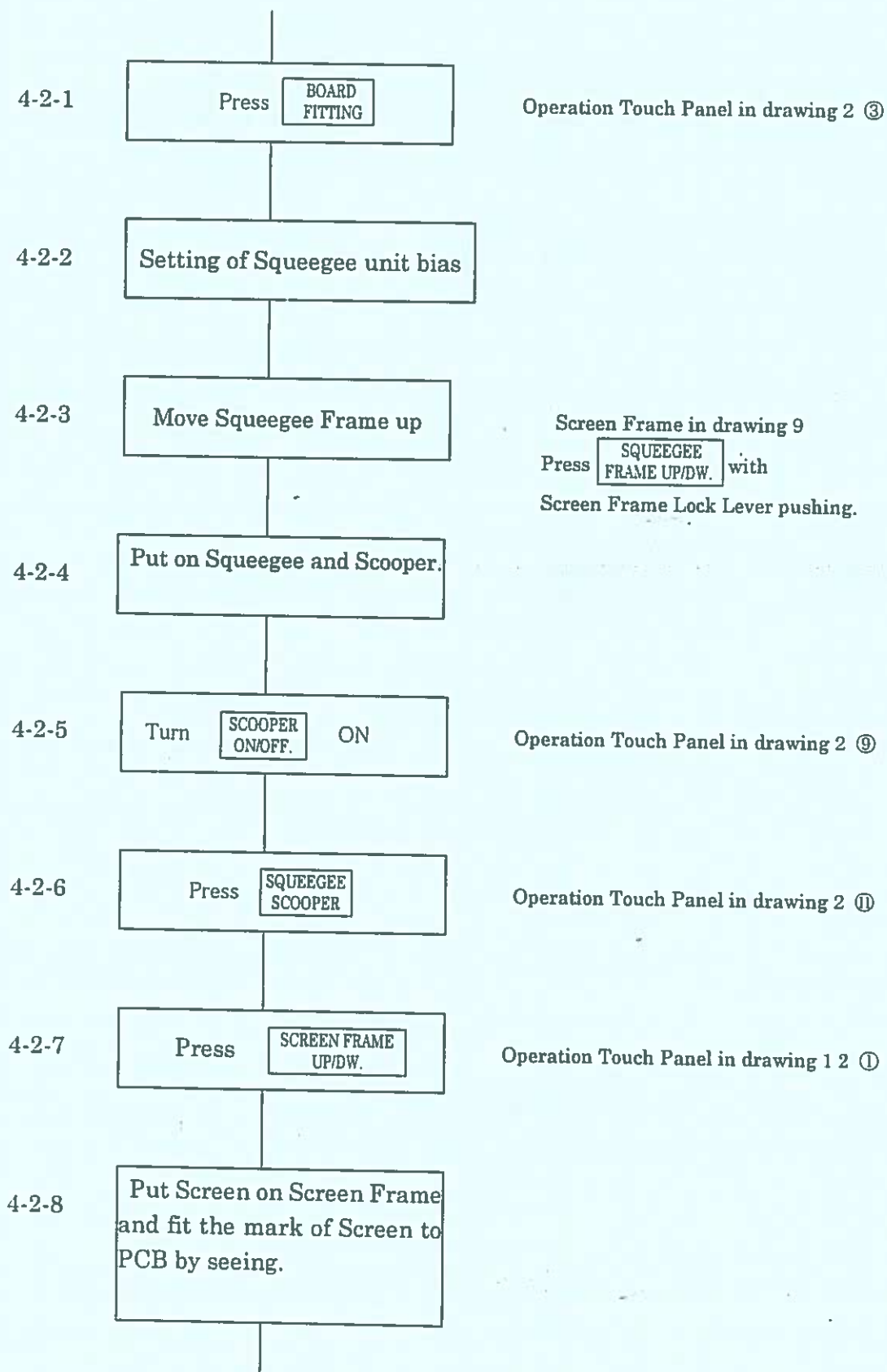


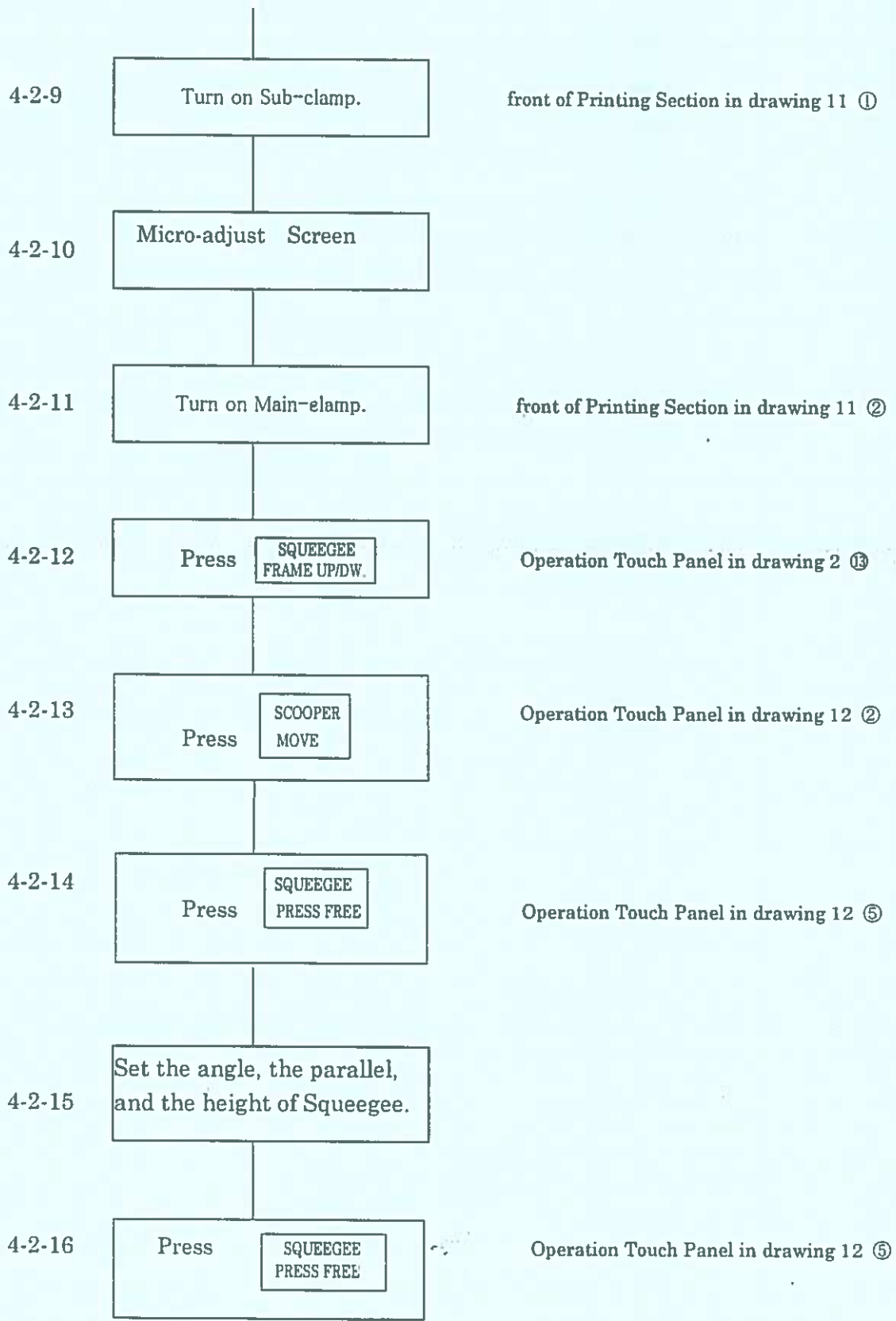


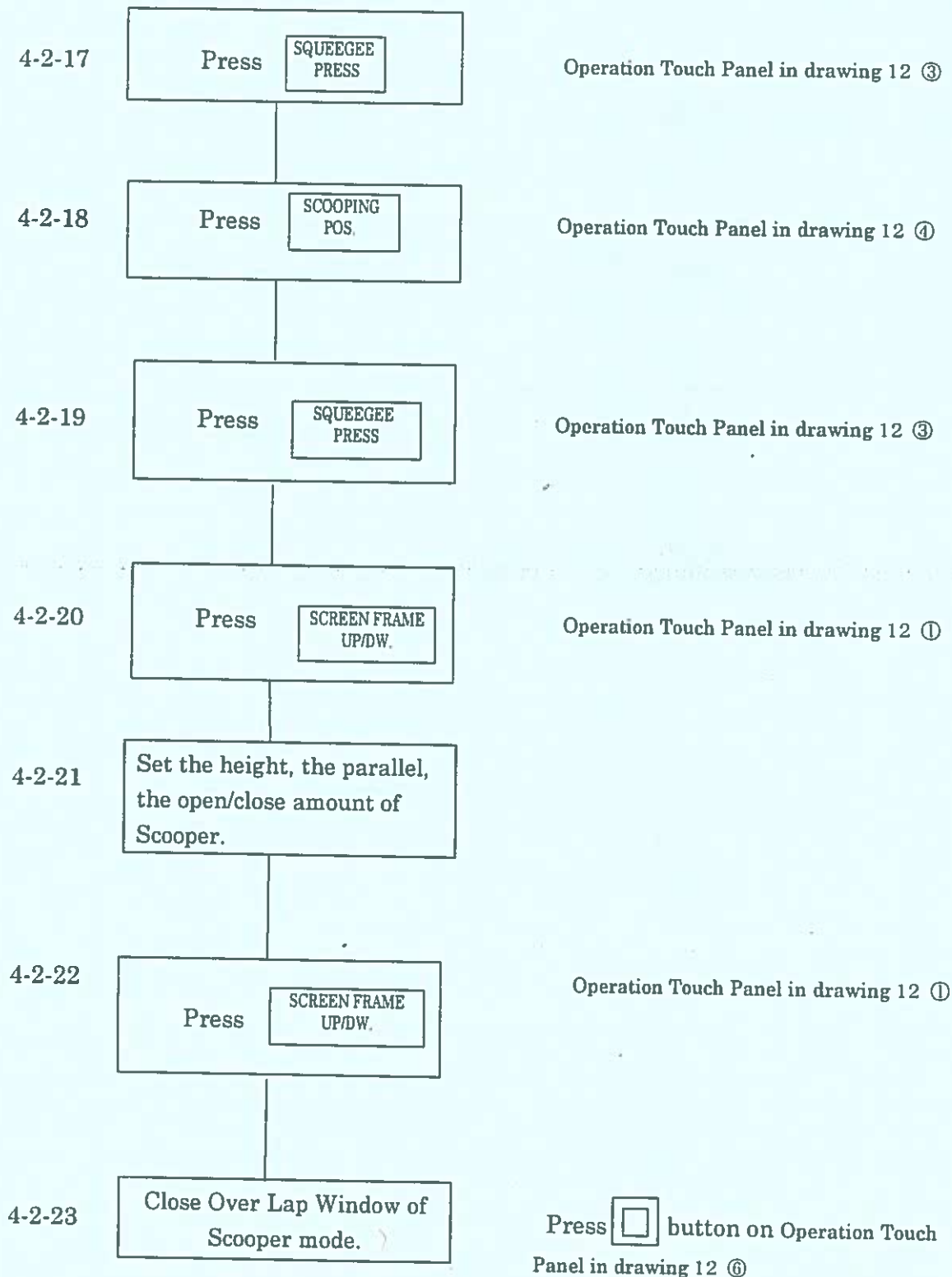
Operation Touch Panel in drawing 10 ①

Press  button on Operation Touch Panel in drawing 10 ④

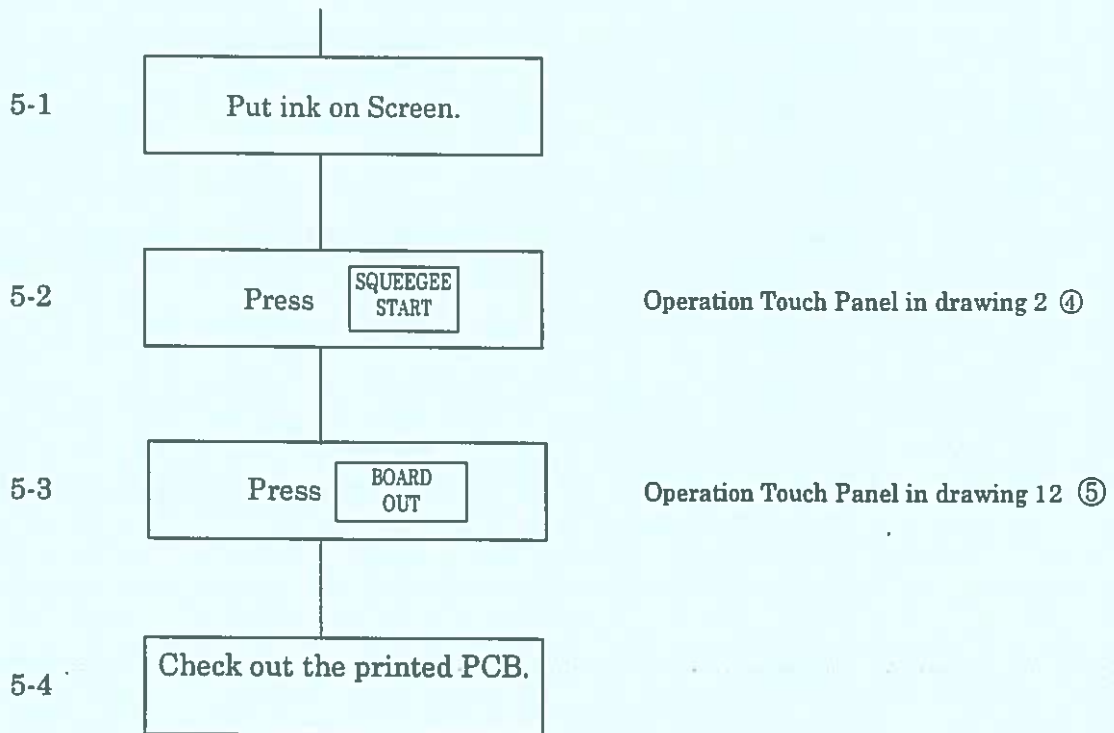
4-2. Printing set-up (Scooper)







5. Test Print



fn.)

For more details are on next.

Details of operation order

1. Starting up CP-15

- Turn on CP-15.

Image processing and Operation Touch Panels turn live, and after a few seconds, Manual Image in drawing 2- ⑱ turns lighting in blue.

fn.1. Make sure to take PCBs or any unnecessary things away from CP-15 before turning it on.

- Check **MANUAL** in drawing 2-⑱ is lighting in blue.
- Press **ORG** in drawing 2-⑰.
The cylinders and motors return to the original position, and Manual set-up mode can be started.
- For more details, refer to ch.2 § 2-1Explanation of operating Touch Panel (Manual Operation).

2. SIZE SET

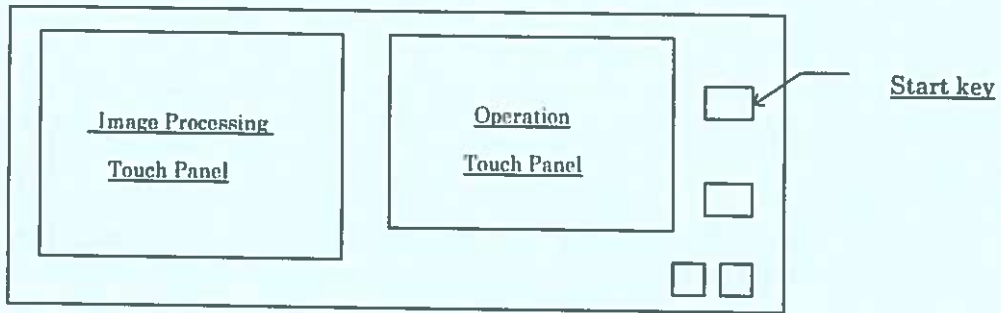
- Press the key **SIZE SET** in drawing 2-⑳, and the image of **SIZE SET** in drawing 3 shows up.

At the image of **SIZE SET** , the size of PCB for print or parameters printing can be input.

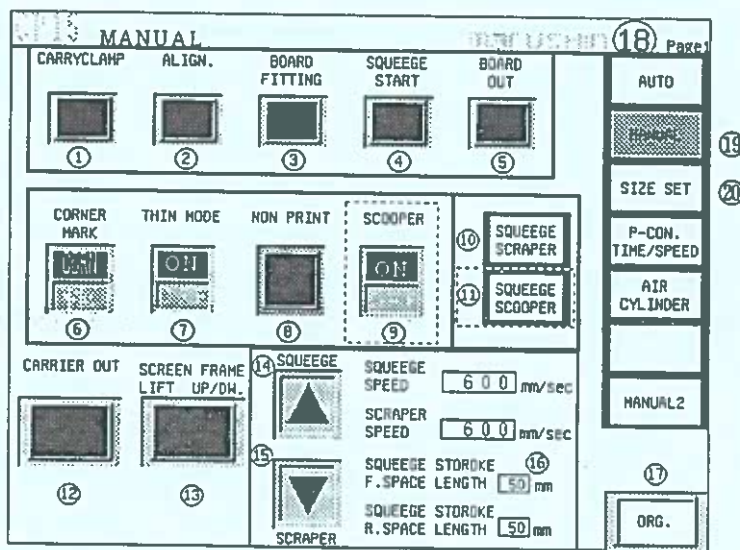
In case using unregistered PCB, it can't be set about the camera positioning drawing 3-2~5 at this moment.

If printing parameters have been already kept in PC card, call recipe data No.

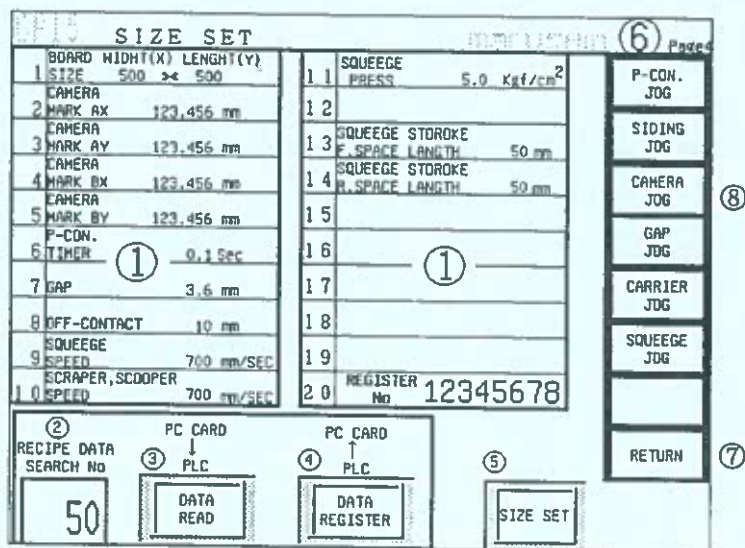
- When new type of PCB is printed, input each parameter. Refer to 'SIZE SET keys' , M18-3' , in ch. 2, § 2



drawing 1 OPERATION SECTION



drawing 2 MANUAL IMAGE

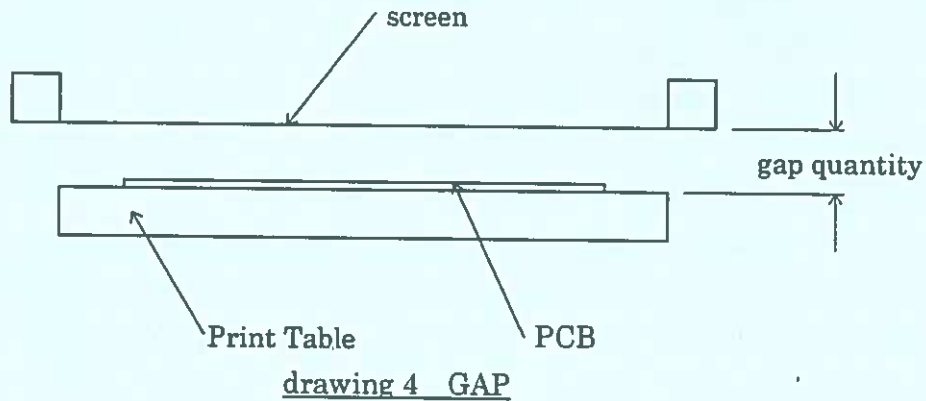


drawing3 SIZE SET IMAGE

- Explanation of 7 GAP and 8 OFF-CONTACT in drawing 3 'SIZE SET' image

- 7 GAP

Gap is the clearance between of Screen and Print Table. (For more details, refer to 'GAP' in drawing 4.)

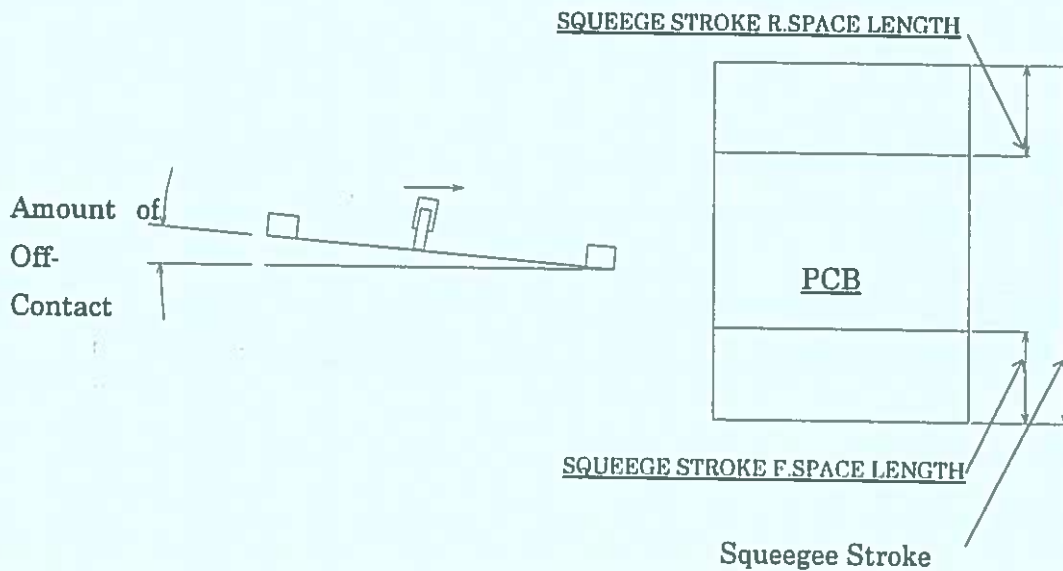


- 8 OFF-CONTACT

For much clearer printing, CP-15 has Off-contact function. That is, it prints with taking off Screen from PCB gradually from front. Lifting amount against squeegee stroke is called frame separate quantity.

The details are 'OFF-CONTACT'.

Squeegee stroke means PCB size of Y direction plus SQUEEGEE STROKE F.SPACE LENGTH in drawing 2-16 and drawing 3-13 and plus SQUEEGEE STROKE R in drawing in drawing 2 Na and drawing 3-14.



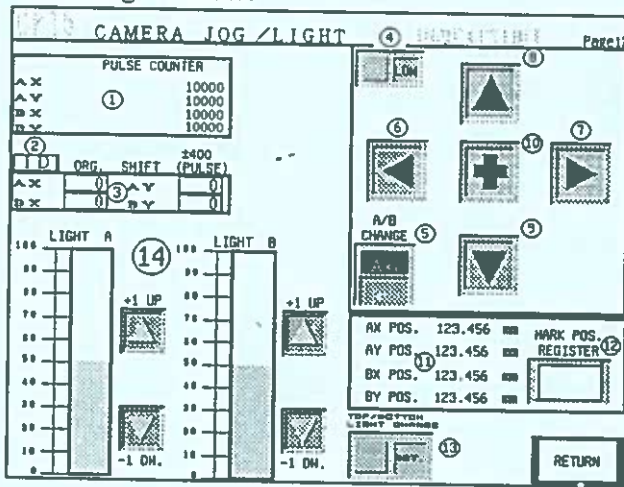
drawingM-5 OFF-CONTACT

3.Alignment

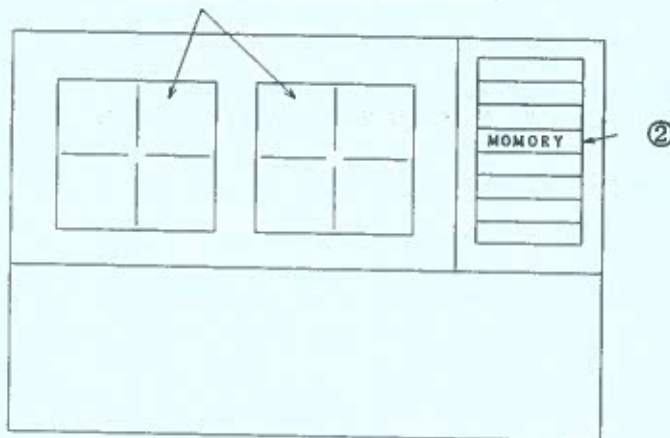
- Press the key **CARRY-CLAMP** in drawing 2-①
Carry-in conveyor starts to move after 3-axis table returns to the original point.
- Insert PCB.
After siding is done, Board Clamp fixes a PCB.
- Press **CAMERA JOG** in drawing 3 ⑧.
CAMERA JOG image in drawing 6 shows up. Set-up of camera positions and adjustment of the light can be done.
(For more details, refer to CAMERA JOG image are on ch.2 § 2 SZ-3 **CAMERA JOG** function)
- See Image Operation Touch Panel. It shows the initial image of drawing 7
(For more details, refer to Image Operation Touch Panel are on ch.2 § 4.)
- Use the keys of ⑤~⑨ in drawing 6 to make two marks of PCB come to the center of drawing 7-①.
- Press **MARKPOS REGISTER** key in drawing 6-⑫.
A,B Camera positions value can be automatically registered for the image SIZE SET in drawing 3 - 2 to 5.
- Press **RETURN** key 2 times to get back to the image of MANUAL in drawing 2.
- Press **MEMORY** key in drawing 7 on Image Operation Touch Panel
shows up. The image of Image operation Touch Panel in drawing 8 shows up.
- Touch target marks in drawing 8-① in order. Target marks turn yellow from white.
- Press **MARK ME** key in drawing 8-②
The position and shape of the target marks are registered.
- Press **CALIBRA** key in drawing 8-③.
Image processing system learns the present target position.

- Press **AL.POS** in drawing 8-④.

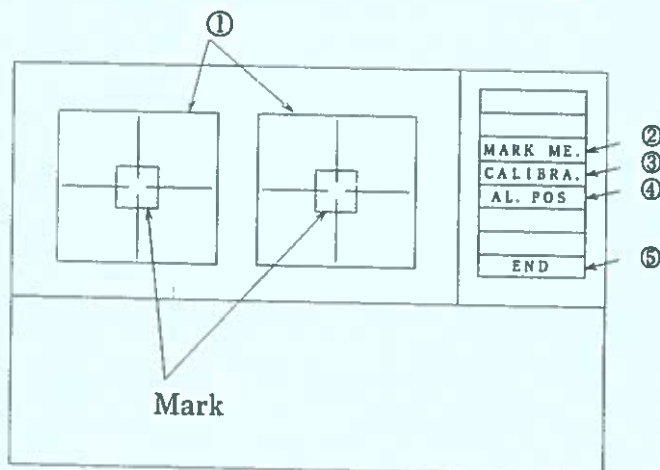
Lines are drawn at the center of both X and Y axis of target mark as drawing 7 below.



drawing6 CAMERA JOG



drawing7 Image Processing Touch Panel

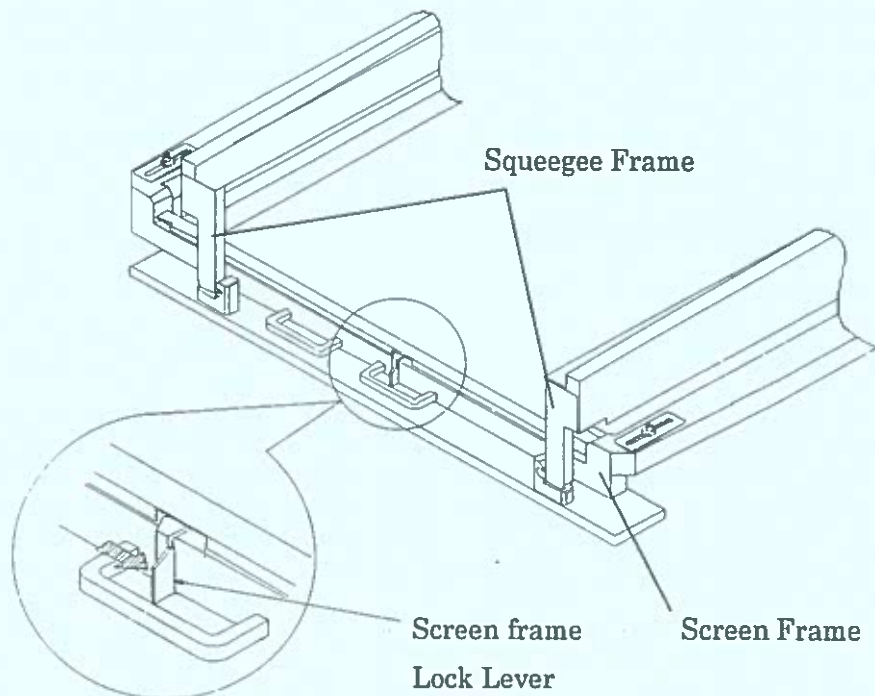


drawing8 Image Processing Touch Panel

- Press **ALIGN** key in drawing 2-②.
3 axis table makes a micro-alignment.




4. Print

- Press **BOARD FITTING** key in drawing 2-③.
Carrier conveys PCB to Alignment Section to Printing Section from Alignment Section.
- Set squeegee bias.(For more details, refer to ch.1 § 2-2-2'Squeegee' of explanation of squeegee adjustment)
Adjust it with Squeegee Frame down. Press **SQUEEGE FRAME UP/DW.** in drawing 2-⑬,so Squeegee Frame and Screen Frame can go up/down.
- Press **SQUEEGE FRAME UP/DW.** in drawing2-⑬, make only Squeegee Frame go up.
Press **SQUEEGE FRAME UP/DW.** with pushing Screen Frame Lock Lever in drawing 2 ,to move up only Squeegee Frame. Squeegee Frame can move up.
- Put on Squeegee Rubber and Scraper or Scooper.

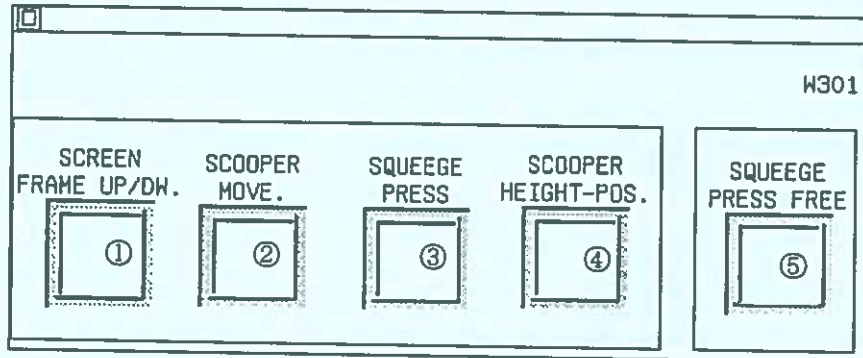


drawing9 Screen Frame Lock


Using Scooper

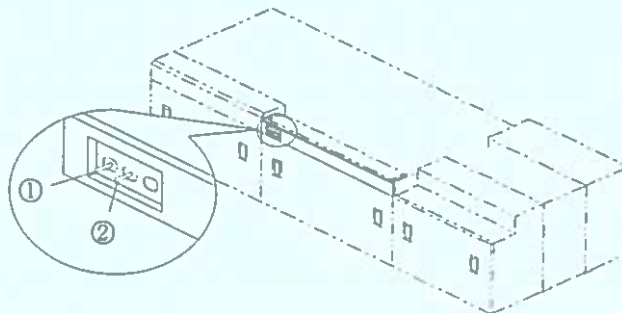
- Turn on  in drawing 2-⑨.
It shows the key  in drawing M-2-⑩.
- Press the key  in drawing 2-⑩.
Overlap Window of 'Scooper Mode' in drawing 10 Shows up.
(For more details, refer to ch.2 § 2 M11 of Manual Operation part.)

⑥



drawing10 Scooper mode

- Press the key  in drawing 10-①.
Screen Frame goes down.(For more details, refer to ch.1 § 2-2-1 'Screen Frame'.)
- Put screen on Screen Frame and fit to PCB to the mark of Screen Mask by seeing.
- Turn on Sub-clamp key and clamp Screen Mask temporary.
- Make a micro-adjustment to set up on the correct position of Screen by using 4 Micro-Adjusters on Screen Frame.
- Turn on Main-clamp key in drawing 11-②, and clamp Screen on Screen Frame.



drawing11 Clamp Key

- Press the key

SCOOPER MOVE

 in drawing 10-②. (The details are on ch. 1 § 2-2-2 'Squeegee')
Scooper opens.
- Press the key

SQUEEGE PRESS FREE

 in drawing 10-⑤.
Air pressure is cut off and Squeegee goes down.
- Adjust the angle, the parallel, the height of Squeegee.
- Press the key

SQUEEGE PRESS FREE

 in drawing 10-⑤.
Air pressure is on and Squeegee goes up.
- Press the key

SQUEEGE PRESS

 in drawing 10-③.
Squeegee goes down to squeegee position.
- Press the key

SCOOPING HEIGHT POS.

 in drawing 10-④.
Middle stopper goes down.
- Press the key

SQUEEGE PRESS

 in drawing 10-③.
Squeegee goes up to scooping position.
- Press the key

SCREEN FRAME UP/DW.

 in drawing 10-①.
Screen Frame goes up.
- Adjust the height matching of Scooper and Squeegee with Screen, and closing condition of Scooper.
- Press the key

SQUEEGE FRAME UP/DW.

 in drawing 2-⑬.
Squeegee frame goes down.
- Press the key

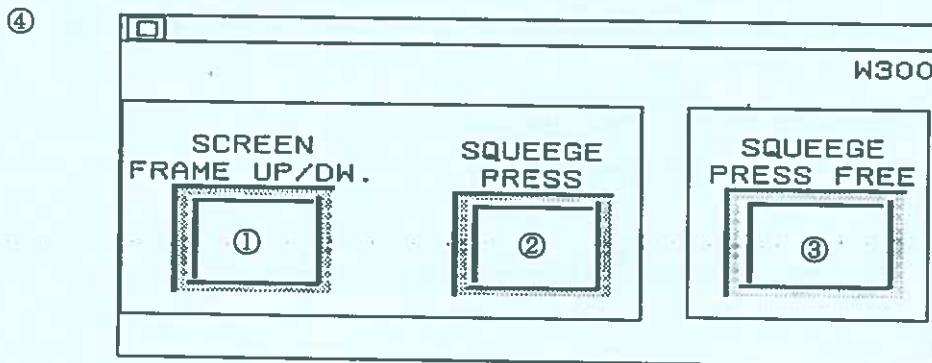
□

 in drawing 10-⑥ to close the Overlap Window of Scooper mode.

using scraper

- Turn off the key **SCOOPE
ON/OFF** in drawing 2 ⑨.
It shows the key **SQUEEGE
SCRAPER** in drawing 2 ⑩.

- Press the key **SQUEEGE
SCRAPER** in drawing 2 ⑩.
It shows the Overlap Window of 'Scrapper Mode' in drawing 12.
(For more details, refer to in ch2 §2 M10 of Scrapper mode.)



drawing12 scraper mode

- Press the key **SCREEN FRAME
UP/DW.** in drawing 12 ①.
Screen Frame goes down.(For more details, refer to 1-2-2-1 'Screen Frame'.)
- Put Screen Mask on Screen Frame and fit to PCB.
- Turn on Sub clamp key and clamp Screen Mask temporarily.
- Make a micro-adjustment to set up to the correct position of Screen Mask using 4 micro-adjusters on Screen Frame.
- Turn on Main-clamp in drawing 11 ②, and clamp Screen by on Screen Frame.
- Press the key **SQUEEGE
PRESS FREE** in drawing 12 ③.
Air pressure is cut off and Squeegee goes down.

- Adjust the angle, the parallel, the height of Squeegee.

- Press the key

SQUEEGE
PRESS FREE
LIFT UP/DW.

 in drawing 12-③.
Squeegee goes up.

- Press the key

SCREEN FRAME
UP/DW.

 in drawing 12-①.
Screen Frame goes up.

- Adjust the height, the parallel of Scraper with Screen.

- Press the key

□

 12-④ to close Touch Panel of Scooper mode.

- Press the key

SCREEN FRAME
UP/DW.

 in drawing 12-①.
Screen Frame goes down.

- Move Squeegee unit backward to put ink on Screen Mask.

- Press the key

SQUEEGE
START

 in drawing 2-④.
Begin printing a PCB.

5. Carrying out a PCB

- Press the key

BOARD
OUT

 in drawing 2-⑤.
Carrier conveys PCB from Printing Section to Carry-out Section.

6. Check

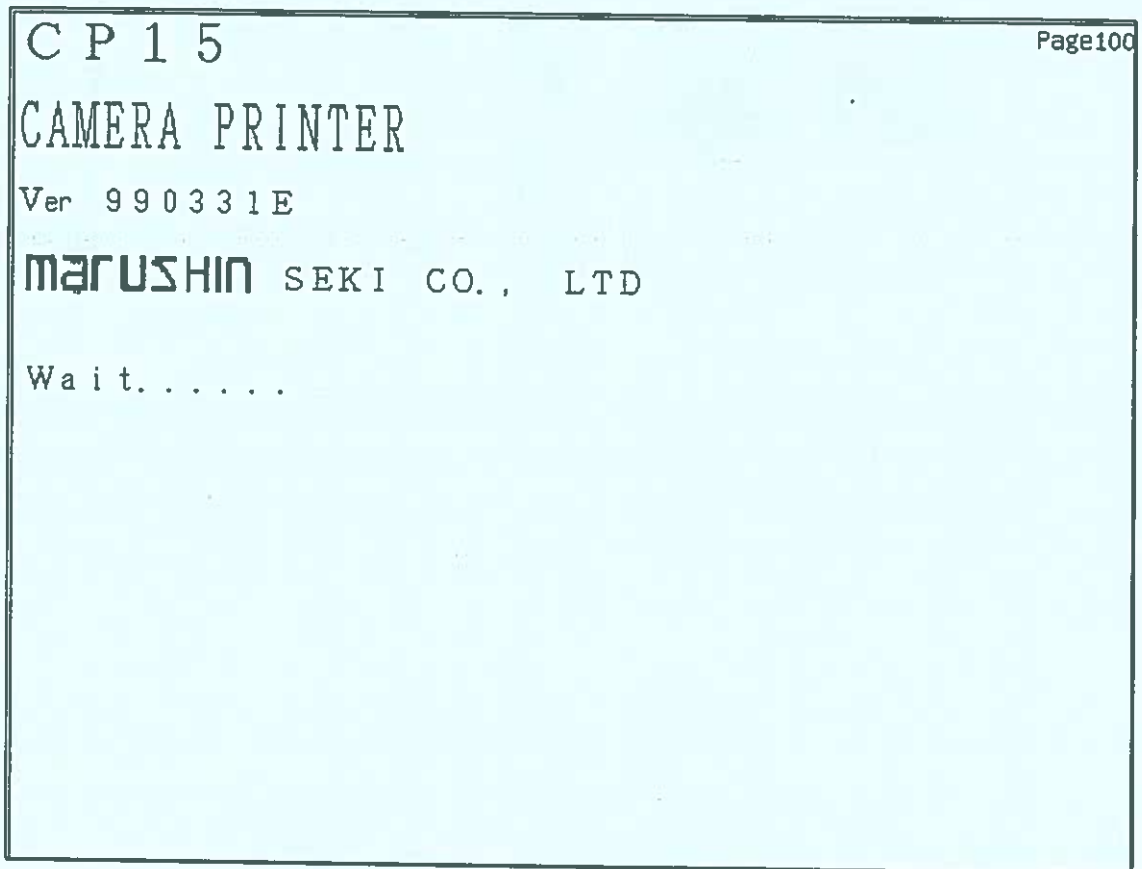
- Check the printed PCB isn't correct.
In case that printing has trouble, Make an appropriate adjustment and setting again, and print another PCB.

2-6.Auto-running

Auto-running is explained below.

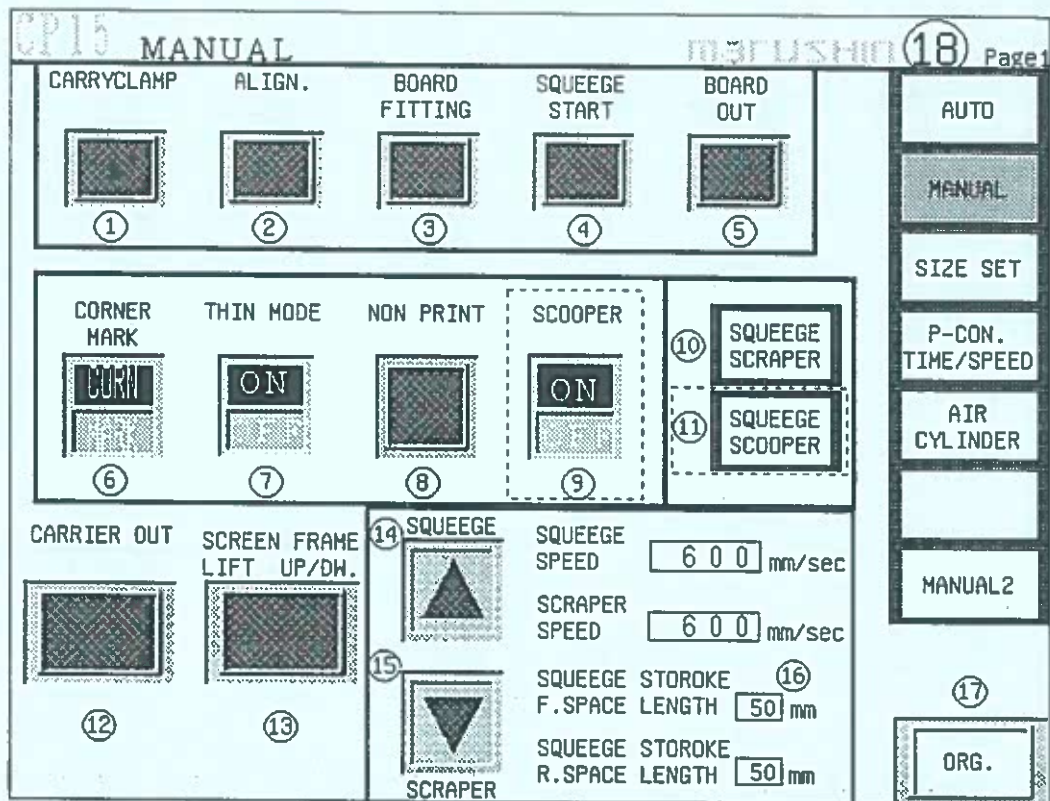
-1.T urn on CP-15

-2.T hen the initial set-up image shows up below.



The image of Manual Shows up.

-3.The image of MANUAL is drawn below.



- 4. Press No. M17 ORG to return the cylinders and motors to the original position. This key ORG turns green after return to the original position. Warning below is showed on Overlap Window if AUTO is pressed without pressing this key.

WARNING
NOT CYLINDER
ORIGINAL POSITION !
 PUSH **ORG** KEY

In this case, press ORG. key on Overlap Window or on MANUAL to return the cylinders and motors to the original position.

- 5. Press **AUTO** key on **MANUAL**, and then the image of **AUTO** shows up.
The image is drawn below.

CP15 AUTO manushin Page2

BOARD MARK/CORNER MODE BOARD THIN MODE SCRAPER/SCDOOPER MODE NON PRINT MODE PCB WAIT 11 TOP/BOTTOM CAMERA CARRIER TORQUE 7 0 % PRODUCT TACT 5.0 SEC ALIGN.PLACE 3.0 SEC PRINT PLACE 3.0 SEC SQUEEGING 1.0 SEC	<div style="border: 1px solid black; padding: 5px;"> 1 TOTAL/CN <div style="border: 1px solid black; text-align: center; padding: 2px;">9 9 9 9 9</div> </div> <div style="border: 1px solid black; padding: 5px; margin-top: 5px;"> 2 TOTAL RESET </div> <div style="border: 1px solid black; padding: 5px; margin-top: 5px;"> 3 PRISET/SET <div style="border: 1px solid black; text-align: center; padding: 2px;">9 9 9 9 9</div> </div> <div style="border: 1px solid black; padding: 5px; margin-top: 5px;"> 4 PRISET/CN <div style="border: 1px dashed black; text-align: center; padding: 2px;">9 8 7 6 5</div> </div> <div style="border: 1px solid black; padding: 5px; margin-top: 5px;"> 5 PRISET RESET </div>	<div style="border: 1px solid black; padding: 5px; margin-bottom: 5px;"> 6 BOARD OUT <div style="border: 1px solid black; width: 40px; height: 40px; margin: 5px auto;"></div> </div> <div style="border: 1px solid black; padding: 5px;"> 7 SCREEN FRAME LIFT UP/DW. <div style="border: 1px solid black; width: 40px; height: 40px; margin: 5px auto;"></div> </div>																																								
<table border="1" style="width: 100%; border-collapse: collapse; font-size: small;"> <tr> <td>PCB</td><td>500</td><td>x</td><td>500</td><td>P.TIMER</td><td>0.1</td><td>SQ.PRESS</td><td>5.0</td><td rowspan="5" style="border: none; text-align: center; vertical-align: middle;">8</td></tr> <tr> <td>AX POS.</td><td>123.456</td><td></td><td></td><td>GAP</td><td>3.6</td><td>SQ.LENGTH F.</td><td>50</td></tr> <tr> <td>AY POS.</td><td>123.456</td><td></td><td></td><td>OFFCON.</td><td>10</td><td>SQ.LENGTH R.</td><td>50</td></tr> <tr> <td>BX POS.</td><td>123.456</td><td></td><td></td><td>SQ.SPEED</td><td>700</td><td>SQ.STROKE</td><td>600</td></tr> <tr> <td>BY POS.</td><td>123.456</td><td></td><td></td><td>SC.SPEED</td><td>700</td><td>REGI. No</td><td>12345678</td></tr> </table>	PCB	500	x	500	P.TIMER	0.1	SQ.PRESS	5.0	8	AX POS.	123.456			GAP	3.6	SQ.LENGTH F.	50	AY POS.	123.456			OFFCON.	10	SQ.LENGTH R.	50	BX POS.	123.456			SQ.SPEED	700	SQ.STROKE	600	BY POS.	123.456			SC.SPEED	700	REGI. No	12345678	<div style="border: 1px solid black; padding: 5px; margin-bottom: 5px; text-align: center;"> 9 RESET </div> <div style="border: 1px solid black; padding: 5px; margin-bottom: 5px; text-align: center;"> 10 </div> <div style="border: 1px solid black; padding: 5px; text-align: center;"> T.STOP </div>
PCB	500	x	500	P.TIMER	0.1	SQ.PRESS	5.0	8																																		
AX POS.	123.456			GAP	3.6	SQ.LENGTH F.	50																																			
AY POS.	123.456			OFFCON.	10	SQ.LENGTH R.	50																																			
BX POS.	123.456			SQ.SPEED	700	SQ.STROKE	600																																			
BY POS.	123.456			SC.SPEED	700	REGI. No	12345678																																			

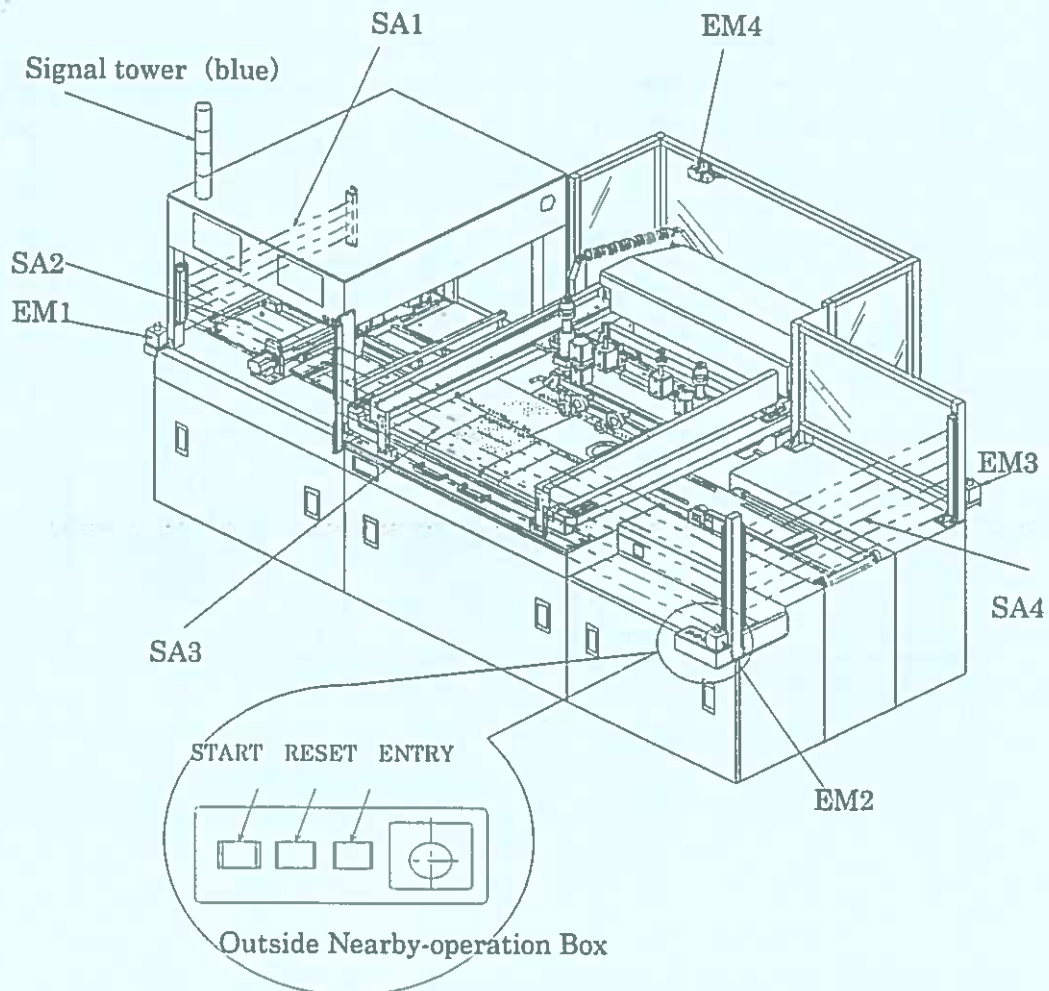
Check out the choice and set-up of the modes on **AUTO**.

Press START out of Touch Panel if nothing is wrong with the choice and set-up.

2-7. CE Modification

CP-15 is suitable for CE.

The overview drawing of CP-15 modified into CE is drawn below.



For detailed explanation of the above drawing, please refer to each section as below.

EM1,2,3,4 : CE-EM

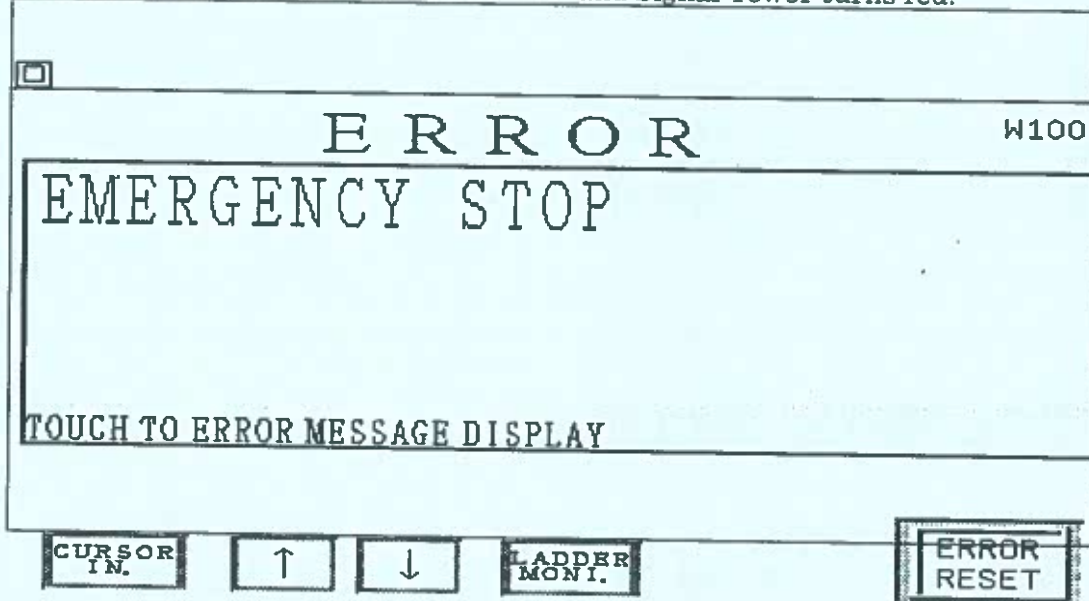
SA 1,2,3,4 : CE-SA

The apparatus attached to CP-15 is explained next.

CE-EM ①~④ outside Emergency Stop Switches and Cover Sensor

Pressing this switch leads CP-15 to an immediate stop and the servo motors, stepping motors and actuators to a cut-off of electricity.

ERROR below is showed on Touch Panel and Signal Tower turns red.



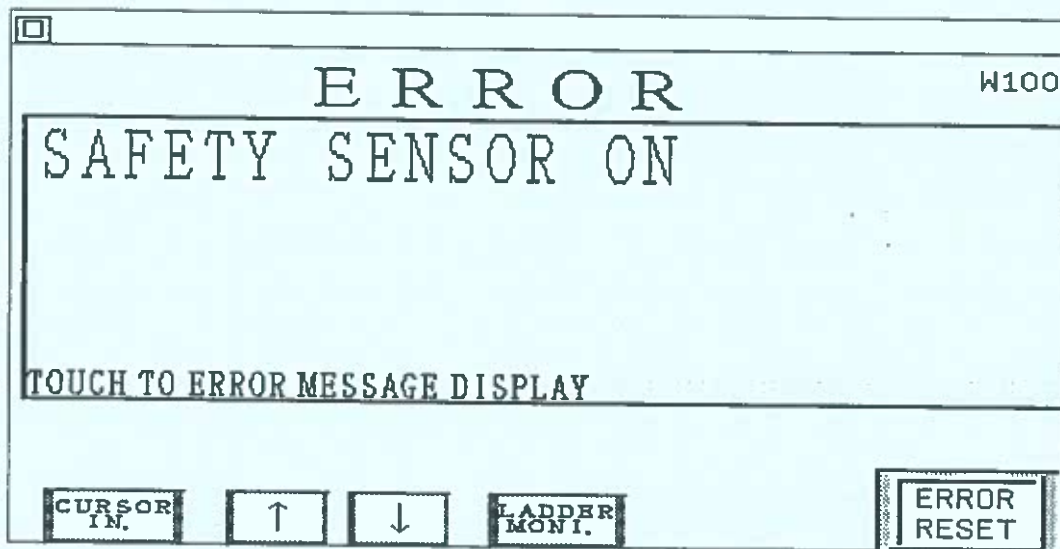
Pull up this Emergency Stop switch to re-start, and press **ERROR RESET** to release the error.

To re-start auto-running, refer to "2-6. Auto-running".

CE-SA ①~④ Safety Sensor s (to keep a worker from being hurt)

Safety Sensor is explained next.

- 1. Shutting out this Safety Sensor without pressing **ENTRY** on auto-running leads CP-15 to an immediate stop and the servo motors, stepping motors and air-actuators to a cut-off of electricity.



Leave the space of Safety Sensor area to re-start, and press **ERROR RESET** to release the error.

To re-start auto-running, refer to "2-6. Auto-running".

- 2. Enter the space of Safety Area Sensor after making sure to press **ENTRY** and confirming that blue Signal Tower is on, otherwise Electricity turns off.

Chapter 3 How to deal with errors and maintenance

3 - 1 If CP-15 falls into an error,

3 - 3 CP-15 Error Message Display

Error Message Display is explained next.

Error Message Display

If something wrong happens to CP-15, Error Message Display appears automatically.

If Error Message Display shows up, CP-15 comes to a stop and Signal Tower turns red.

How to deal with an error.....

See the details of an error

How to release an error.....

Press ERROR RESET key to release

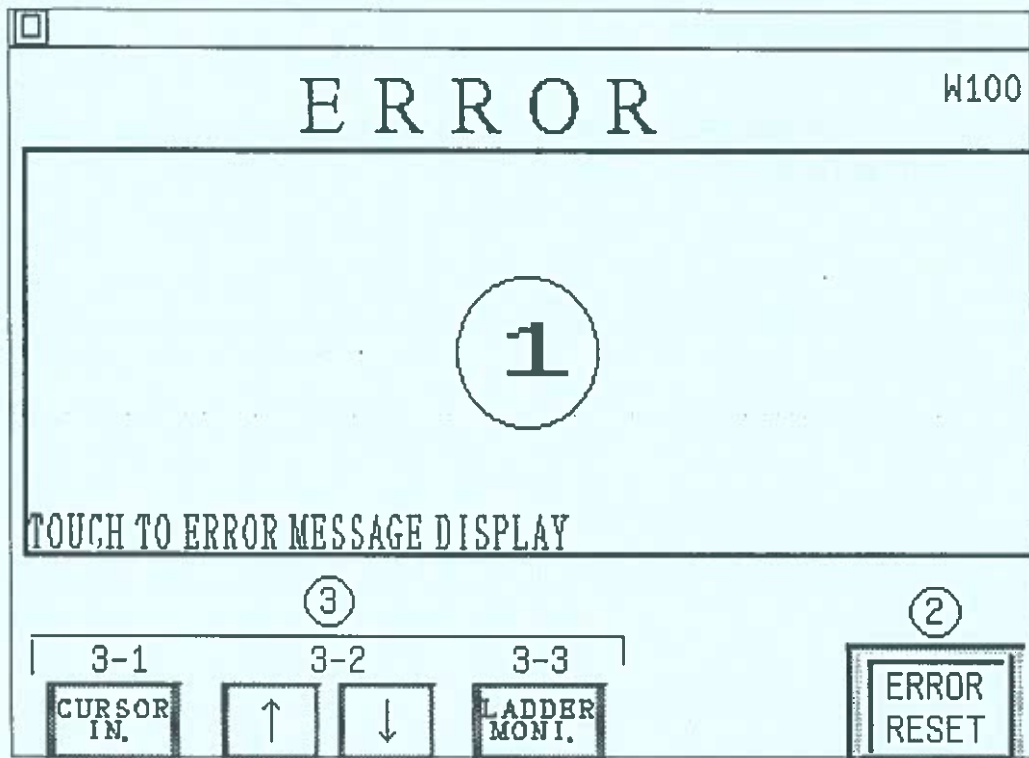
In case of a fatal error, turn off CP-15.

Chapter 3 How to deal with errors and maintenance

3 - 1 If CP-15 falls into an error,

If CP-15 falls into an error, Error Message Display below automatically appears and Signal Tower turns red.

Error Message Display is explained next.



For detailed explanations, refer to each section as below. :

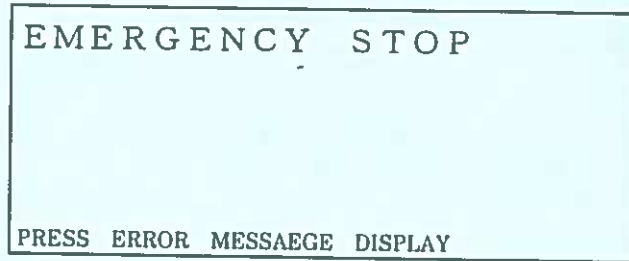
① : E-1

② : E-2

③ : E-3

E — ① Example of error message is explained.

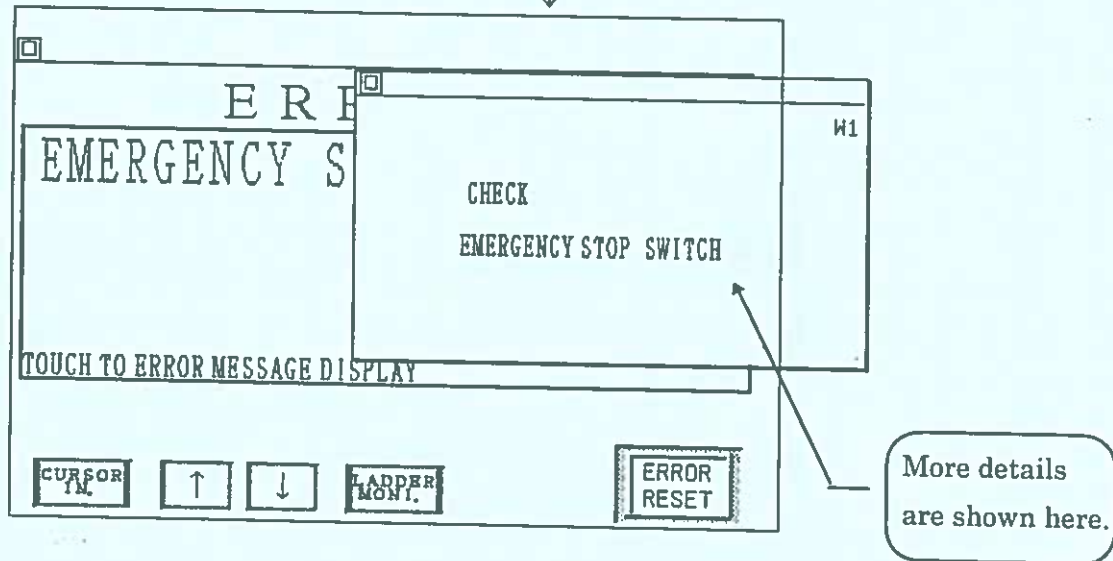
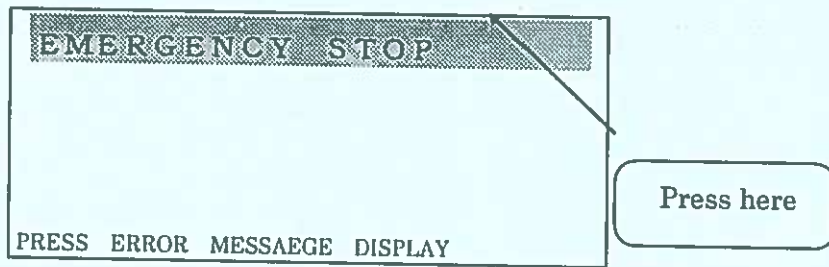
Example >



(4 messages can be shown at most if CP-15 falls into consecutive errors.)

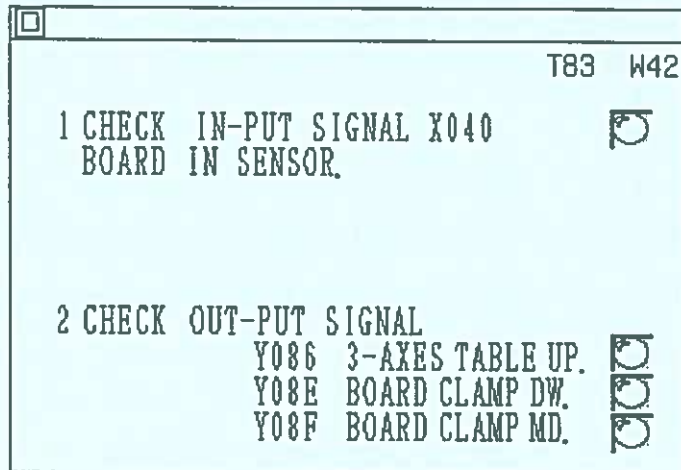


The details are explained next.



Detailed Error Message Display

Example >



Lamp to check
X040 Input Signal
ON : green
OFF : white

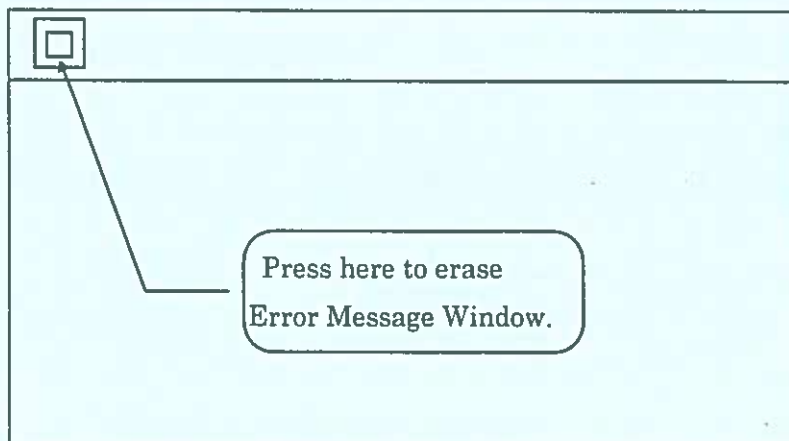
Check items are
shown here

Y...,M...,
Lamp to check
Output Signal
ON : green
OFF : white

< For more details on errors, refer to ch.3 § 2. >



How to erase Error Message Window after checking the details.



E — ② **ERROR RESET** key

ERROR RESET — Press **ERROR RESET** key to release the error and Error Message Window disappears.

fn.

ERROR RESET If an error can't be released, make sure to release it by Detailed Error Message Display.

If the error can't be released along the details, give us a contact.

E—③

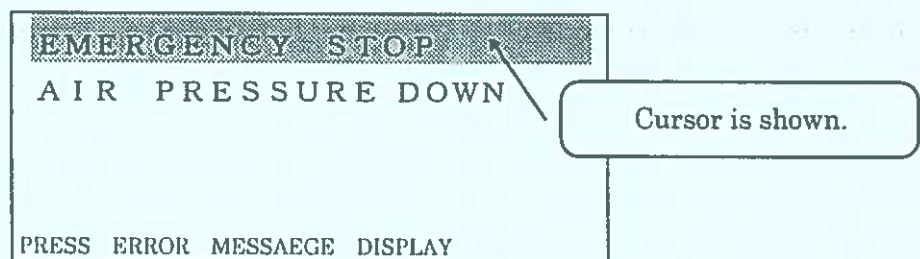
Function ③ is used when error can't be released on Detailed Error Message Display.

PLC program gets to be read and is monitored on Touch Panel.

The reading procedure of program on the error is explained below.

3 - 1 CURSOR IN key

A cursor shows up on Error Message when this key is pressed.

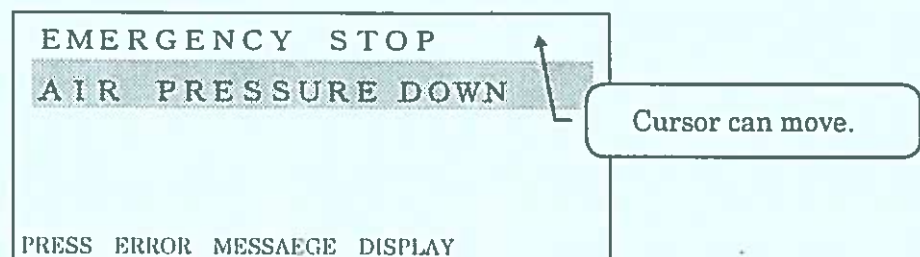


fn. Even though plural errors are shown on Error Message Display, cursor is always on the top.



3 - 2 ↑ ↓ key

Cursor display can move up/down.



3 - 3 **LADDER MONI.** key

PLC program image is shown on error.

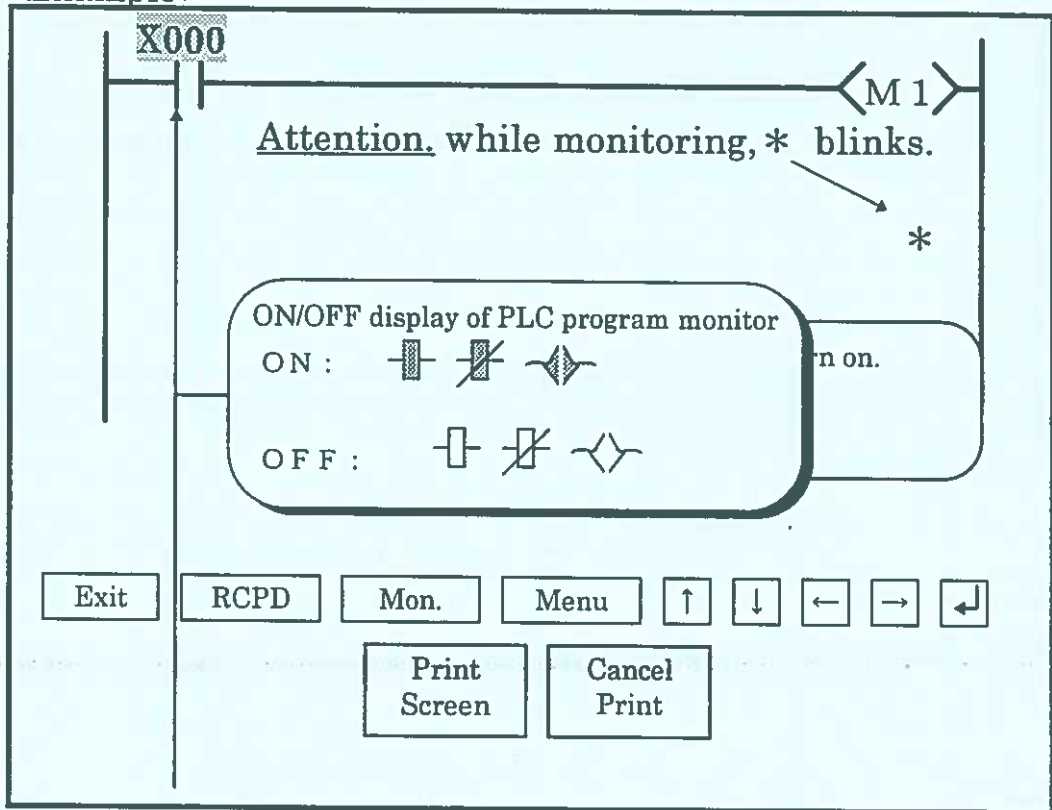
Point **LADDER MONI.** key is available only when cursor is on the Error Message Display.

PLC program Monitor automatically search the error and shown it.

Turn to the next page.

PLC program image

Example >



Check PLC program monitor and press Exit key ,then the former image gets back.

Key Functions

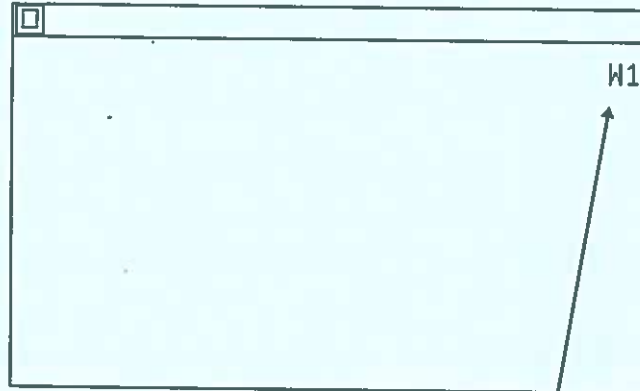
Exit	PLC program image ends. The former image gets back.
PCRD	PLC program begins to be read.
Mon.	Program monitoring begins to be done. (* blinks)
Menu	Devices, Coil etc. in program are sought.
↑ ↓	One circuit of program can be scrawled.
←	Next program is read.
Print Screen /Cancel Print	These are not used at the moment.

Chapter 3 How to deal with error and maintenance

3 - 2 How to maintain CP-15

How to deal with details

Detailed Error Message Display No.



W 1

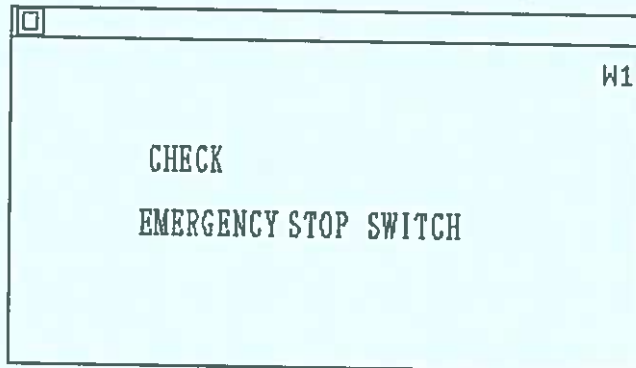
W : Message Display

1 : Message Display No.

Detailed Error Message is explained next in numerical order as W...

How to deal with details W 1

W 1 >



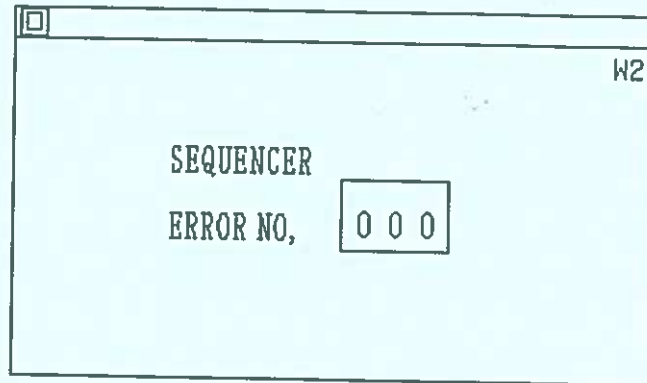
(Explanation) Emergency Stop Switch is pressed.

(Countermeasure) Release the Emergency Stop Switch.

Press ERROR RESET to release the error..

How to deal with details W 2

W 2 >



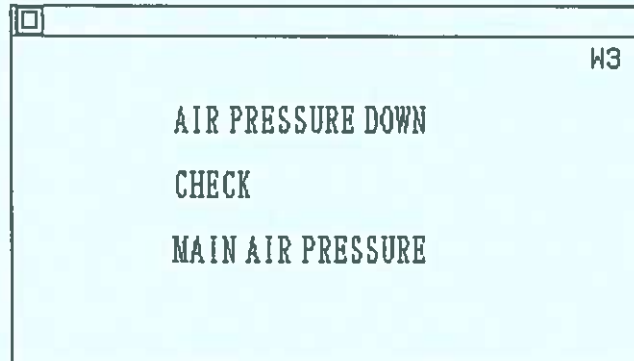
(Explanation) PLC Sequencer unit makes an error.

(Countermeasure)

- 1 : Turn off power supply, and turn it on again.
- 2 : If error No. **70** is shown battery voltage in Sequencer goes down. Change the battery
- 3 : Give us a contact in case showing another error No.

How to deal with details W 3

W 3 >



(Explanation) Air pressure (main pressure) is down.

(Countermeasure)

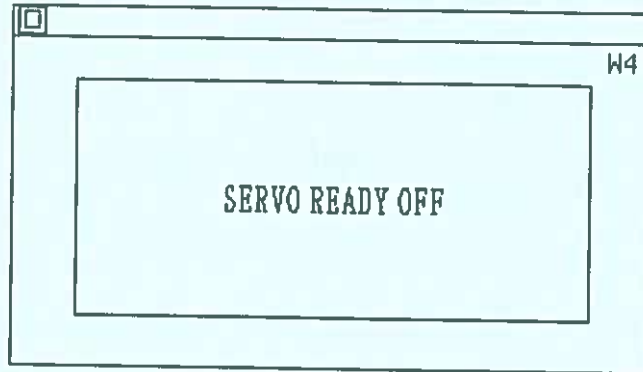
1 : Check the pressure on main air pressure gauge.

2 : Check the input signal of pressure sensor and circuit lines.

Press **ERROR RESET** to release the error.

How to deal with details W 4

W 4 >



(Explanation) Servo Amplifier turns off.

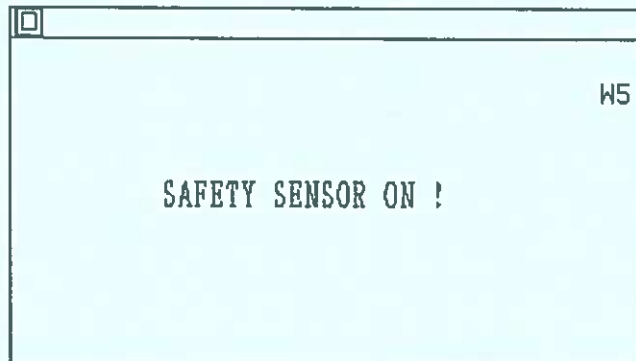
(Countermeasure)

1 : Turn off CP-15, and turn it on again.

2 : Give us a contact if it shows again after re-start.

How to deal with details W 5

W 5 >



(Explanation) Safety Areas sensor cut off.

(Countermeasure)

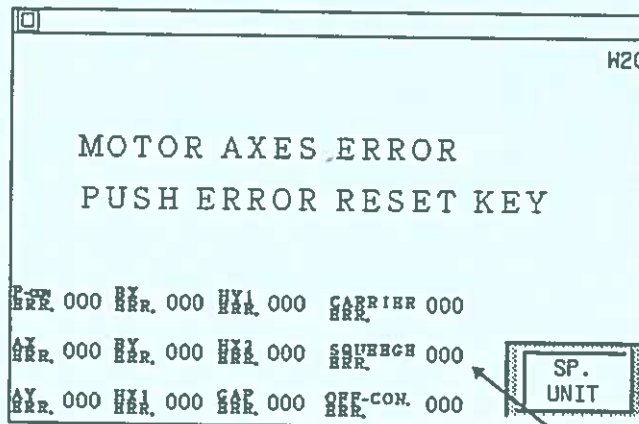
1 : Step away from safety Area Sensor, or check if there is any obstacle or not.

2 : Check the input signal of device No.X05C.

Press **ERROR RESET** to release the error.

How to deal with details W 2 0

W 20 >



(Explanation)

Motor axis made an error.

ex >

No. 000-regular

Except for No. 000-irregular

A motor axis on which No. 000 is not showed makes an error.

(Countermeasure)

1 : Press ERROR RESET key to release the error.

2 : In case ERROR RESET can't release it, turn off CP-15.

3 : How to deal with error codes is described below.

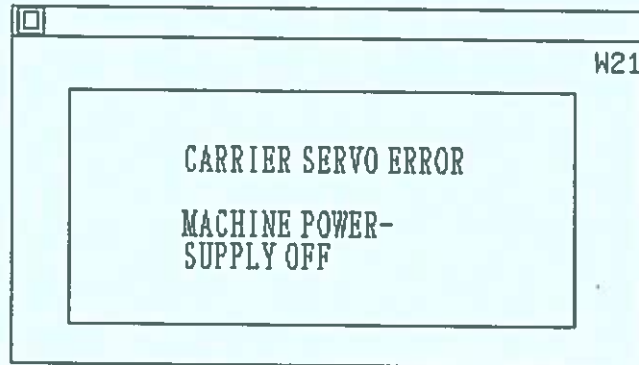
Countermeasure of error code chart

error code	Explanation	Countermeasure
1 0 4	OT sensor on +	Move to minus direction by using JOG key.
1 0 5	OT sensor on -	Move to plus direction by using JOG key.
5 0 7	soft stroke (out) starting +	: Size set ,numerical value settings. : Check the input of OT sensor. : In case the present position is out of the limits, move it by using JOG key.
5 0 8	soft stroke (out) starting -	
5 0 9	soft stroke (out) starting +	
5 1 0	soft stroke (out) starting -	

5 1 1	soft stroke (out) starting +	
5 1 2	soft stroke (out) starting -	
0 0 4	over flow	: Re-set CP-15 : Change Positioning unit.

How to deal with details W 2 1

W 2 1 >

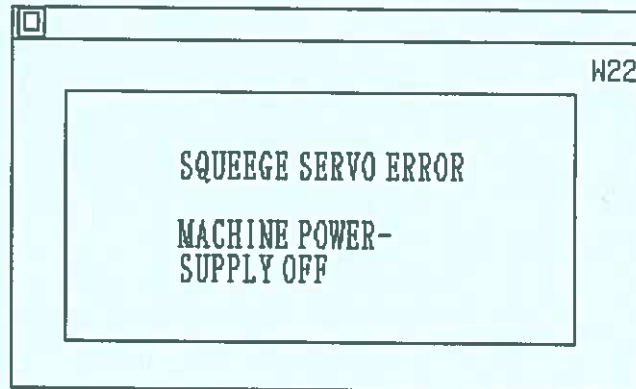


(Explanation) Carrier motor axis made an error.

(Countermeasure) 1 : Turn off CP-15, and turn on again.

How to deal with details W 2 2

W 22>

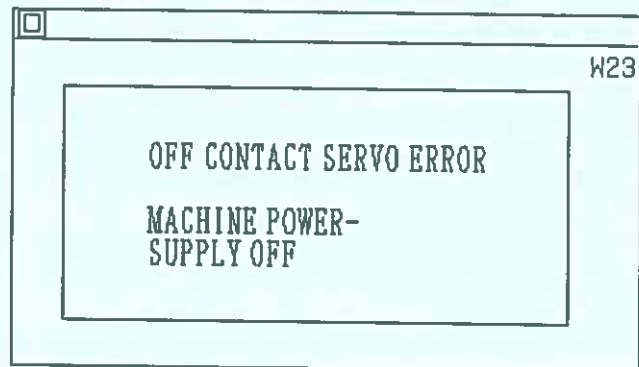


(Explanation) Squeegee motor axis made an error.

(Countermeasure) 1 : Turn off CP-15, and turn it on again.

How to deal with details W 2 3

W 23 >



(Explanation) Off Contact (Frame Separation) motor axis made an error.

(Countermeasure) 1 : Turn off CP-15, and turn it on again.

How to deal with details W 2 4 ~ W 2 5

W 24 >

CARRIER SERVO-MOTOR OVER TRAVER (+SOFT LIMIT) H24

PUSH KEY IN TO SOFT LIMIT COUNTER DATA

+SOFT LIMIT 110100	PULSE COUNTER CARRIER 111000
-----------------------	---------------------------------

CARRIER ERROR 509

Callouts: soft limit value (points to +SOFT LIMIT), present value (points to CARRIER 111000), jog key (points to jog key icon).

W 25 >

CARRIER SERVO-MOTOR OVER TRAVER (-SOFT LIMIT) H25

PUSH KEY IN TO SOFT LIMIT COUNTER DATA

-SOFT LIMIT 450	PULSE COUNTER CARRIER 550
--------------------	------------------------------

CARRIER ERROR 510

(Explanation) The present value of Carrier Servo axis exceeds soft limit value.

(Countermeasure)

1 : present value(out of the limits), the color of numerical value = red

present value(within the limits), the color of numerical value = black

2 : Change the value to one within the limits of soft limit by jog key.

Press ERROR RESET to release the error.

How to deal with details W 2 6 ~ W 2 7

W 2 6 >

SQUEEGE SERVO-MOTOR OVER TRAVER (+SOFT LIMIT) H26

PUSH KEY IN TO SOFT LIMIT COUNTER DATA

+SOFT LIMIT 500050	s q.	PULSE COUNTER 500100
-----------------------	------	-------------------------

SQUEEGE ERROR 509

soft limit value

present value

jog key

W 2 7 >

SQUEEGE SERVO-MOTOR OVER TRAVER (-SOFT LIMIT) H27

PUSH KEY IN TO SOFT LIMIT COUNTER DATA

-SOFT LIMIT -500000	s q.	PULSE COUNTER -500100
------------------------	------	--------------------------

SQUEEGE ERROR 510

(Explanation) The present value of Squeegee Servo axis exceeds soft limit value.

(Countermeasure)

1 : present value(out of the limits), the color of numerical value = red

present value(in the limits), the color of numerical value = black

2 : Change the value to one in the limits of soft limit by jog key.

Press ERROR RESET to release the error.

How to deal with details W 2 8 ~ W 2 9

W 2 8 >

OFF-CONTACT SERVO-MOTOR OVER TRAVEL (+SOFT LIMIT) W28

PUSH KEY IN TO SOFT LIMIT COUNTER DATA

+SOFT LIMIT 5 0 0 5 0	OFF-CON.	PULSE COUNTER 5 0 1 0 0
--------------------------	----------	----------------------------

OFFCON. ERROR 5 0 9

Callouts: soft limit value (points to +SOFT LIMIT), present value (points to PULSE COUNTER), jog key (points to key icon).

W 2 9 >

OFF-CONTACT SERVO-MOTOR OVER TRAVEL (-SOFT LIMIT) W29

PUSH KEY IN TO SOFT LIMIT COUNTER DATA

-SOFT LIMIT -5 0	OFF-CON.	PULSE COUNTER -1 0 0
---------------------	----------	-------------------------

OFFCON. ERROR 5 1 0

(Explanation) The present value of Off -Contact Servo axis exceeds soft limit value.

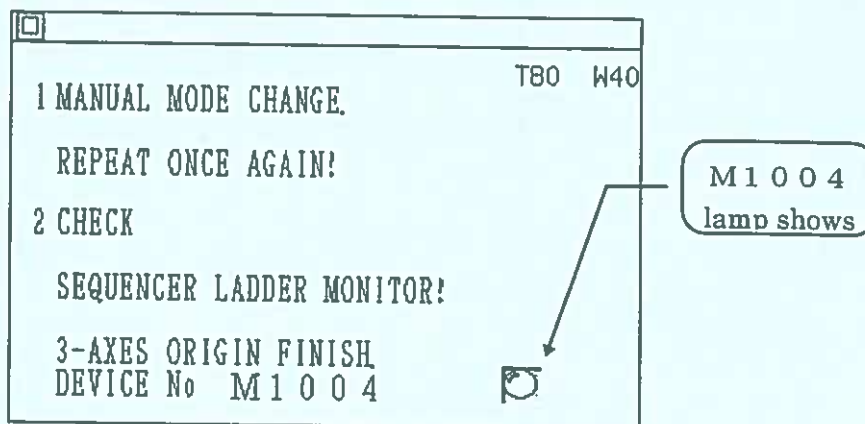
(Countermeasure)

- 1 : present value(out of the limits), the color of numerical value
red
 present value(within the limits), the color of numerical value
black
- 2 : Change the value within the limits of soft limit by jog key.

Press ERROR RESET to release the error.

How to deal with details W 4 0

W 4 0 >



(Explanation) 1 The return of 3-axis Table to the original point failed.

(Countermeasure)

- 1 : Go back to Manual image, and start auto-running again.
- 2 : Check if the Over-Travel sensors for all the motor axes of 3-axis table (X Y θ) are on.
- 3 : Find No. M 1 0 0 4 with **Coil Search** key on PLC program image and check which Input Signal is off.

fn.

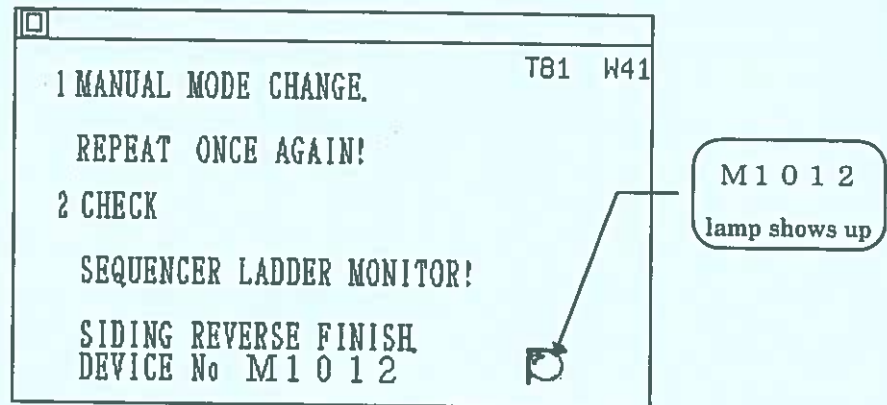
Use PLC program image on error.

For the details of Coil Search, refer to ch.3 §3.

Press ERROR RESET to release the error.

How to deal with details W 4 1

W 4 1 >



(Explanation) 1 : The return of siding to the original point failed.

(Countermeasure)

1 : Return to Manual image to start auto-running again.

2 : Find No. M1012 with **Coil Sea.** key on PLC program image, and check which Input Signal is off.

fn.

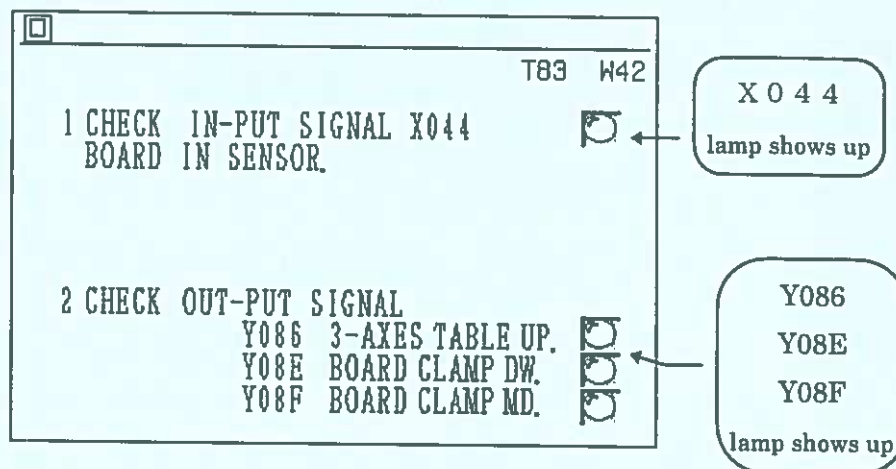
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error.

How to deal with details W 4 2

W 4 2 >



(Explanation) 1 Error happens at Carry-in section.

(Countermeasure)

- 1 : Check Input Signal of Board-In Sensor and check sensitivity of sensor.
- 2 : Find Output Signal No. Y... which lamp is not green with **Coil Sea.** key and check which Input Signal is off.

fn.

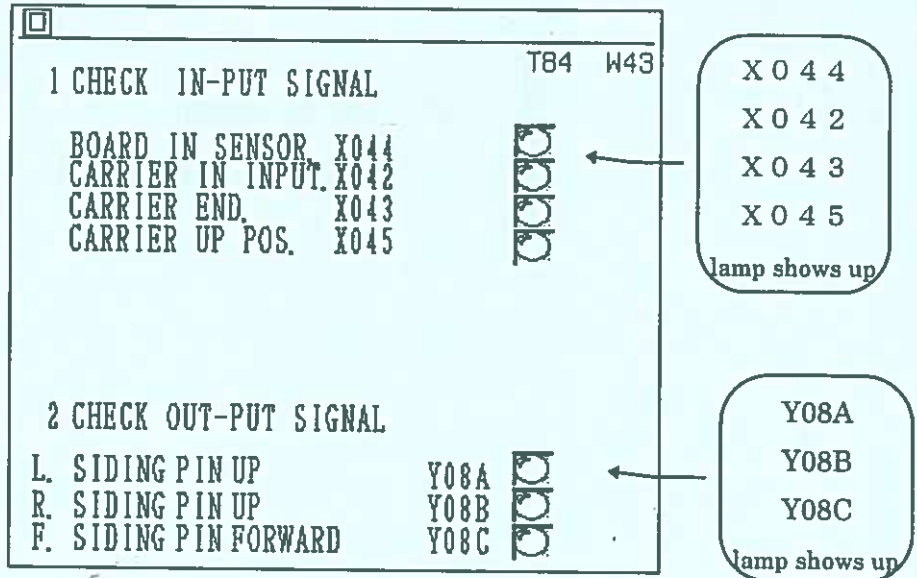
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error.

How to deal with details W 4 3

W 4 3 >



(Explanation) 1 Siding pins don't move at the time of siding.

(Countermeasure) 1 : Find the sensor which Input Signal X ... lamp is not green on Detailed Error Message Display.

fn.
Input Signal X045 is normal in off(white).

2 : Find Output Signal No. Y... which lamp is not green with **Coil Sea** key and check which Input Signal is off.

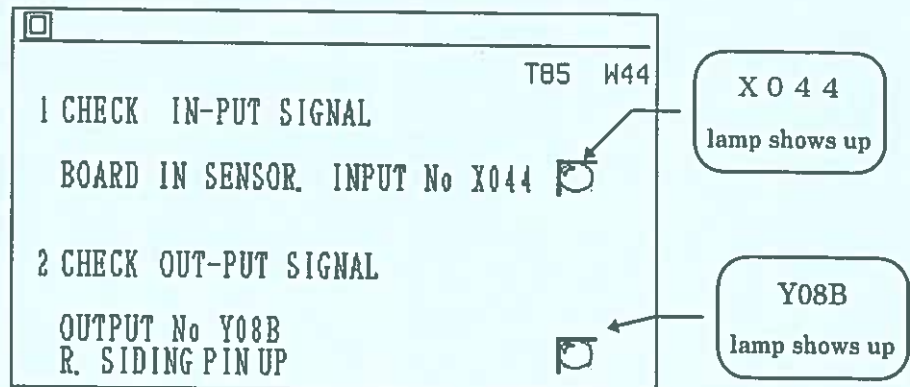
fn.
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

How to deal with details W 4 4

W 4 4 >



(Explanation) 1 Right siding pin doesn't move up.

(Countermeasure)

- 1 : Find the sensor which Input Signal X... lamp is not in green on Detailed Error Message Display.
- 2 : Find Output Signal No. Y... which lamp is not green with **Coil Sea.** key and check which Input Signal is off.

fn.

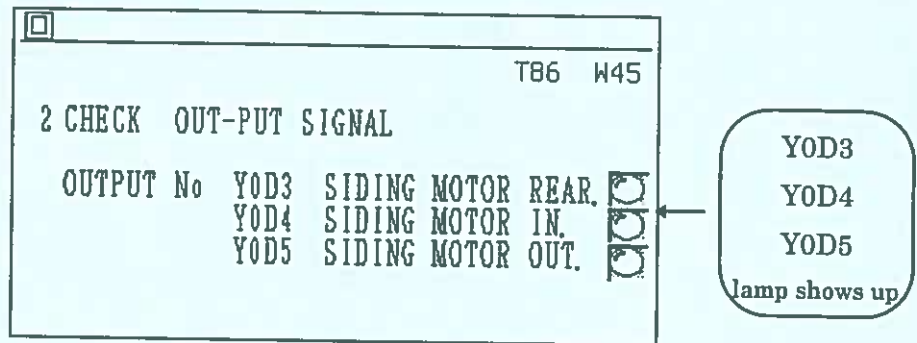
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error.

How to deal with details W 4 5

W 4 5 >



(Explanation) 1 Siding doesn't work.

(Countermeasure)

1 : Find Output Signal No. Y... which lamp is not green with **Coil Sea.** key and check which Input Signal is off.

Point

- : The check-out of Y0D4 is not needed when reference is left.
- : The check-out of Y0D5 is not needed when reference is right.

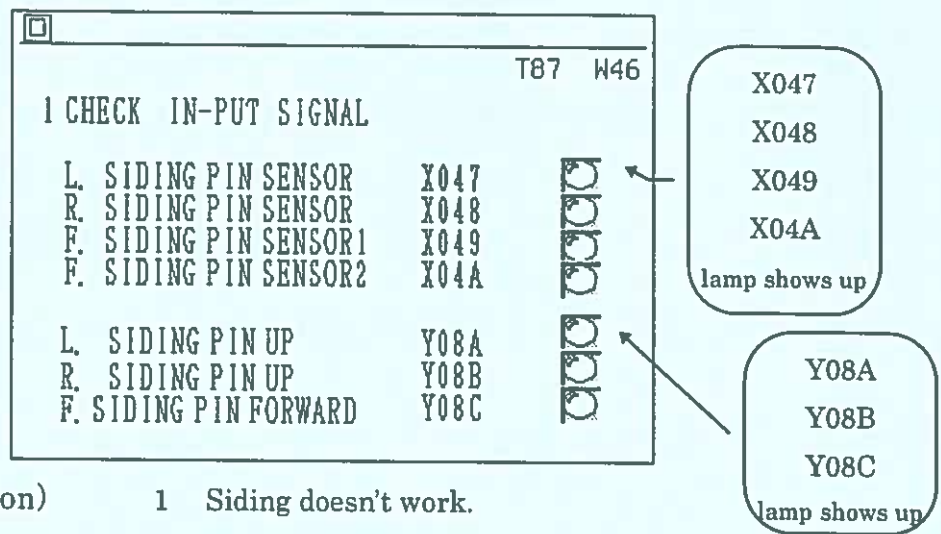
fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

W 4 6 >



(Explanation) 1 Siding doesn't work.

or

Siding check-out sensor remains off.

(Countermeasure)

1 : Check out the sensor which input lamp is not green.

2 : Check out siding powder clutch and push-up torque.

3 : Find Output Signal No. Y... which lamp is not green with **Coil Sea** key and check which Input Signal is off.

Point

- : Check Counter Measure 1 : and 2 : if Y... is in green.
- : The check-out of X048 is not needed when reference is left.
- : The check-out of X047 is not needed when reference is right.

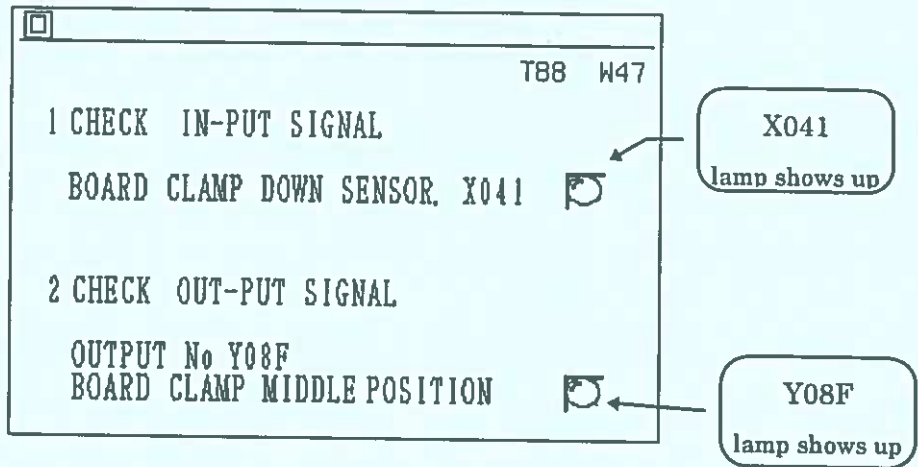
fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

W 4 7 >



(Explanation)

- 1 The lowest-position sensor of Board Clamp remains off.

or

The middle-position air-cylinder of Board Clamp.

(Countermeasure)

- 1 : Check the sensor of device No. X041 (the lowest PCB clamp).
- 2 : Check the movement of Board Clamp up / down
- 3 : Find Output Signal No. Y08F which lamp is not green with **Coil Sea** key and check which Input Signal is off.

Point

Check Counter Measure 1 : 2 : if Y08F is green.

fn.

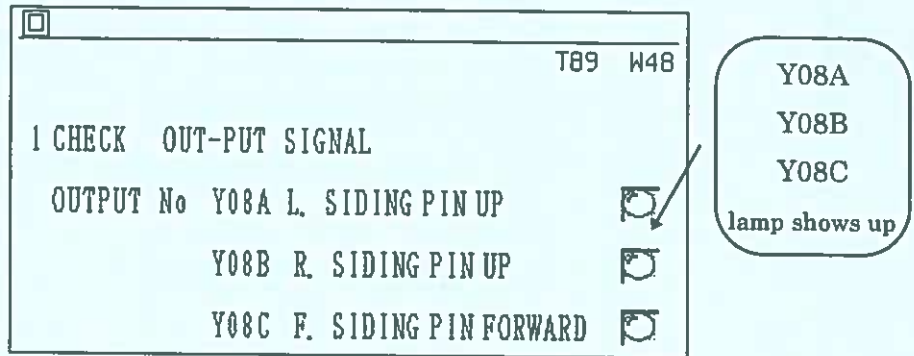
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error. .

How to deal with details W 4 8

W 4 8 >



(Explanation) 1 Siding pin(right / left) doesn't move down.

or

Siding pins (front) don't move backward.

(Countermeasure)

- 1 : Find Output Signal No. Y... which lamp is not green with **Coil Sea** key and check which Input Signal is off.

fn.

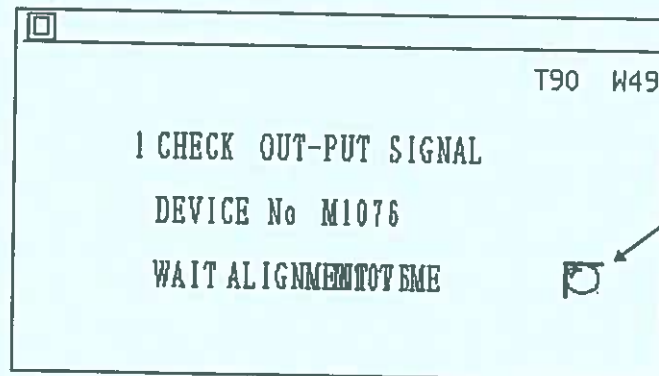
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error. .

How to deal with details W 4 9

W 4 9 >



M1076
lamp shows up

(Explanation) 1 Alignment waiting time is up.

(Countermeasure)

1 : Find Output Signal No. M1076 which lamp is not

green

with **Coil Sea** key and check which Input Signal is off.

fn.

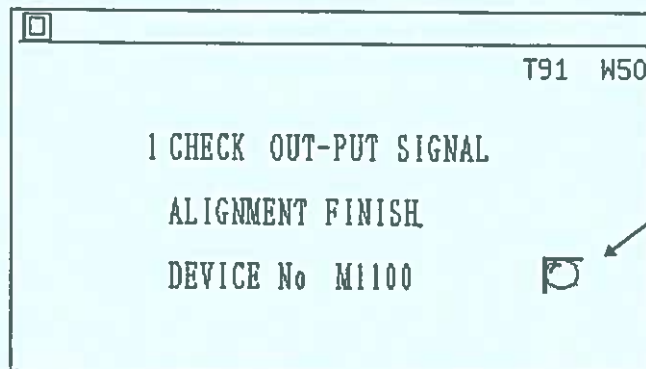
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error.

How to deal with details W 5 0

W 5 0 >



M1100
lamp shows up

(Explanation)

1 Alignment isn't completed.

or

2 Input signal doesn't turn on even though alignment is completed.

(Countermeasure)

1 : Find Output Signal No. M1100 which lamp is not green with **Coil Sea** key and check which Input Signal is off.

fn.

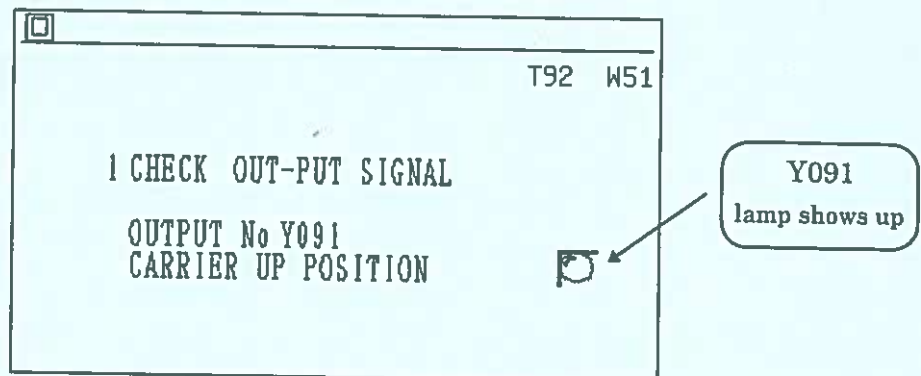
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

How to deal with details W 5 1

W 5 1 >



(Explanation) 1 Carrier doesn't move up at **THIN MODE** .

(Countermeasure)

- 1 : Check the input of Carry-in END Sensor
Check the input of Catty-in Down Sensor
- 2 : Find Output Signal No. Y091 which lamp is not green with **Coil Sea** key and check which Input Signal is off.

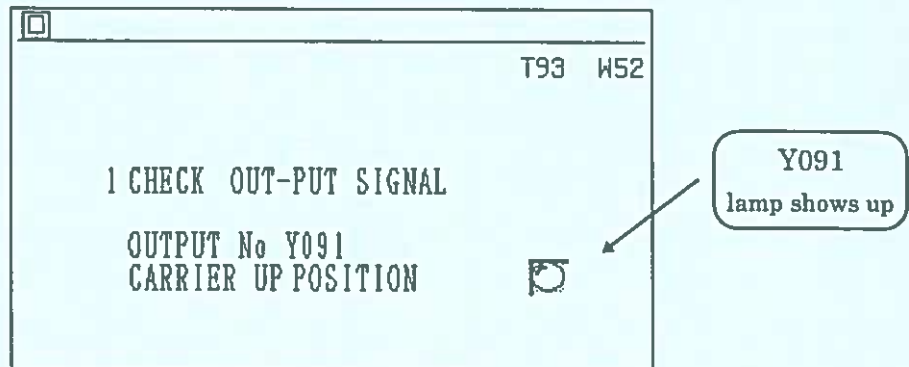
fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.
Press **ERROR RESET** to release the error.

How to deal with details W 5 2

W 5 2 >



(Explanation) 1 Carrier doesn't move up.

(Countermeasure)

1 : Check the input of Carry-in END Sensor
Check the input of Catty-in Down Sensor

2 : Find Output Signal No. Y091 which lamp is not green with
Coil Sea key and check which Input Signal is off.

fn.

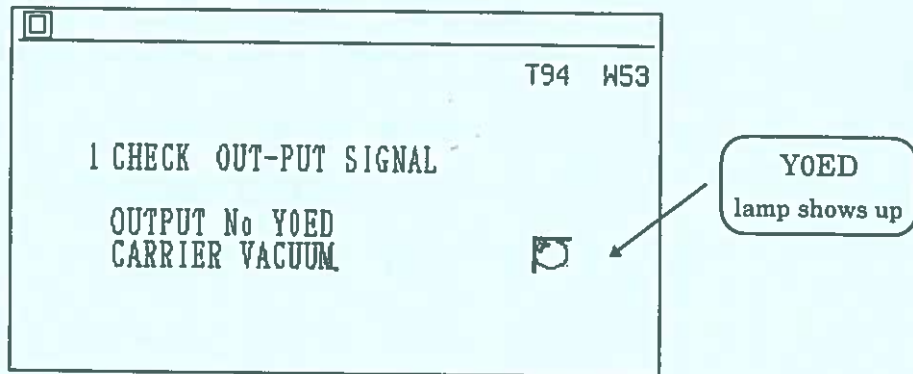
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

How to deal with details W 5 3

W 5 3 >



(Explanation) 1 Carrier Vacuum doesn't work.

(Countermeasure)

- 1 : Check if Carry-in Down Sensor is off.
Check if Carry-in END Sensor is on.
- 1 : Find Output Signal No. YOED which lamp is not green with **Coil Sea** key and check which Input Signal is off.

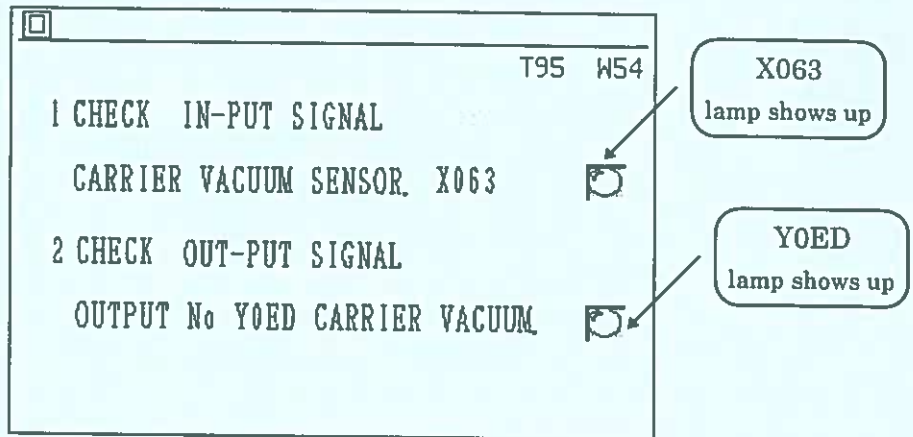
fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

W 5 4 >



- (Explanation)
- 1 Carrier Vacuum Sensor is not on.
or
 - 2 Carrier Vacuum doesn't work.

- (Countermeasure)
- 1 : X063 (Carrier Vacuum Sensor) Lamp is off (white)
↓
Check the difference between the set value and the present value.
↓ NO
The present value is lower than the set value. → Check Sensor and electrical lines
↓ YES NO
Carrier Vacuum is leaking → Decrease the set value
↓ YES
Re-set Vacuum values
 - 1 : Find Output Signal YOED with **Coil Sea** key and check which input signal is off.

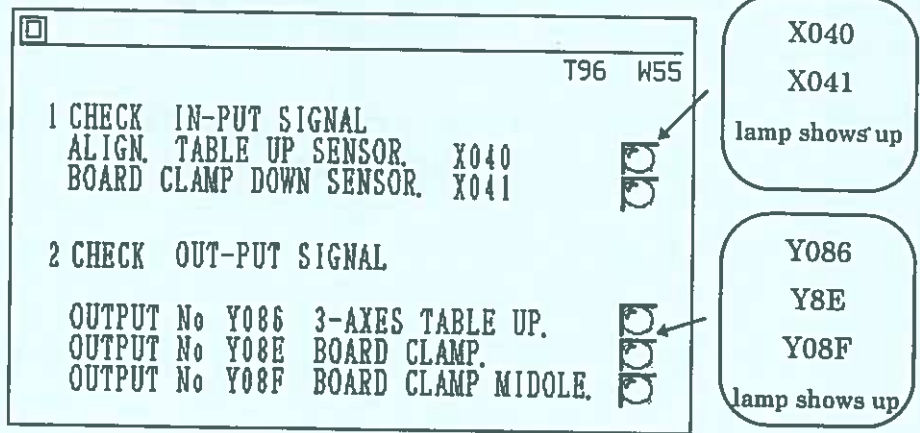
fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.
Press **ERROR RESET** to release the error.

How to deal with details W 5 5

W 5 5 >



(Explanation) 1 : Board Clamp is not waiting.
or
Board Clamp can not wait.

fn.

One lamp at least is usually green on W55 error.

(Countermeasure)

1 : Check that all the Output Signals (Y...) are off (white) on Detailed Error Message Display.



If there is any Output Signal which is on (green), check it with **Coil Sea.** key.

fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.



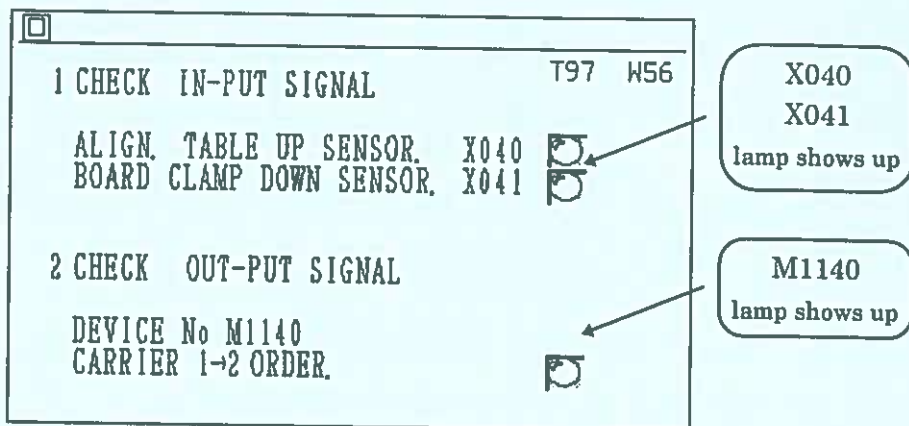
(Countermeasure)

2 : Check Input Signal of Alignment Table Up Sensor X040
OFF(white) is Normal

3 : Check Input Signal of Board Clamp lowest Sensor X041
OFF(white) is Normal

Press ERROR RESET to release the error.

W 5 6 >



(Explanation) 1 Carrier Servo axis move from Carry-in position to Printing position.

(Countermeasure)

1 : Alignment Table Up Sensor (X040) is on.



Check that Alignment Table is at the lowest.



Check input of X040 sensor or electrical lines.

2 : Board Clamp Down Sensor (X041) is still on.



Check that Board Clamp is at the highest.



Check Input of X041 sensor or electrical lines.

3 : Find Output Signal M1140 with Coil Sea key and check which input signal is off.

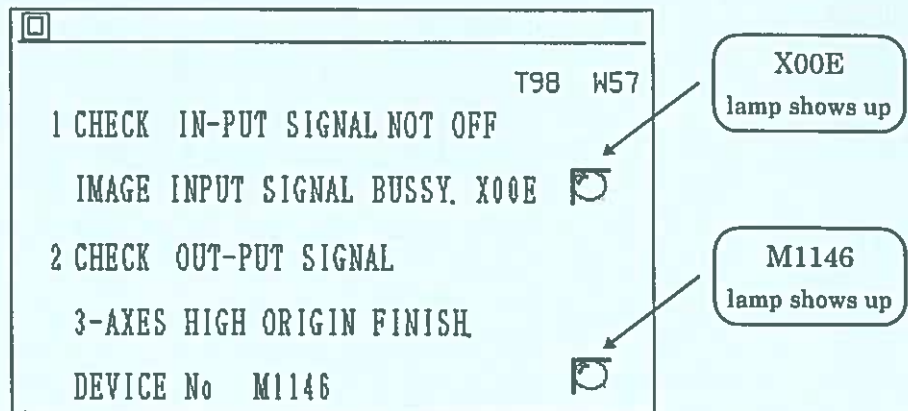
For the details of Coil Search, refer to Ch.3 § 3

Press ERROR RESET to release the error.

fn.

Use PLC program image on error.

W 5 7 >



(Explanation) 1 The high-speed return of 3-axis Table the original position failed and time up.

(Countermeasure)

- 1 : Release the error to return Manual image and start auto-running.
- 2 : Find Output Signal M1146 with Coil Sea. key and check which input signal is off.

fn.

X00E is correct in white(OFF). M1146is correct in green(ON).

fn.

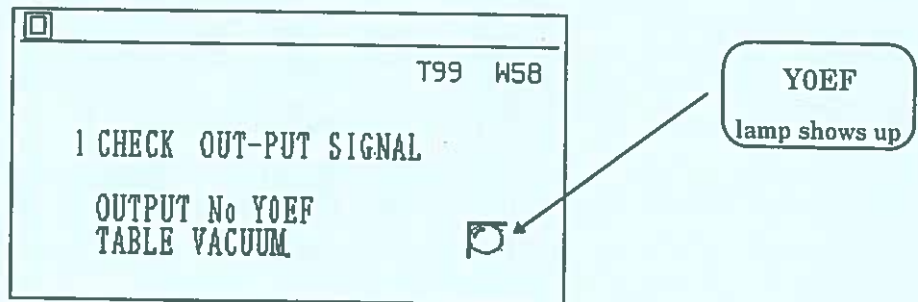
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

How to deal with details W 5 8

W 5 8 >



(Explanation) 1 Printing Table Vacuum doesn't work.

(Countermeasure)

- 1 : Check Input Signal of Lowest -Carrier Sensor(X058).
- 2 : Check Input Signal of Carry-out End Sensor(X05D).
- 3 : Find Output Signal YOEF with **Coil Sea** key and check which input signal is off.

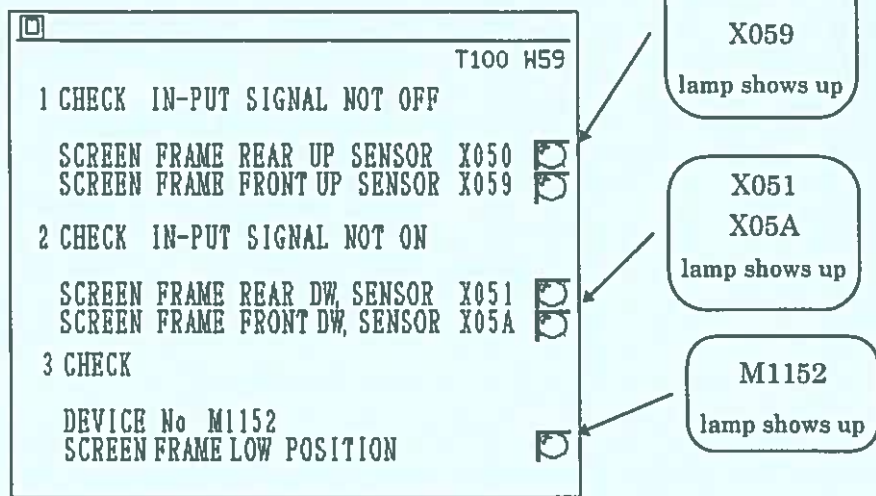
fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

W 5 9 >



(Explanation) 1 Screen Frame is not at the lowest.

(Countermeasure)

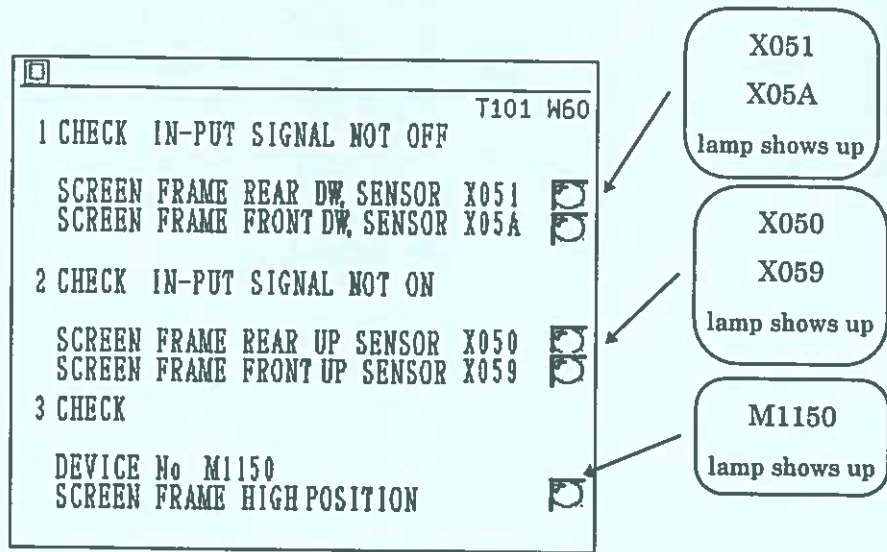
- 1 : Check if Screen Frame is at the lowest.
- 2 : Check Screen Frame Sensor on Error Detailed-Massage Display.
X050,X059 the highest sensor OFF(white)
X50,X05A the lowest sensor ON(green)
- 3 : Find Output Signal M1152 with Coil Sea key and check which input signal is off.

fn.
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

W 6 0 >



(Explanation) 1 Screen Frame is not at the highest.

(Countermeasure)

- 1 : Check if Screen Frame is at the highest.
- 2 : Check Screen Frame Sensor on Error Detailed-Massage Display.
X051,X05A the highest sensor OFF(white)
X50,X05A the lowest sensor ON(green)
- 3 : Find Output Signal M1152 with **Coil Sea** key and check which input signal is off.

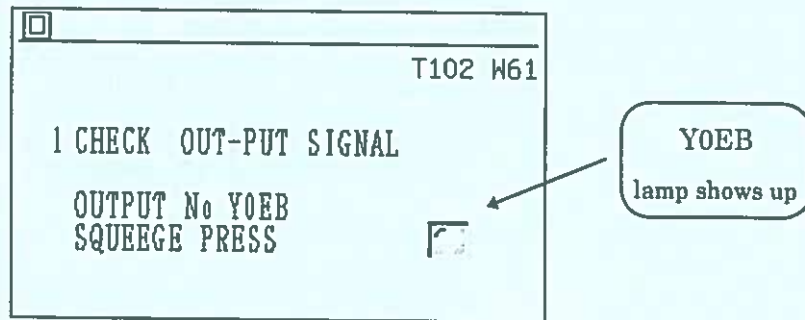
fn.
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

How to deal with details W 6 1

W 6 1 >



(Explanation) 1 Squeegee Press doesn't move down.

(Countermeasure)

1 : Find Output Signal YOEB with Coil Sea key and check which input signal is off.

fn.

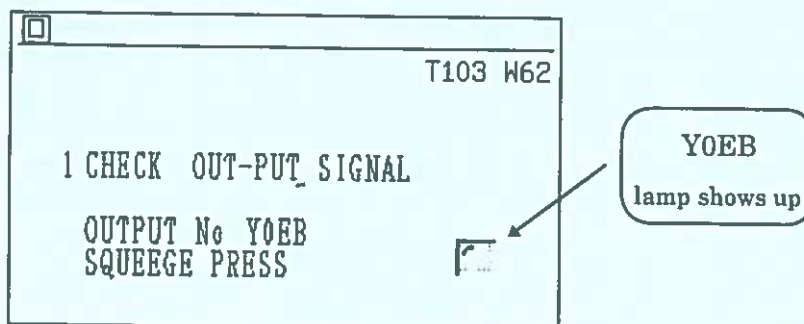
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

How to deal with details W 6 2

W 6 2 >



(Explanation) 1 Squeegee Press doesn't move up.

Point

YOEB Lamp is correct in white (OFF) if Squeegee Press move-up makes an over-time error(W 6 2).

(Countermeasure)

- 1 : Find Output Signal YOEB with **Coil Sea** key and check which input signal is off.

fn.

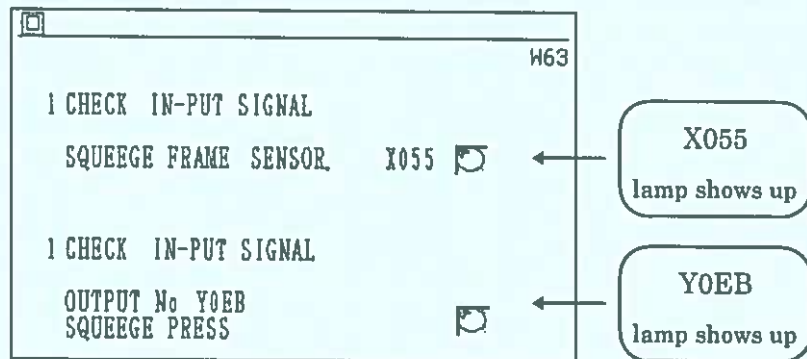
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error.

How to deal with details W 6 3

W 6 3 >



(Explanation) Squeegee Frame moves up and Squeegee pressure gets cut off while printing.

(Countermeasure)

- 1: Check Input Signal(X055)of Squeegee Frame Sensor .
- 2 : Find Output Signal YOEB with **Coil Sea** key and check which input signal is off.

fn.

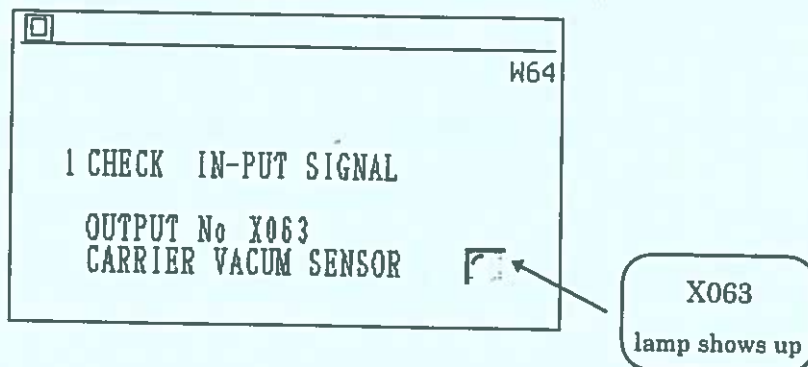
Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press **ERROR RESET** to release the error.

How to deal with details W 6 4

W 6 4 >



(Explanation) Carrier Vacuum pressure gets down while printing and Squeeging pressure gets cut off.

(Countermeasure)

- 1 : Check Input Signal (X063) of Carrier Vacuum Sensor.
- 2 : Find Output Signal M1100 with **Coil Sea** key .
If coil is off, it is normal.

fn.

Use PLC program image on error.

For the details of Coil Search, refer to Ch.3 § 3.

Press ERROR RESET to release the error.

Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 Warning Image Window

Warning Image Window is explained next.

Warning Image Window shown on auto-running... • •

Warning message shows up if something abnormal happens on auto-running.

This is different from Error, so auto-running doesn't stop.

Warning message automatically disappears when running conditions are set.

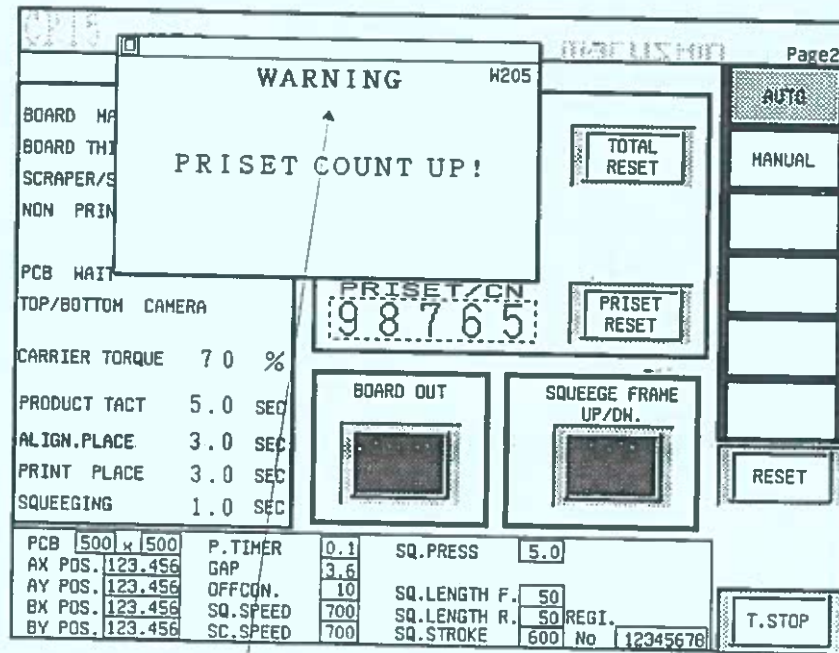
Warning Image Window shown on Manual... • •

Warning message is shown to protect against an operational mistake on Manual. Warning message automatically disappears when running conditions are set.

3 - 3 CP-15 Warning Image Window

Warning Image Window is explained next.

Example >



Warning Image Window



It's impossible to erase Warning Message deliberately. Warning message automatically disappears when running conditions are set.

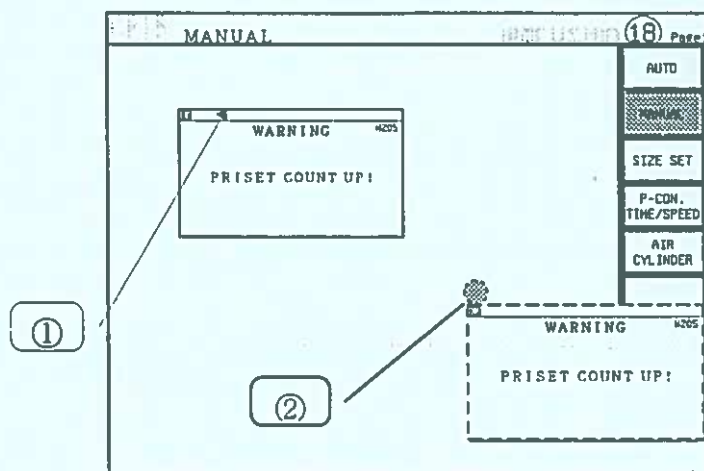
The position of Warning Message Window can be changed.

How to change the position is explained next.

3 - 3 CP-15 Warning Image Window

How to change the position of Warning Message Window is explained next.

Example >



↓
Press ① (It buzzes)

Press ② (It's available while buzzing)

Point

② is a new position.

3 - 3 CP - 1 5 Warning Image Window

How to see Warning Image Window

Example >

The diagram shows a rectangular window with a title bar. The text inside the window is as follows:

WARNING W207

NOT CYLINDER

ORIGINAL POSITION !

PUSH ORG KEY

Three callout boxes provide additional information:

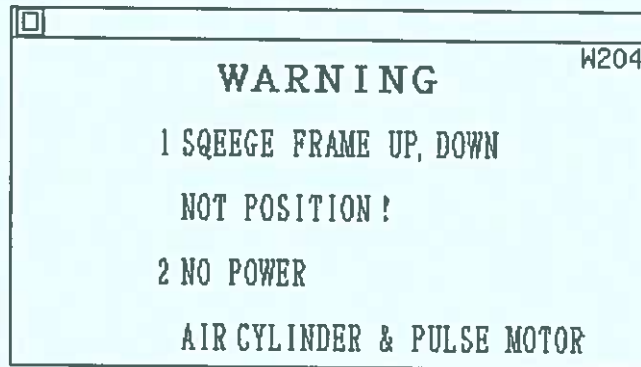
- A box on the left points to the main text: "The meaning of warning is shown."
- A box at the bottom points to the "ORG" key: "This key can be pressed."
- A box on the right points to the "W207" label: "Image No. is shown here
W = Window
207 = Image No."

Each Warning Message Window is explained next.

3 - 3 CP-15 Warning Image Window

Explanation of Warning Image Window W204

W204 >



(Explanation) Squeegee Frame remains in between
or
AIR apparatus or pulse motor are cut off.

(Cause) Input Signal of No. X5C Safety Sensor or X4E, X4F Squeegee
Frame up/down Sensor is not on.

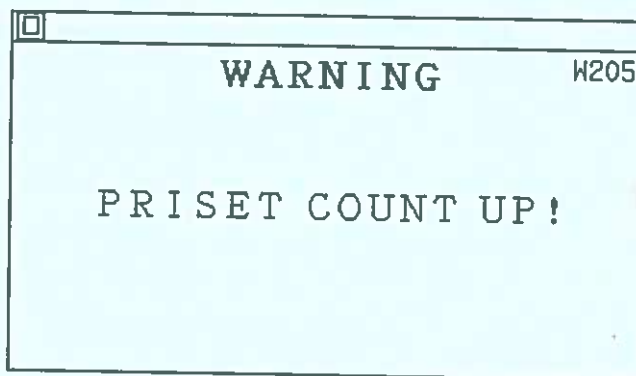
(Countermeasure) Check Input Signal of Safety Sensor.

Press Squeegee Frame up/down key to move it up.

3-3 CP-15 Warning Image Window

Explanation of Warning Image Window W205

W205 >



(Explanation) Preset Counter caught up with the set value.

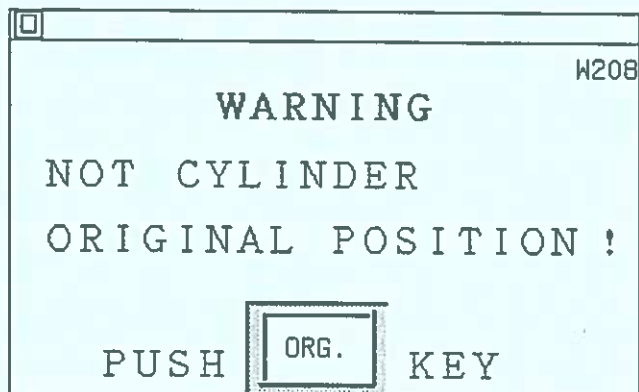
(Countermeasure)

- 1 : Press **PRISET RESET** key to clear 0 on auto-running image.
- 2 : Move Squeegee Frame up and down. The counter gets to clear 0.

3-3 CP-15 Warning Image Window

Explanation of Warning Image Window W207

W207 >



(Explanation) This Warning message shows up when Manual set-up or Auto-running is done with **[ORG.]** key on Touch Panel NOT green.

(Cause) The cylinders except Squeegee cylinder and Carrier haven't returned to the original position.

(Countermeasure)

Press **[ORG.]** key to return the cylinders and Carrier to the original position.

Warning Message Window automatically disappears after **[ORG.]** key turns green.

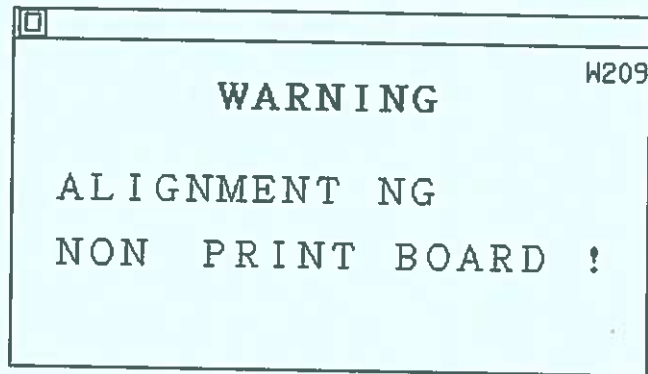
fn.

Make sure to take any PCBs away from CP-15 to press **[ORG.]** key, otherwise CP-15 could be damaged.

3-3 CP-15 Warning Image Window

Explanation of Warning Image Window W209

W209 >



(Explanation) Image processed value gets to be out of the allowance the limits,

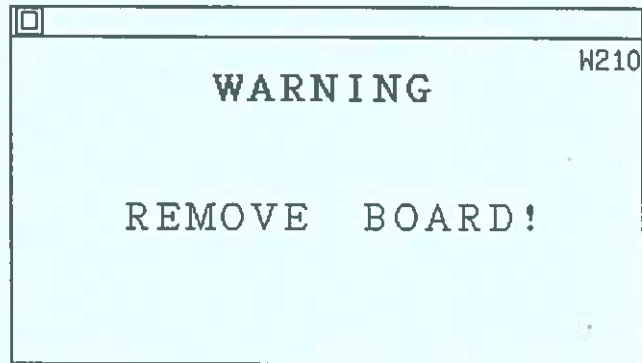
so PCB is conveyed onto Carry-out Conveyer.

(Countermeasure) If a next PCB is correctly image-processed, Warning Message Window automatically disappears.

3 - 3 CP-15 Warning Image Window

Explanation of Warning Image Window W 2 1 0

W 2 1 0 >



(Explanation) A PCB is at Carry-in Section, so CP-15 doesn't run.

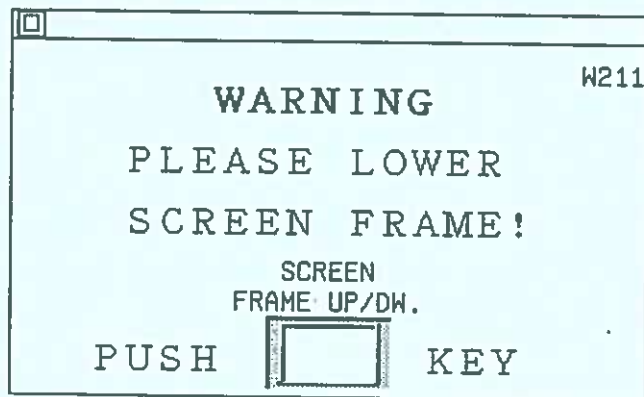
(Countermeasure)

Take a remaining PCB away from Carry-in Section, so Warning Message Window automatically disappears.

3 - 3 CP-15 Warning Image Window

Explanation of Warning Image Window W 2 1 1

W 2 1 1 >



(Explanation) Screen Frame remains up when squeegee on Manual.

(Countermeasure)

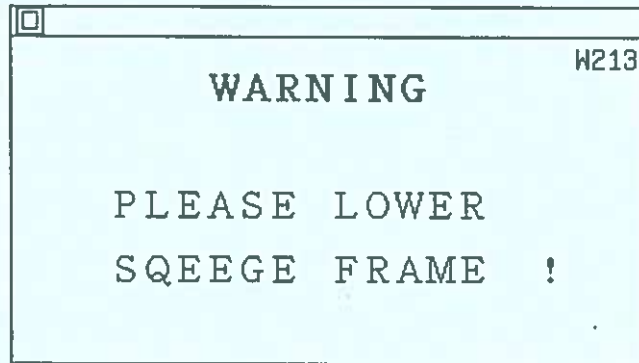
Press **SCREEN FRAME UP/DW** key to move Screen Frame down.

When Screen Frame lowest point is sensed, Warning Message Window automatically disappears.

3-3 CP-15 Warning Image Window

Explanation of Warning Image Window W213

W213 >



(Explanation) Printing can't be done with Squeegee Frame up.

(Countermeasure)

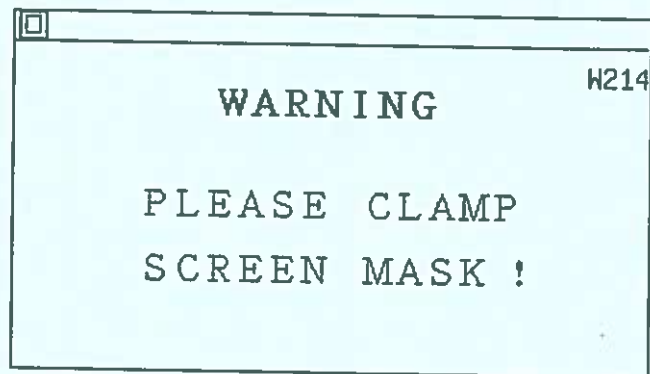
Press **SQUEEGE FRAME UP/DW.** key to move Squeegee Frame down.

When Squeegee Frame lowest point is sensed, Warning Message Window automatically disappears.

3-3 CP-15 Warning Image Window

Explanation of Warning Image Window W214

W214 >



(Explanation) Main-clamp is not clamping Screen on auto-running.

(Countermeasure)

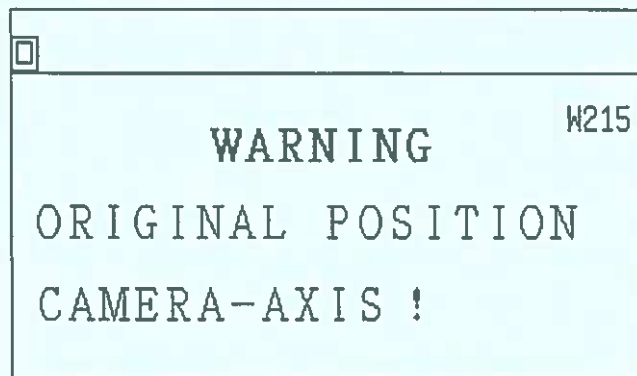
Turn on Main-clamp switch at the front.

Warning Message Window automatically disappears when Main-clamp is done.

3 - 3 CP-1 5 Warning Image Window

Explanation of Warning Image Window W 2 1 5

W 2 1 5 >



(Explanation) Camera axis doesn't return to the original position.

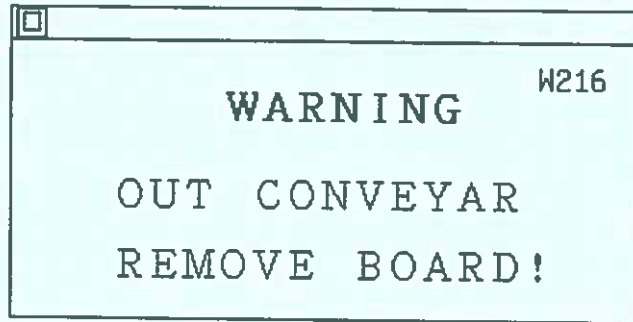
(Countermeasure) Press jog key to return Camera axis to the original point.

Warning Message Window automatically disappears after the return of Camera axis is done.

3 - 3 CP-15 Warning Image Window

Explanation of Warning Image Window W216

W216 >



(Explanation) A PCB is on Carry-out Conveyor.

(Countermeasure)

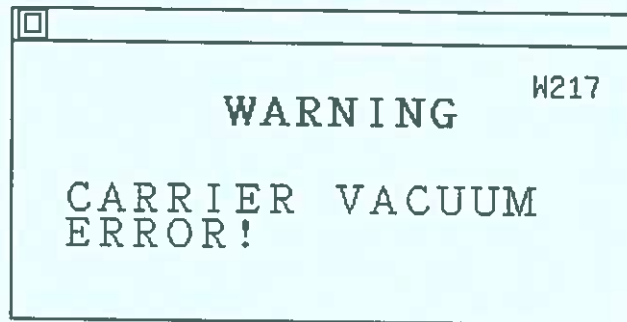
Take a PCB away from Carry-out Conveyor.

Warning Message Window automatically disappears after a PCB removed.

3 - 3 CP-15 Warning Image Window

Explanation of Warning Image Window W217

W217 >



(Explanation) Carrier Vacuum pressure is too low to print on auto-running.
Carrier moves at low speed on this warning.

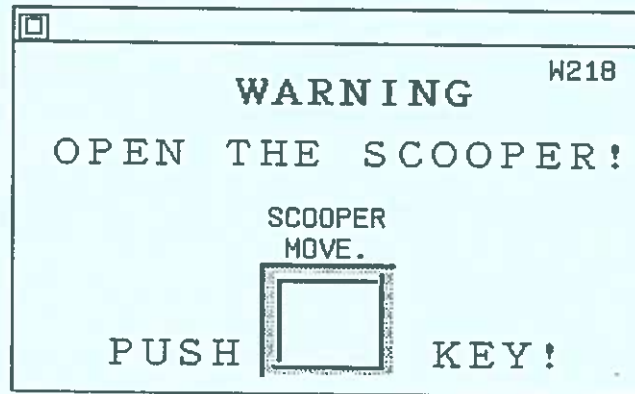
(Countermeasure)

Warning Message Window automatically disappears after a PCB
is carried out.

3 - 3 CP-15 Warning Image Window

Explanation of Warning Image Window W 2 1 8

W 2 1 8 >



(Explanation) Scooper is closed (scoop up) on squeegee on Manual.

(Countermeasure)

Press the key to open Scooper (scoop down).

Warning Message Window automatically disappears after scooper is open(down).

Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 PLC program (functions)

PLC program is explained next.

PLC program can be seen on Touch Panel.

When PLC program image is on, the images on Manual or Auto-running is not shown.

It's recognizable how CP-15 is working at the moment on PLC program image.

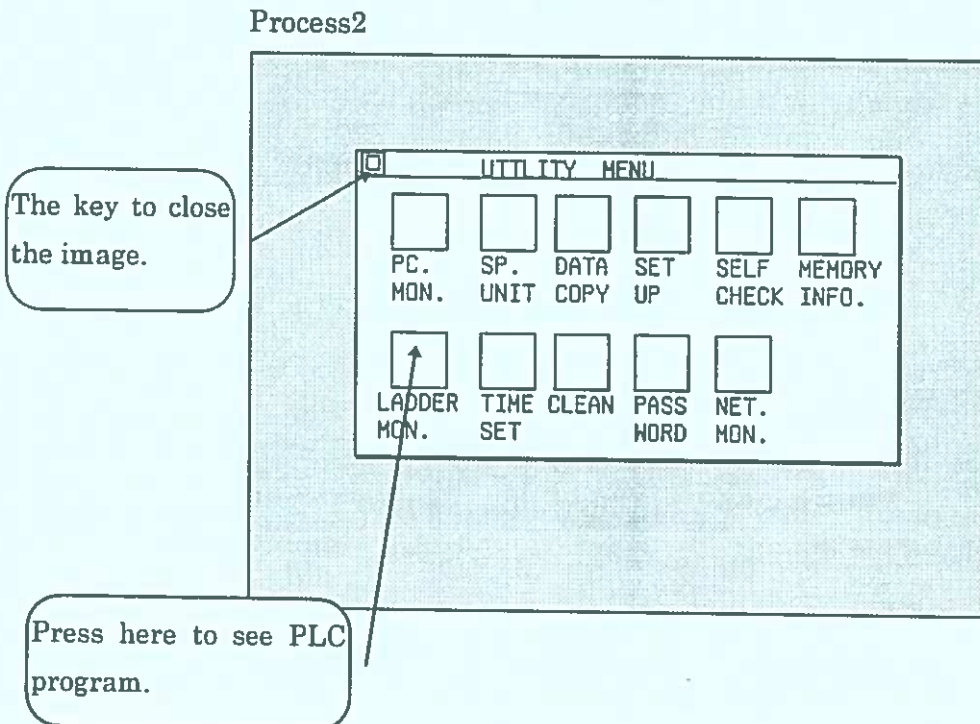
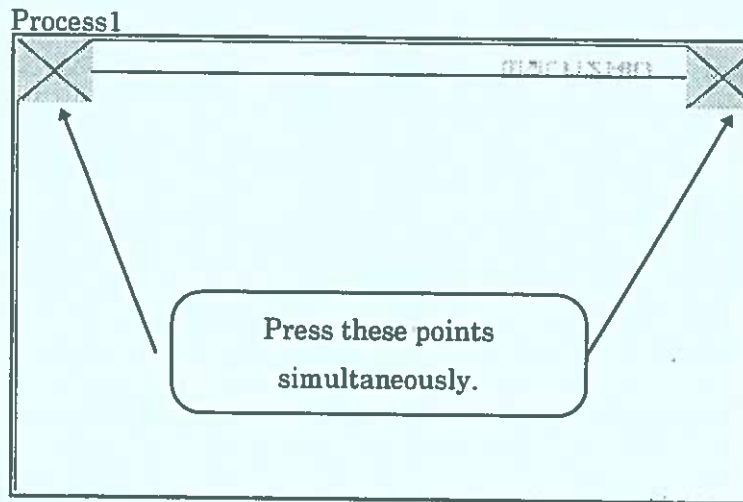
PLC program can't be changed on this image because this is only for reading.

The procedure to read PLC program is explained next.

Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 PLC program (reading)

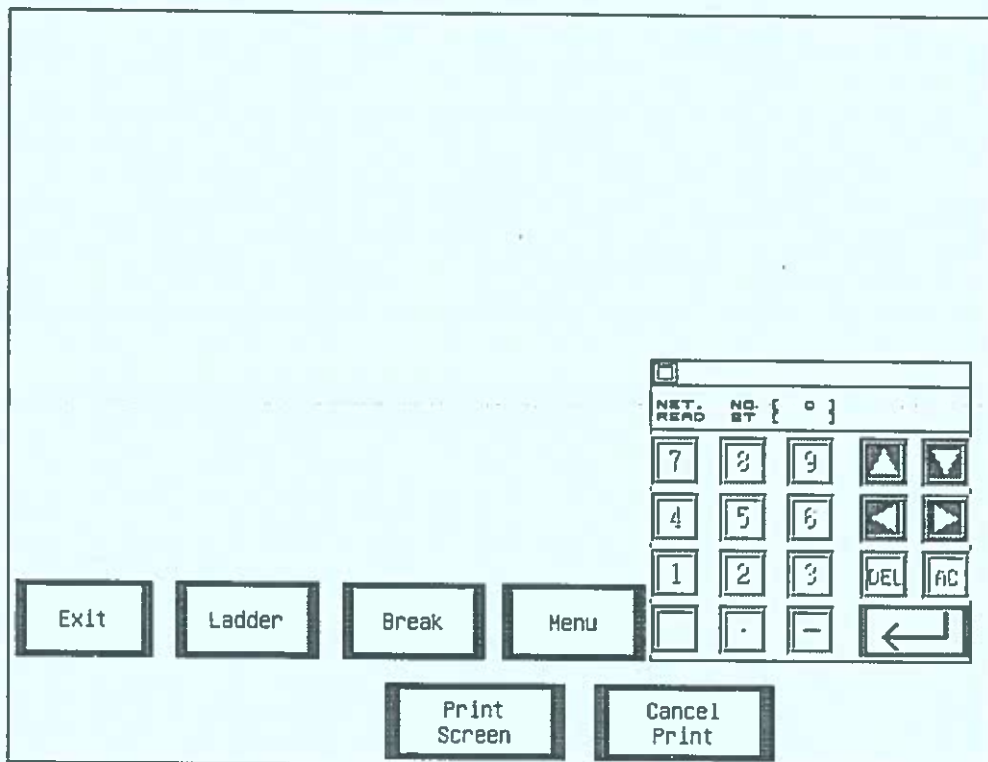
The procedure to read PLC program is explained next.



3 - 3 CP-15 PLC program (reading)

The procedure to read PLC program is explained next.

Process3



↓
NET NO. [0] blinks on Ten Key Overlap Window.

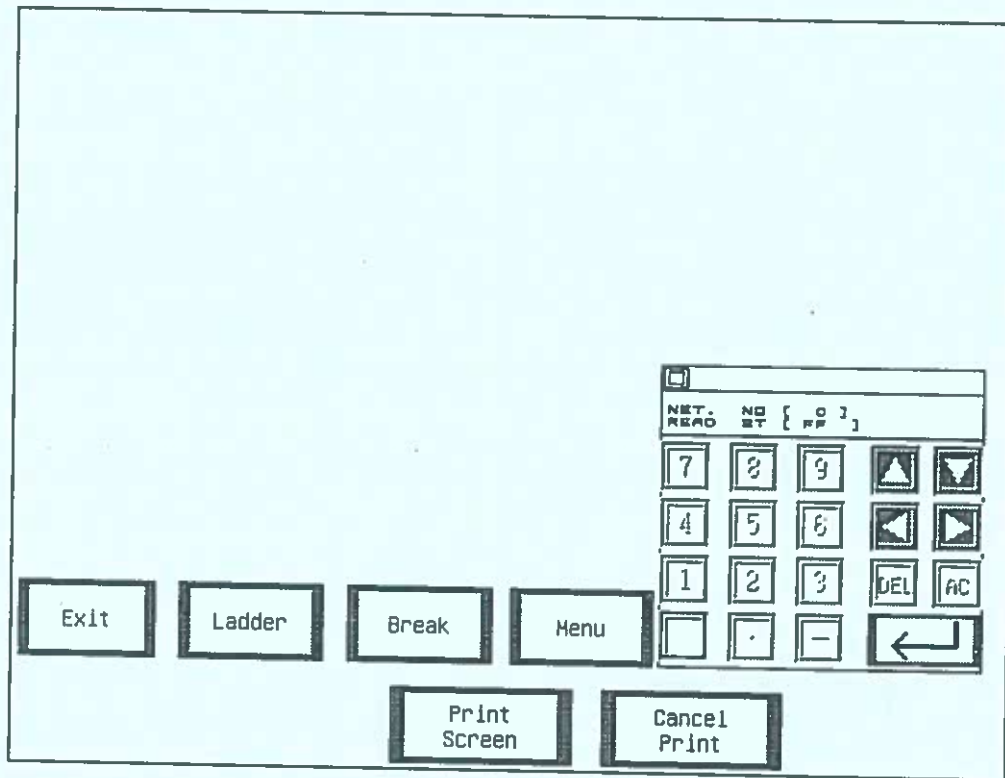
↓
Press  key.

↓
NET. NO [0] is chosen.

3 - 3 CP-15 PLC program (reading)

The procedure to read PLC program is explained next.

Process4



↓
NET NO. [FF] blinks on Ten Key Overlap Window.

↓
Press  key

↓
NET. NO [FF] is chosen.

3 - 3 CP-15 PLC program (reading)

The procedure to read PLC program is explained next.

Process5

<table border="1"><tr><td colspan="2">READ STATE</td></tr><tr><td>PARAM.</td><td></td></tr><tr><td>PROG.</td><td></td></tr><tr><td>CMNT</td><td></td></tr><tr><td>EX..CMNT..</td><td></td></tr><tr><td>NETWORK NO.</td><td>0</td></tr><tr><td>PC NO.</td><td>FF</td></tr></table>	READ STATE		PARAM.		PROG.		CMNT		EX..CMNT..		NETWORK NO.	0	PC NO.	FF	<table border="1"><tr><td colspan="2">READ SELECTION</td></tr><tr><td>READ PROGRAM</td><td>COMMENT</td></tr><tr><td>MAIN PROGRAM</td><td>SETTING</td></tr><tr><td>SUB PROGRAM</td><td>NON SETTING</td></tr><tr><td>SUB PROGRAM 1</td><td></td></tr><tr><td>SUB PROGRAM 2 (A4U)</td><td></td></tr><tr><td>SUB PROGRAM 3 (A4U)</td><td></td></tr></table>	READ SELECTION		READ PROGRAM	COMMENT	MAIN PROGRAM	SETTING	SUB PROGRAM	NON SETTING	SUB PROGRAM 1		SUB PROGRAM 2 (A4U)		SUB PROGRAM 3 (A4U)	
READ STATE																													
PARAM.																													
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EX..CMNT..																													
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PC NO.	FF																												
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READ PROGRAM	COMMENT																												
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SUB PROGRAM 2 (A4U)																													
SUB PROGRAM 3 (A4U)																													
<table border="1"><tr><td>Exit</td><td>Ladder</td><td>Break</td><td>Menu</td><td>↑</td><td>↓</td><td>←</td><td>→</td><td>↶</td></tr></table>		Exit	Ladder	Break	Menu	↑	↓	←	→	↶																			
Exit	Ladder	Break	Menu	↑	↓	←	→	↶																					

↓
press

↶

 key when the image above is on.

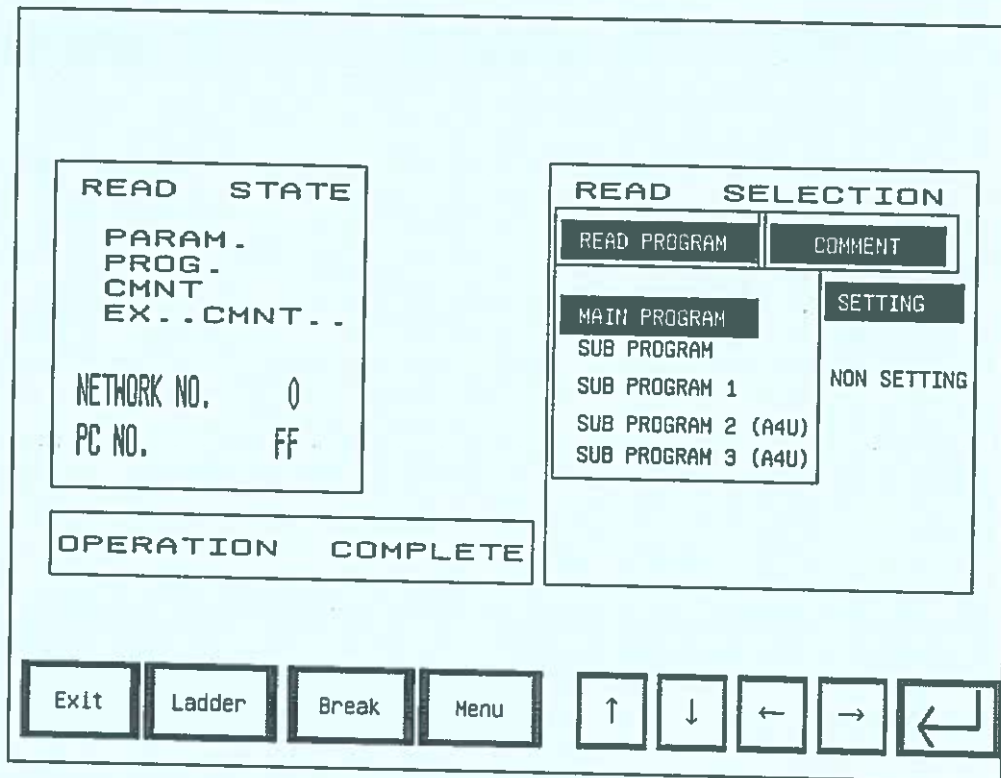
↓
PLC program begins to be read.

↓

3 - 3 CP-15 PLC program (reading)

The procedure to read PLC program is explained next.

Process6



↓
(OPERATION COMPLETE) gets to be shown.

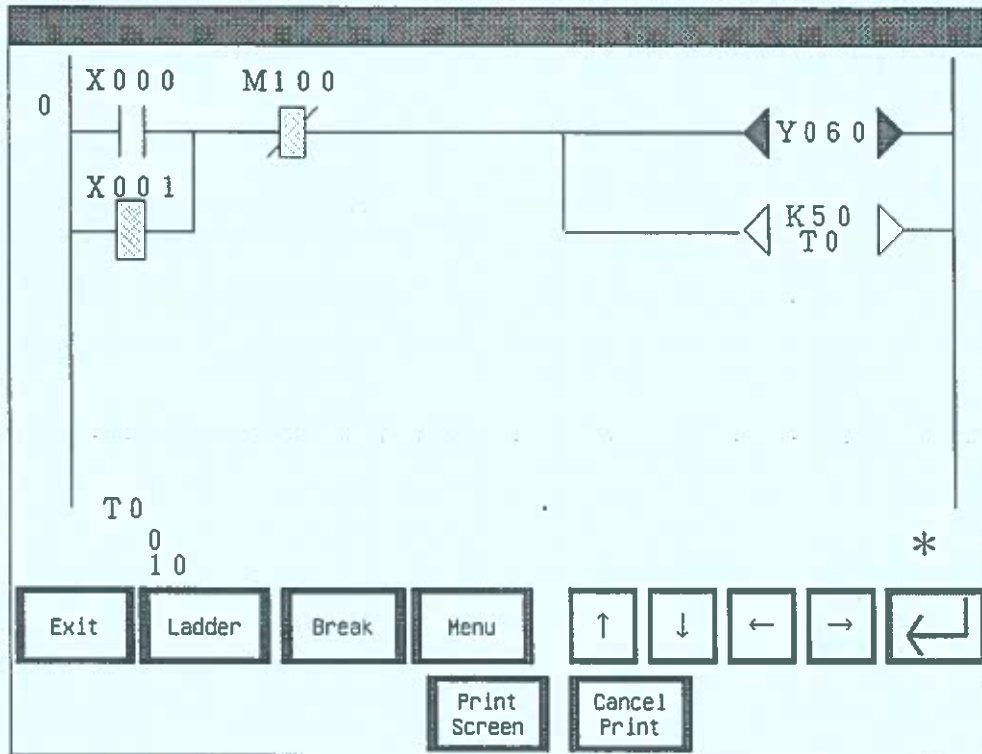
It takes some time to complete reading.

↓
Press **LADDER** key after reading is completed.

3 - 3 CP-15 PLC program (reading)

The procedure to read PLC program is explained next.

Process7



↓
PLC program image gets to be shown on Touch Panel.

↓
Press **MONI.** key.

fn.

1 : Asterisk ***** blinks on the right of the image on monitoring.

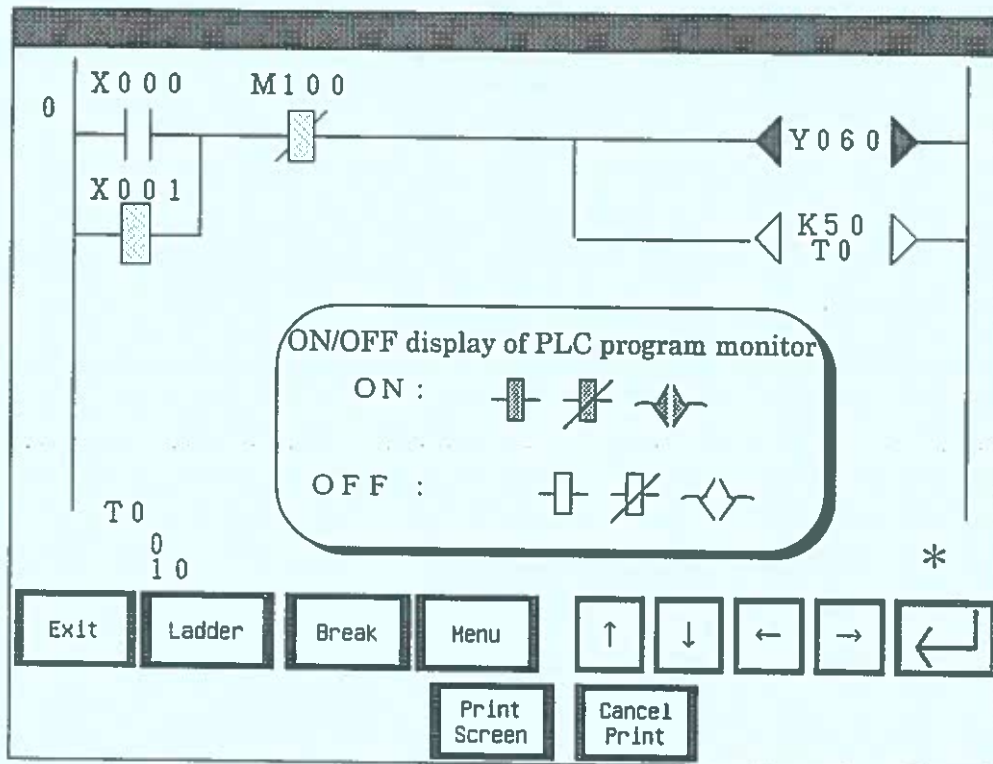
2 : PLC program above is different from CP-15 program.

Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 PLC program (operation key)

Operation keys of PLC program is explained next.

Example >



Key Functions

Exit	PLC program image ends. The former image gets back.
PCRD	PLC program begins to be read.
Mon.	PLC program begins to be monitored. (*blinks)
Menu	Devices, Coil etc. in program are sought.
↑ ↓	One circuit of program can be scrawled.
↩	Next program is read.
Print Screen /Cancel Print	These are not used at the moment.

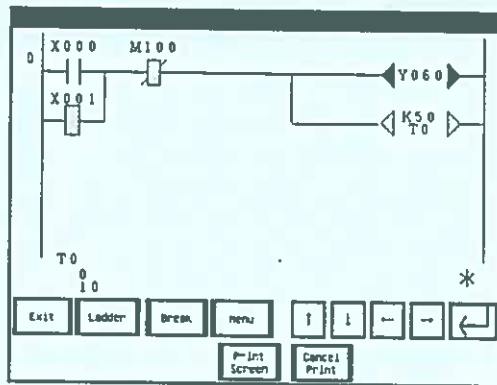


Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 PLC program (How to operate coil search)

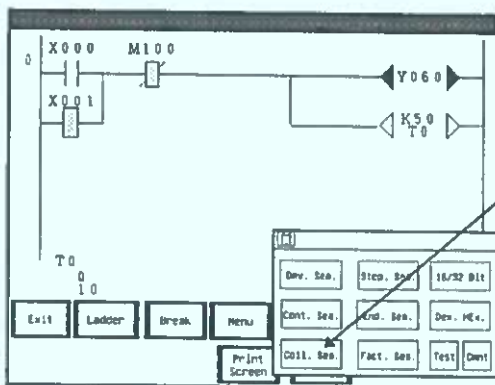
The procedure of Coil Search is explained next.

Process1 >



Press **MENU** key.

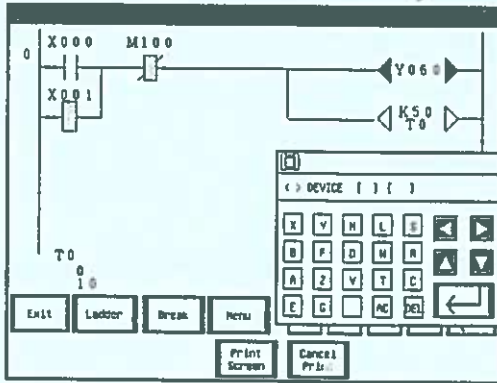
Process2 >



Press **Coil Sea** key.

3 - 3 CP-15 PLC program (How to operate coil search)

Process 3 >



ex.> Seek No.Y080 by Coil Search.

Press **Y** key.

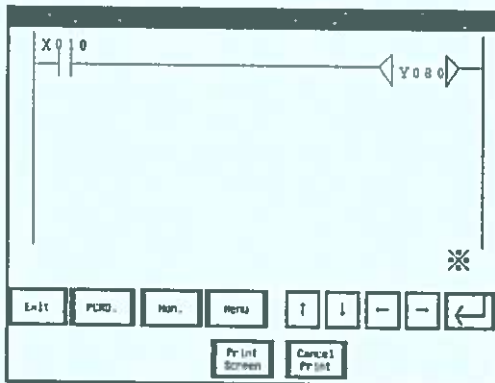
Press **←** key.

Press **8** **0**.

Display <> DEVICE [**Y**] [**80**]

Press **←** key.

Process 4 >



The result of Y080 Coil Search is shown.

Point

The procedure above is only an example, so M... and D... can be sought in the same way.

Press **Cont Sea.** key to search Input Signal in Process 2.

Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 PLC program Check the signal In / Output (X,Y)

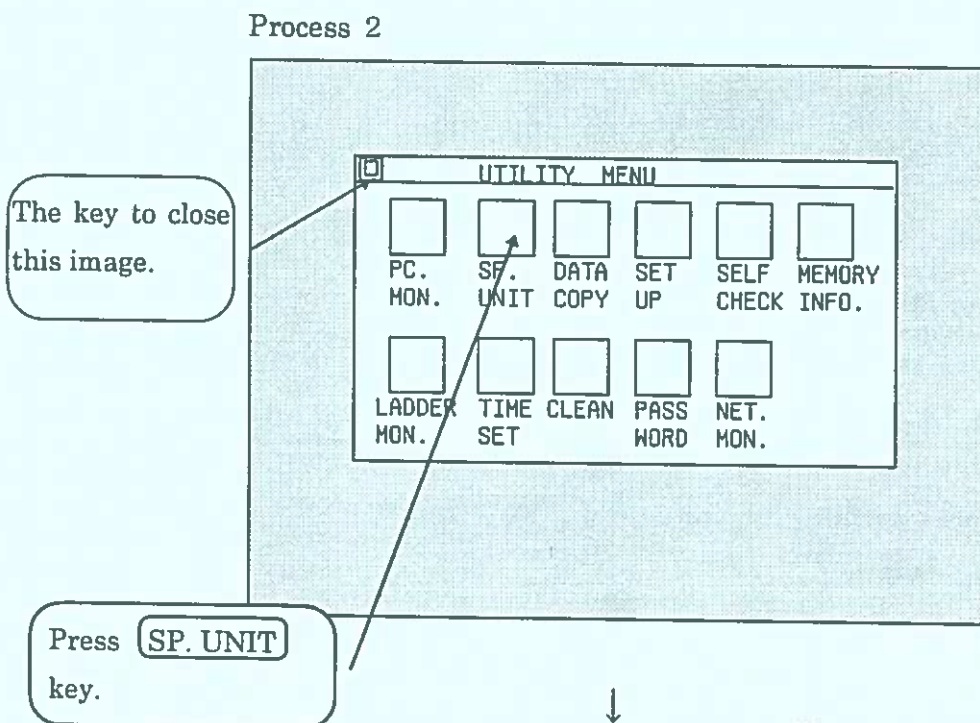
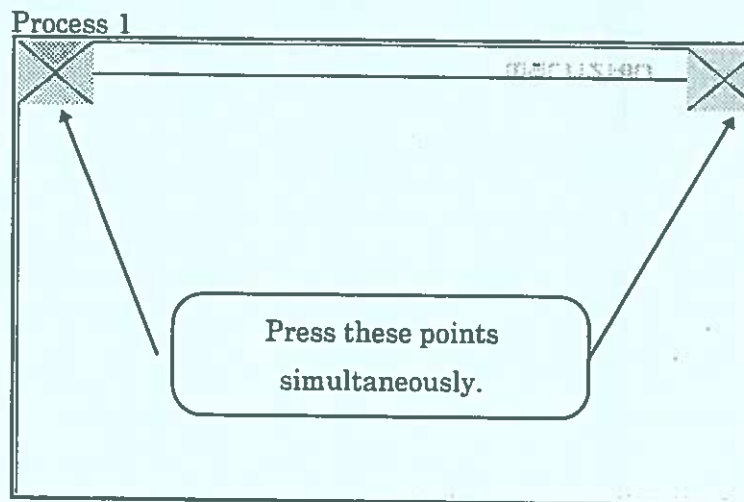
The image to check Input Signal is explained next.

This function makes both X input and Y output checked.

Chapter 3 How to deal with errors and maintenance

3 - 3 CP-15 PLC program Check the signal In / Output (X,Y)

The procedure of In and Out-put Signal Check is explained next.



3 - 3 CP-15 PLC program Check the signal In / Output (X,Y)

The procedure of In and Out-put Signal Check is explained next.

Process 3 Special Unit (SP. UNIT) image shows up.

System Configuration								NET	END
								PCNo	
CPU	IN	IN	OUT	OUT	A1SD75	A1SD75	A1SD75	A1SD75	
	X 0	X 4 0	Y 8 0	Y C 0					

Press here to close the image.



ex. > Input Signal of X030

System Configuration								NET	END
								PCNo	
CPU		IN	OUT	OUT	A1SD75	A1SD75	A1SD75	A1SD75	
		X 4 0	Y 8 0	Y C 0					

Press here.



3 - 3 CP-15 PLC program Check the signal In / Output (X,Y)

The procedure of check In and Output Signal X0 to X30 is explained next.

Process 4 In and Out-put Signal image is shown.

X MODULE				Sys. Conf.	END
X					
00	<input type="radio"/>	10	<input type="radio"/>	20	<input type="radio"/>
01	<input type="radio"/>	11	<input type="radio"/>	21	<input type="radio"/>
02	<input type="radio"/>	12	<input type="radio"/>	22	<input type="radio"/>
03	<input type="radio"/>	13	<input type="radio"/>	23	<input type="radio"/>
04	<input type="radio"/>	14	<input type="radio"/>	24	<input type="radio"/>
05	<input type="radio"/>	15	<input type="radio"/>	25	<input type="radio"/>
06	<input type="radio"/>	16	<input type="radio"/>	26	<input type="radio"/>
07	<input type="radio"/>	17	<input type="radio"/>	27	<input type="radio"/>
08	<input type="radio"/>	18	<input type="radio"/>	28	<input type="radio"/>
09	<input type="radio"/>	19	<input type="radio"/>	29	<input type="radio"/>
0A	<input type="radio"/>	1A	<input type="radio"/>	2A	<input type="radio"/>
0B	<input type="radio"/>	1B	<input type="radio"/>	2B	<input type="radio"/>
0C	<input type="radio"/>	1C	<input type="radio"/>	2C	<input type="radio"/>
0D	<input type="radio"/>	1D	<input type="radio"/>	2D	<input type="radio"/>
0E	<input type="radio"/>	1E	<input type="radio"/>	2E	<input type="radio"/>
0F	<input type="radio"/>	1F	<input type="radio"/>	2F	<input type="radio"/>
				30	<input checked="" type="radio"/>
				31	<input type="radio"/>
				32	<input type="radio"/>
				33	<input type="radio"/>
				34	<input type="radio"/>
				35	<input type="radio"/>
				36	<input type="radio"/>
				37	<input type="radio"/>
				38	<input type="radio"/>
				39	<input type="radio"/>
				3A	<input type="radio"/>
				3B	<input type="radio"/>
				3C	<input type="radio"/>
				3D	<input type="radio"/>
				3E	<input type="radio"/>
				3F	<input type="radio"/>

Press here to close the image

In and Out-put Signal check

- ON
- OFF

It's recognizable with

Press **END** key after checking In and Out-put Signal.

The image goes back to Utility image.

3-4 Check-out items

- Purpose of stated check-out
 - To keep CP-15 well-conditioned and drive it effectively.
 - To find a trouble at the early stage.

- Types of stated check-out
 - Daily check-out
 - Weekly check-out
 - Monthly check-out

fn.

Turn off CP-15 to check the inside and the driving parts.
The air circuit drawing is at the end of Ch.3 § 4

1. Daily Check-out

Review

1) Air Pressure ✓

•checking point

Check the pressure of regulator (Main pressure) indicated on the drawing 1.
The appropriate air pressure is 5kgf/c m² (0.5MPa)

•adjustment

Pull down Pressure Adjuster and turn it around to correct air pressure.
Push up Pressure Adjuster to lock.

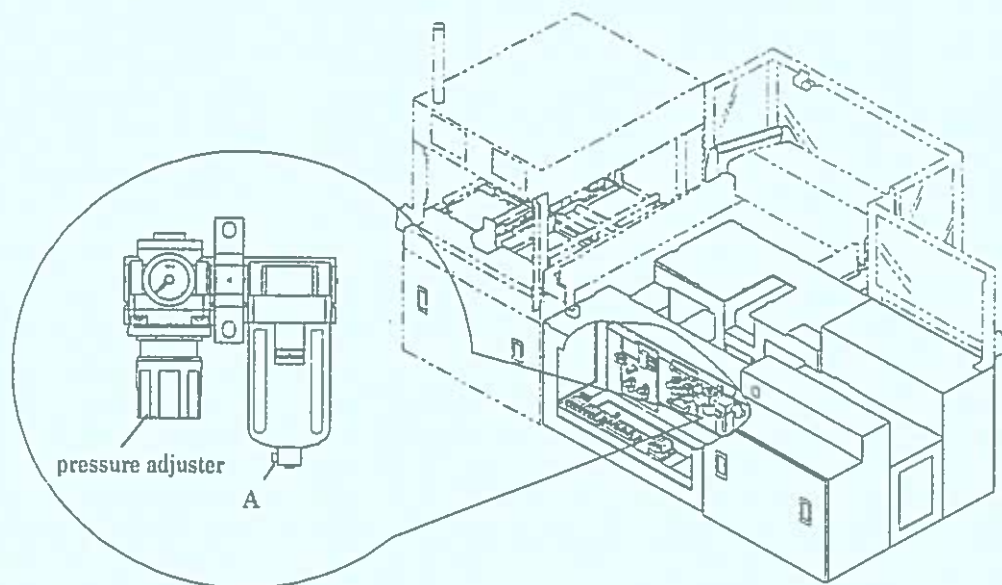
2) Air Filter ✓

•checking point

Check if water is pooled in Air Filter.

•adjustment

Push the button A (Drawing 1) to take out water.



drawing1 Air supply ✓

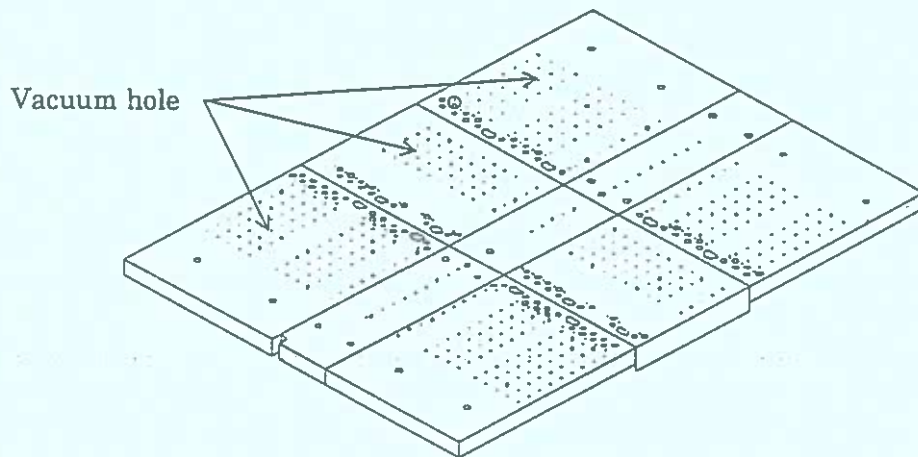
3) Printing Table, table-part of Carrier ✓

•checking point

Check if Printing Table and the table-part of Carrier are stained with ink.

•adjustment

Take away stained ink. Use Vacuum Reverse function (For more details, refer to Ch.2 § 2 M18-5 AIR CYLINDER.



drawing2 Printing Carrier Table

fn.

Stained ink could pop up with Vacuum Reverse function.

4) Cleaning of the interior ✓

•checking point

Take away dust or ink with care to circuit wires and circuit pipes.

fn.

Letting ink stain long could lead to rust, worse movement or worse precision.

2. Weekly Check-out

1) circuit lines, circuit pipes

① Check circuit lines with care

- damage on cords?
- connectors off?

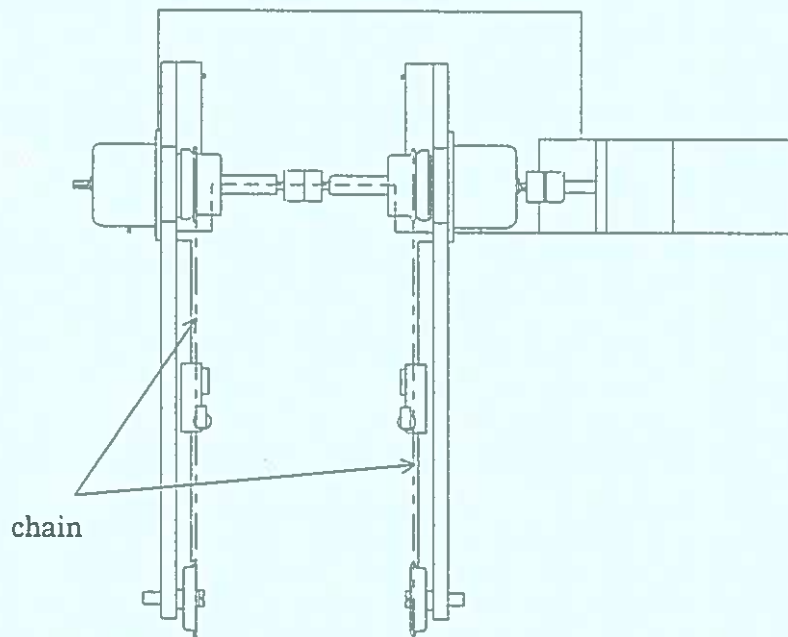
② Check circuit pipes with care

- damage on air hoses?
- air hoses off?
- Air leaking from air cylinder rods.

3) Pouring oil to Alignment Section

- Pour oil drawn below.

Rear Siding chain-part (refer to drawing3)



drawing 3 Rear Siding

fn.

Keep Conveyor Belts from being stained with oil and the like to stay PCB clean.

4) Check how the state of smeared grease is.

- Smear new grease after removing the remaining one if the grease is running or dirty.

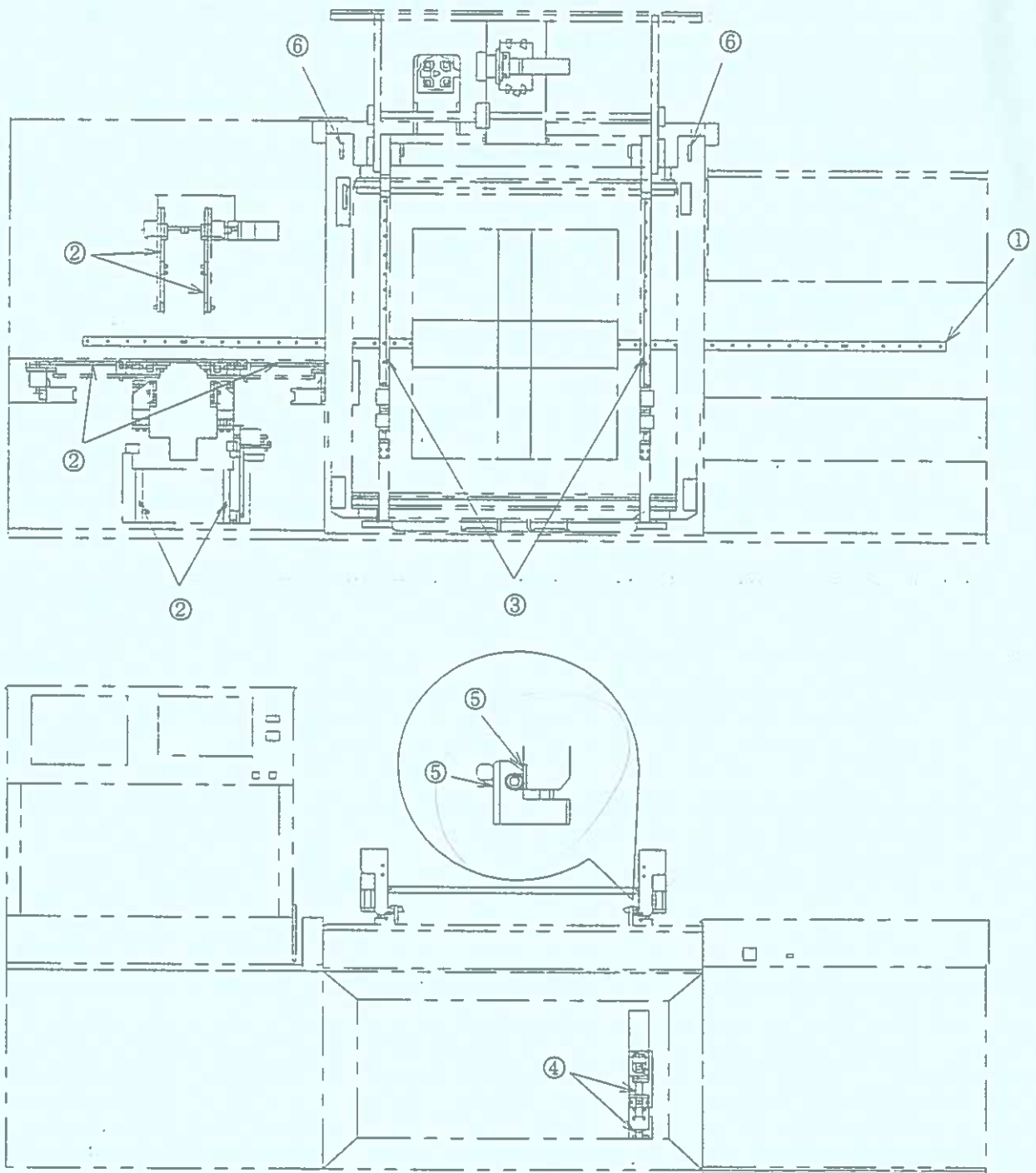
fn.

Use lithium soap thickener grease (extreme pressure).

- ① Carrier Sliding unit (refer to Drawing 4 overview)
- ② Sliding Sliding unit (refer to Drawing 4 overview)
- ③ Squeegee Sliding unit (refer to Drawing 4 overview)
- ④ Off-Contact Sliding unit, Ball Screws (refer to Drawing 4 overview)
- ⑤ Screen Frame unit, Squeegee Frame unit, Cam Followers (refer to Drawing 4 overview)
- ⑥ Screen Frame unit, Sliding unit (refer to Drawing 4 overview)

fn.

In case there is no nipple or it's impossible to pour grease, smear grease widely on Sliding unit or Ball screws. Check the other gears not described above. Covers are the only parts to take off when grease is smeared or oil is poured. (②-3)



Drawing 4 overview

2. Monthly Check-out

1) Check the state of belts

· Check if there are any tears or extensions on belts described below.

① Squeegee belt (refer to Drawing 5 overview)

② Carry-in Conveyor belt (refer to Drawing 5 overview)

③ Carry-out Conveyor belt (refer to Drawing 5 overview)

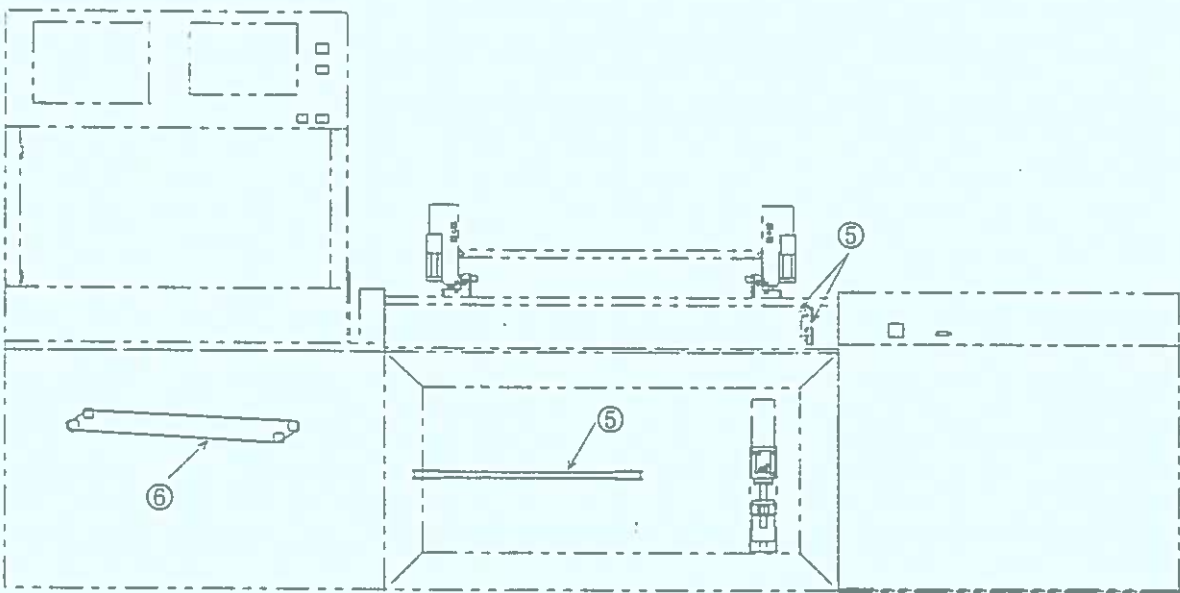
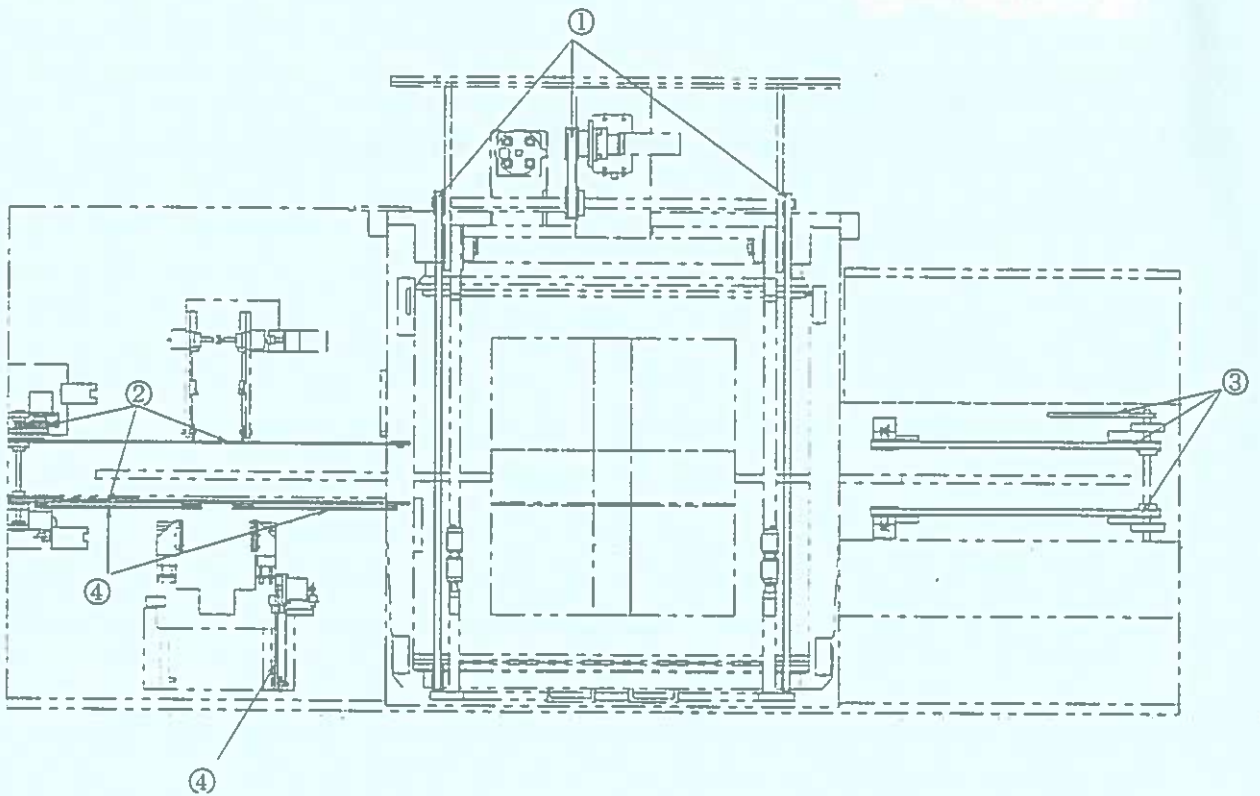
④ Siding unit belt (refer to Drawing 5 overview)

⑤ Screen Gap unit belt (refer to Drawing 5 overview)

⑥ Board Clamp belt (refer to Drawing 5 overview)

fn.

Check the other belts.



Drawing 5 overview

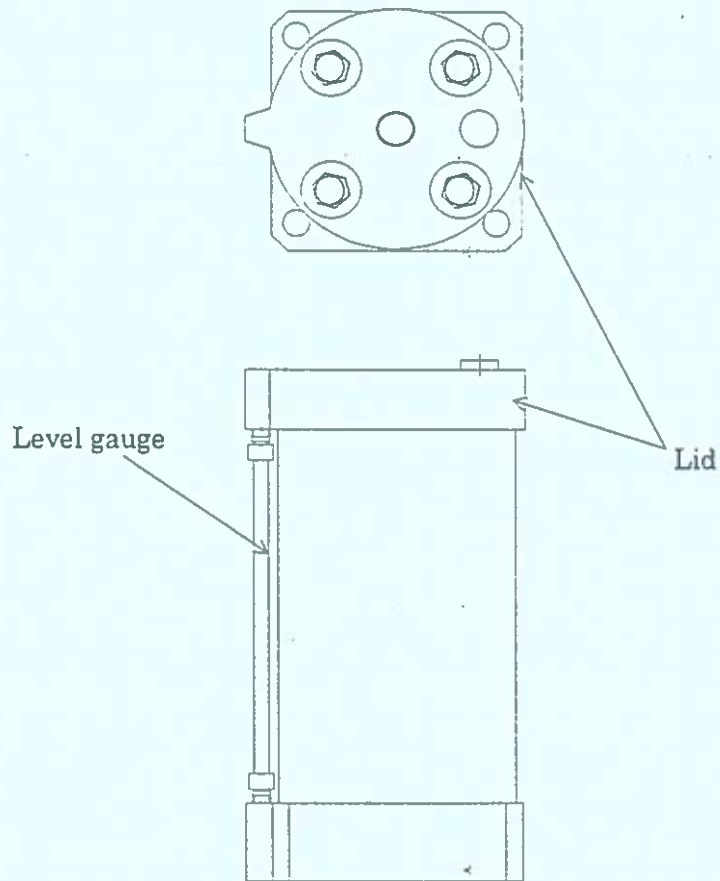
5) Air-Hydro Converter oil

- checking point

Check the remaining oil of Air-Hydro Converter for Squeegee up/down.

- adjustment

Take off the lid and add ISO VG32 turbine oil to the upper level of the level gauge if it is short of oil. (refer to drawing 6 Air-Hydro Converter)



drawing 6 Air-Hydro Converter