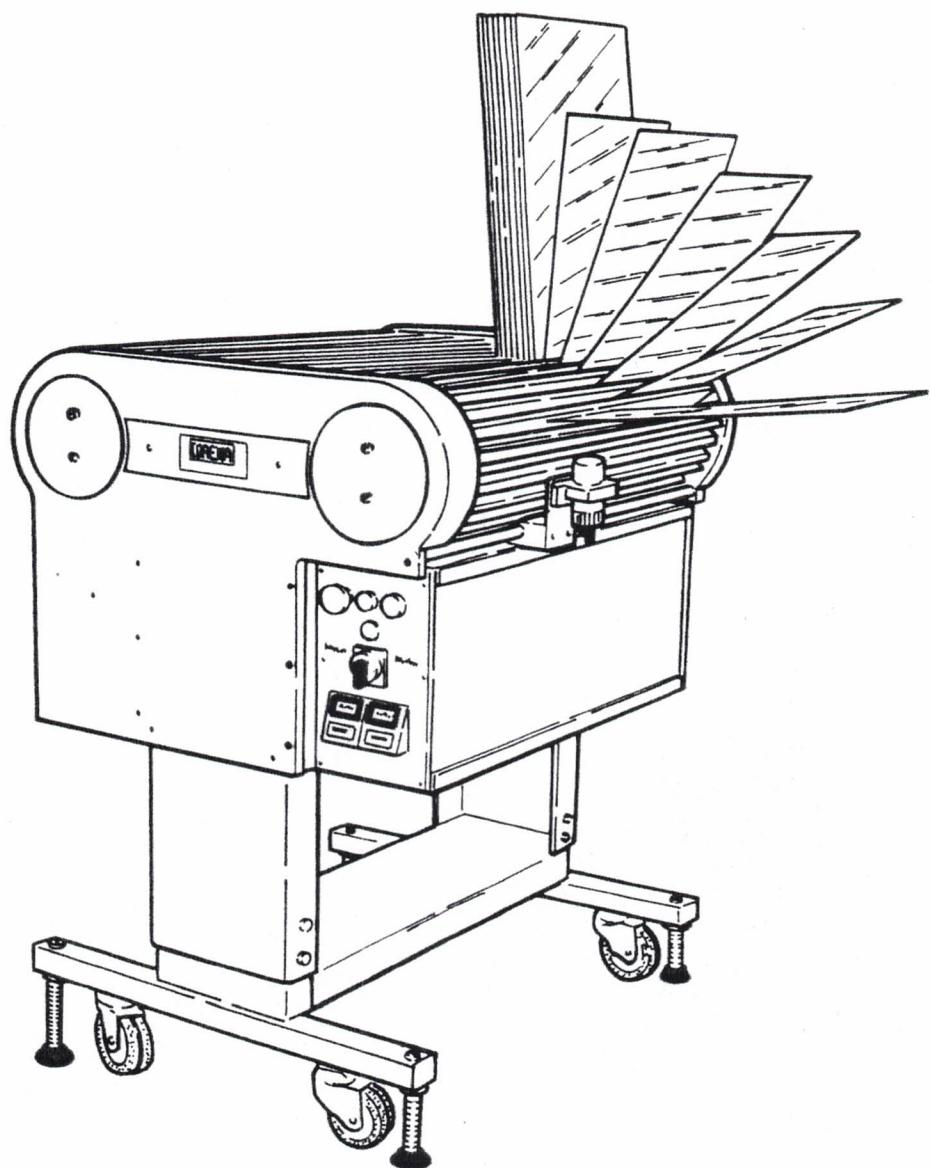


TAPIMATIC



TCMD

IDENTITE DE LA MACHINE		DATE :	févr-06
TAPIMATIC			
TYPE	CD50 / TR 24"		
NUMERO DE SERIE	T060301CH		
DIMENSIONS	LONGUEUR 890mm LARGEUR 890mm HAUTEUR 915mm		
POIDS	120 Kg		
LARGEUR UTILE	650mm		
MOTO REDUCTEUR	SIREM :R1C225H12B/F		
DETECTEUR	E25C2K MY1		
MINUTERIE	H3CAA		
INDEX DE PAS A PAS	XCMA102		
PIGNON D'ENTRAINEMENT	60 dents 3/8"		
PIGNON MOTEUR	12 dents 3/8"		
TENSION - FREQUENCE	220 V MONO		
SCHEMA ELECTRIQUE	16715 167270		
CLIENT	ALWAPRINT AG		
LIEU	GEDRUCKTE SCHALTUNGEN HERM ALEX WALTENBERGER SILORING 8 CH-5606 DINTIKON		

TCMD 10 RUE PASTEUR 95410 GROSLEY
TEL : 01 34 05 82 36 FAX : 01 34 28 79 90

SUMMARY

GENERAL DESCRIPTION AND TECHNICAL SPECIFICATIONS

MAIN DESCRIPTION

- Chassis
- PVC part
- Castors

INSTALLATION

- a. Setting procedure
- b. Electric connections

STARTING UP

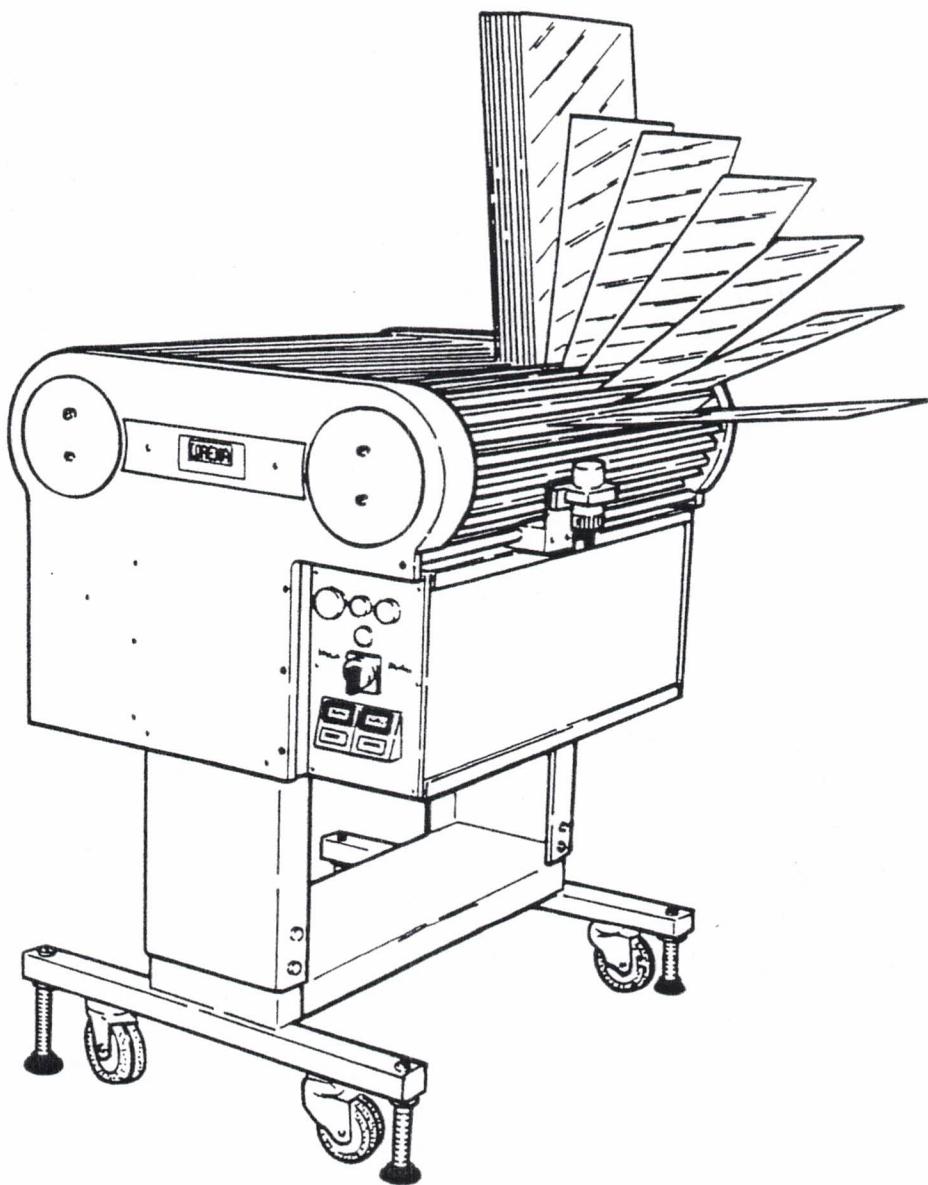
- a. Feeder version
 - V adjustment
 - Timer set up
- b. Collector version
 - V adjustment
 - Timer set up

SPECIAL ADJUSTMENTS

FUNCTIONING DEFECTS

- a. Feeder version
- b. Collection version

MAINTENANCE



GENERAL DESCRIPTION AND TECHNICAL SPECIFICATIONS :

The Tapimatic following its version is used for Loading, or for loading and unloading the pcbs and is available in 610mm "24" and 760mm "30" meanwhile 1016 "40" Tapimatic is delivered on special requests.

Tapimatic C is used as Loader while **Tapimatic CD** as loader/unloader in TR "Transfer" and R." Reversible".

MAIN DESCRIPTION :

The machine constitutes :

A CHASSIS

Black metallic chassis made in two parts as shown in the exploded view :

1. Down part including the footing with height adjustment screws and two metallic bearers (10035 A3) right and left side.
2. Upper black metallic part (10036 A4)called cheeks which is fixed on the down part and allows manual height adjustment of about 300mm (telescopic foot) with the help of height adjustment screws (10083 A3).

B. WHITE PVC PART

It's the main upper part equipped with belt and slats having 4.5mm gap.

C. CASTORS

Most of the Tapimatic are delivered with castors and height adjustment screws (10083 A3).

In option, The Tapimatic can be delivered with bigger castors mounted on the screws (for easy displacement of Tapimatic with pcbs from one machine to the other).

The Tapimatic exists in two versions :

1. **TRANSFER**
Collecting from one side and feeding from other side (change of pcb face)
2. **REVERSIBLE**
Collecting and feeding from the same side.

INSTALLATION :

a. Setting procedure :

Never raise the machine by holding the slats.

The Tapimatic is delivered bolted on a pallett with a pvc film around for protection against transport blows and dust.

Control outside packing and make reserves if necessary.

Install the machine at its working place. The Tapimatic can only be "Feeder" C or "Feeder/Collector" CD .

Security valve (anti-jam device) must always be to the side of the machine to be fed.

Proceed to height adjustment as follows :

The Tapimatic is installed next to the machine to be fed.

Place **PVC adjusting L**(supplied with the machine) on the slats (handle on the slats and the top of this L going down wards on the slats). The Tapimatic will be on the right height when top side of the **PVC L** will stay over the machine to be fed (see drawing n° 11861 A4) and until you don't get this right height adjustment go on setting the height with height adjustment screws

Check machine's horizontality from all sides and block the screws with nuts.

b : Electric connections

Connect to single phase 220 volts.

The Tapimatic is ready to run.

Important note :

The conveyors of the machine to be fed must be enough long so that bigger size pcbs be placed otherwise **additional conveyor TAP CVV** sold in option must be planned.

STARTING UP :

Just check Control board position. It can be fixed either to the right or to the left side passing whole control board plate from inside to the side wanted .

Select Feeder or Loader mode (3 position commutator on control panel) The timer is operational if time is in seconds and the work mode on 1 (see timer notice).

IN COLLECTOR MODE :

The Tapimatic has been positioned as described here above.

The pcb detector must be between the Tapimatic and the machine to be fed.

Check that pcb detector is about 10mm down to the pcb passage.

Check position of the V created by two pvc slats (the gap between two slats making the form of V is called V). The pcb must enter into the V while down slat is completely horizontal so that the pcb pick up takes place on full angle (18°).

Adjustment of V position :

V position can be changed adjusting contact position in front of the coder cog wheel (10057 A4)

Loosen blocking screw (10061 A4) and turn slightly the contact support (11702) in a way to shift the wheel of micro contact from coder cog wheel notch.

Check inferior slat of the V and start again if necessary.

COLLECTOR MODE TIMER SET UP

This timer assures rise control. It must only allow passing distance between detector and V depth. This time delay can slightly be increased to let askew pcb get aligned in the V before rising (if needed set timer on 0.1 seconds instead of 1 second to be more precise).

IN FEEDER MODE :

The security valve (anti-jam device) must always be to the side of the machine to be fed. Be carefull that the Tapimatic is not too near to the machine to be fed otherwise the security valve will not be able to operate. Once the Tapimatic aligned heightwise, place 3 position commutator on **Feeder** mode. Control that feeder is well in working mode **A** and timing in seconds. Press on any time say **20 seconds** and start the cycle pressing on START switch. The count down begins and activates the indexation motor when its on zero. The belt moves a bit and the pcb is taken by the conveyors of the machine to be fed. Note the time so that first pcb be at the needed distance for putting the second one on and for that increase the time (check timer notice). The right time selection comes quickly with a little bit experience and this time selection depends on the speed of the conveyor and on the pcb length.

V ADJUSTMENT

V does not need to be refined for medium or short pcbs. In some cases when pcbs are long and heavy, one must be sure that the second pcb does not touch the one which is on the feed conveyor. This may occur if the pcb is slightly flexible (less than 1.6 or long and narrow) so control **V** position and adjust (as explained for collector mode) in a way that the angle between the flow direction and following slat be the maximum say maximum 18° .

SPECIAL ADJUSTMENTS :

FOR SLANTWISE ENTRY

It may be needed that the pcbs enter slantwise in the machine to be fed. It's possible and for this just need to put the Tapimatic higher from one side (adjust with adjusting wheels and block).

FOR FEEDING NOT TOO FINE PCB'S : double or multiple indexation

In this case one interior timer is added for allowing to index one, two or more angles. This subterfuge is used when pcbs are more flexible than rigid ones but are not too fine. This double or multiple indexation helps to avoid purchase of a **CDS** (Tapimatic for flexible pcbs).

ADDITIONAL CONVEYOR TAP CVV :

This conveyor, needed either in entry or in exit, is to be fixed at the place of the round mouldings which are to be taken away. The conveyor speed which is variable and adjustable can be adjusted by means of a potentiometer situated on the Tapimatic control board.

FUNCTIONING DEFECTS :

a. FEEDER VERSION

After power on and "start" the green indicator remains off :

Check :

Emergency control switch (may be is clicked)
Security control board (may be blocked).

The indicator is on but belt does not work :

Check :

Commutator position : It must be on "Feeder".

The timer "feeder" is not in working mode " A " or the time selection is on " hours ". control and correct.

The first pcb leaves and second one falls over :

Check :

Time selection printed on the timer which must be in **Seconds**,following conveyor speed and the pcbs length ,make it a bit longer.

Indexation contact is loose (10061 A4). Tighten it and put it at the right position.

The break of the motor which may be defective so needs to be changed.

The pcb comes on the conveyor to be fed but does not leave from the V :

Check :

The Tapimatic height using height adjustment screws.

Front and back side level : The pcb is touching just the one roller of the machine. V bottom side is too high so the grip is too feeble for taking out the pcb.

b. COLLECTOR VERSION :

The pcb enters in the V but the belt does not rise :

Check :

The commutator position and it must be on COLLECTOR

The pcb does not rise :

Check :

The timer function it must be in mode " A " and time selection in " seconds ".

The pcb still does not rise :

Check :

The detector. The count down must start as the pcb comes over vertically if still there is not count down then check the OMRON detector with one finger.

Obturate the detector and control that the red led is lighted (cord side). If still there is no light then control the connections and change if needed.

The led is on so the detector is operational but does not detect after a while :

Check :

Its detection height. If the distance is too big, modify the sensibility (consult the notice and use the screw delivered with the machine) The right sensibility is the one which will detect the pcb at 15mm distance from the detector and in detector axis. Adjust the height at 15mm and let the pcb enter.

NOTE : too high sensibility may lead to two defects :

Continuous detection of machine's element (roller, or any corner).

OR previously lifted pcb leading to continuous rotational movement.

ADDITIONAL CONVEYOR TAP CVV :

The conveyor does not work after power on :

Check :

Potentiometer position and set far from zero.

The motor does not run :

Check :

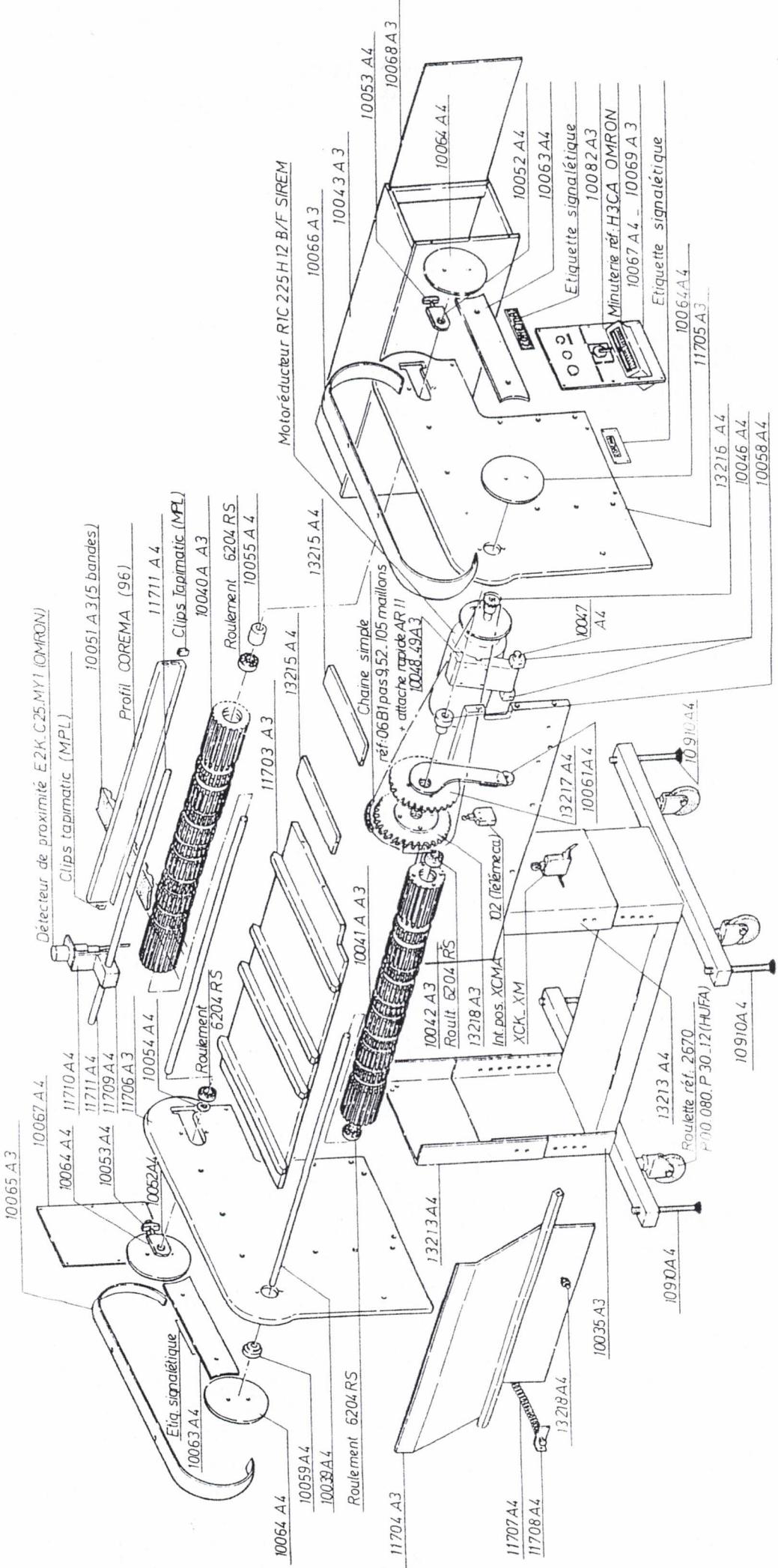
Power supply at motor infeed : 24 volts CC.

Carbon brushes if there is voltage in terminal

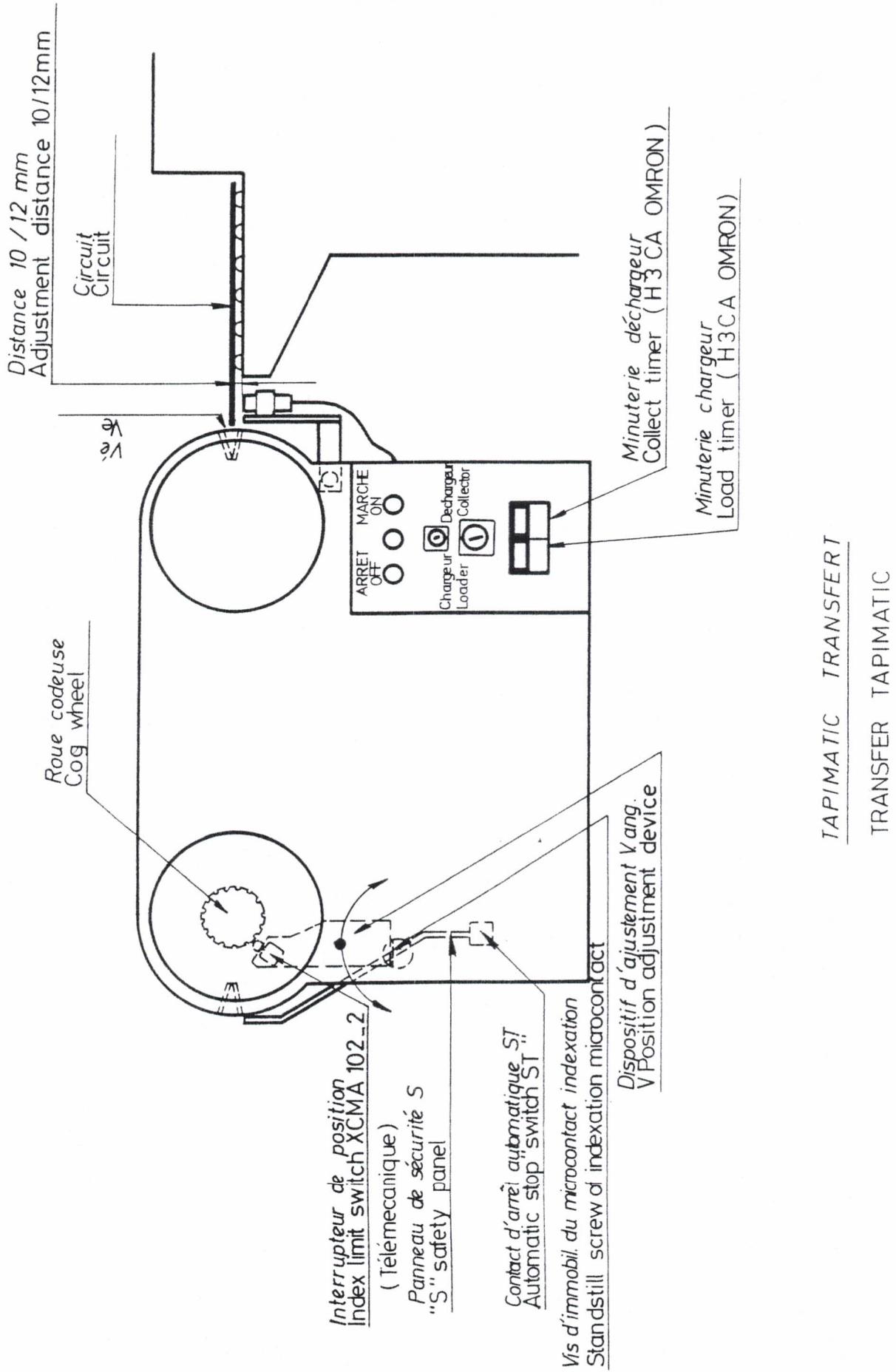
Voltage at speed control board infeed and if there is,control the fuses.

MAINTENANCE :

There is no special maintenance except changing from time to time the motor brushes of indexation.



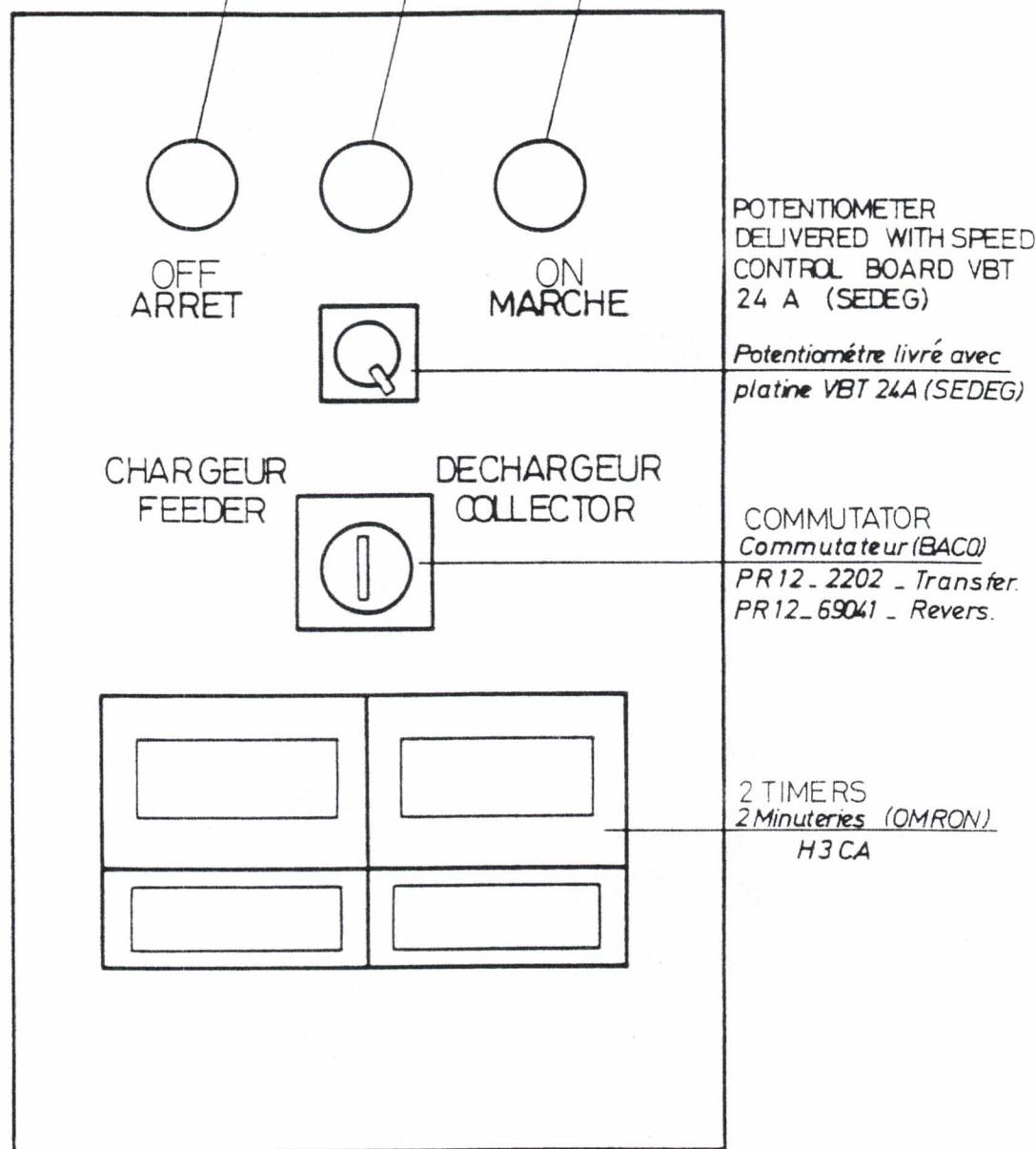
Indice	Modifications	Matière :
B	MISE A JOUR	25.II.93
A	MISE A JOUR	1-7-92
Date	9.1.1991	Date
Dessiné:	<i>Eh</i>	TAPIMATIC CD 50
Vérifié:		Quantité :
Date		Traitement:



V22 ED 01 + 231E01 (BACO)

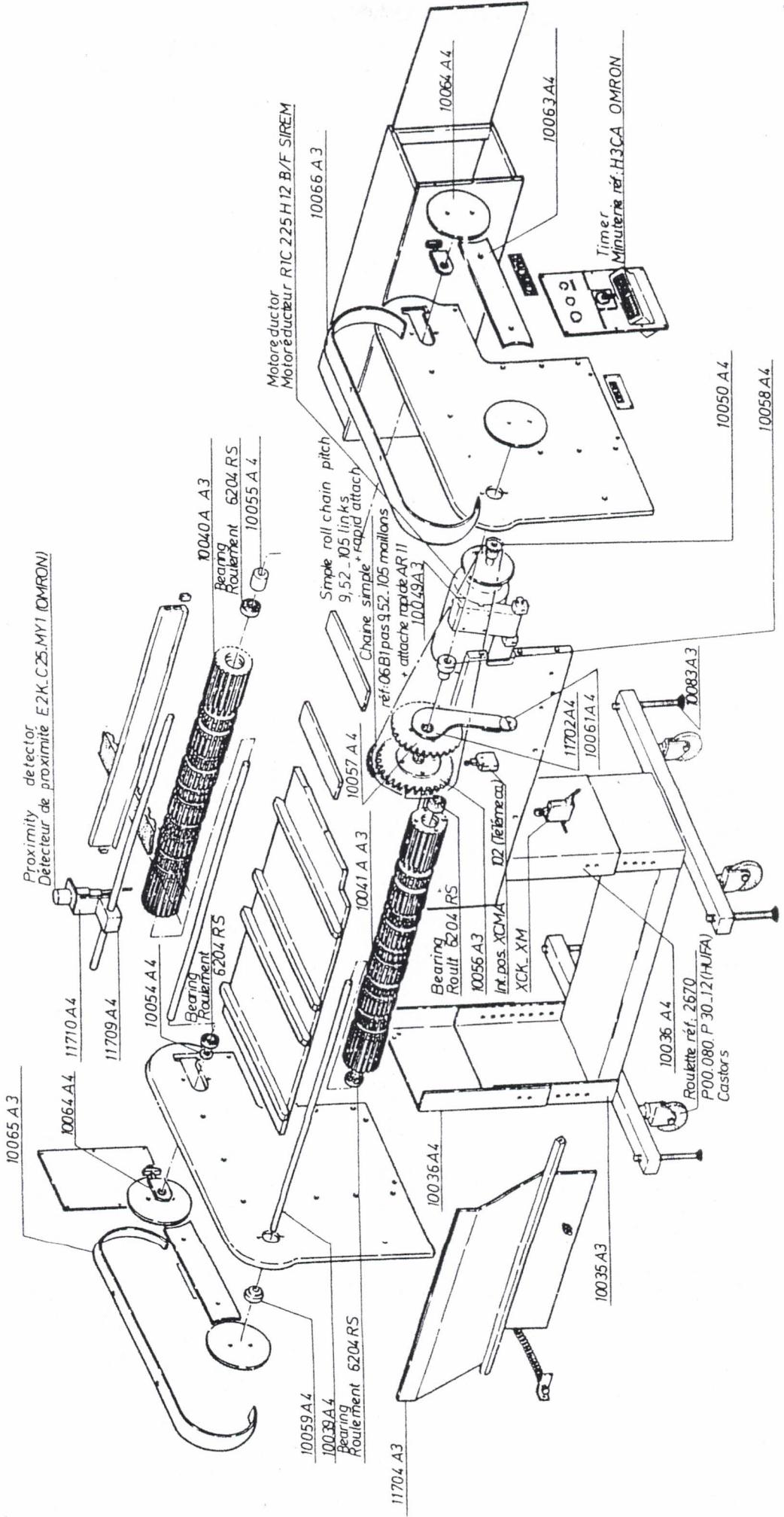
V10 SA 20 + 231ECHG (BACO)

V22 AA 03 + 231E 10 (BACO)



FACE AVANT TAPIMATIC
FRONT SIDE TAPIMATIC

PLAN NOTICE



Indice	Modifications	Date
Dessiné :	<i>Eh</i>	
Vérifié :		
Approuvé :		
Matière :		
Quantité :		
Trimestre :		

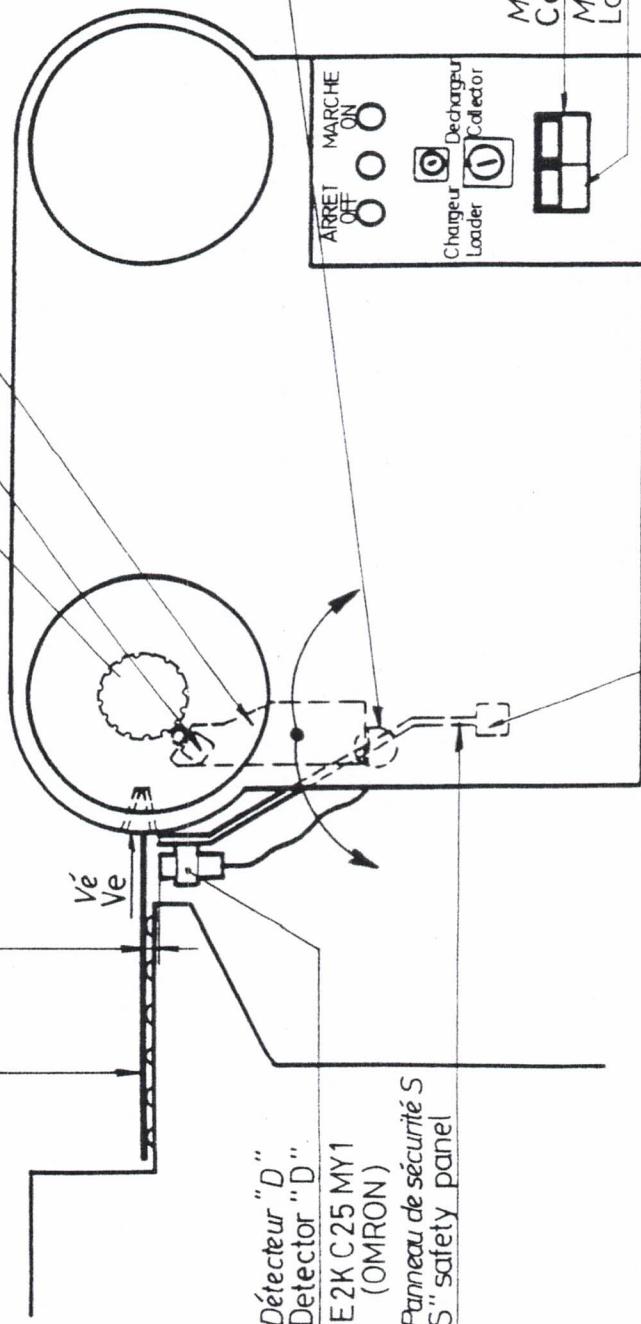
TAPIMATIC CD 50

Roue codeuse
Cog wheel

Interrupteur de position
Index limit switch (Télémécanique) XCMA 102-2
Dispositif d'ajustement V ang.
Position adjustment device

Distance 10 / 12 mm
Adjustment distance 10 / 12 mm

Circuit
Circuit



Vis d'immobilisation du microcontact d'indexation
Standstill screw of indexation microcontact

DéTECTEUR "D"
Detector "D"
E 2K C 25 MY1
(OMRON)

Panneau de sécurité S
"S" safety panel

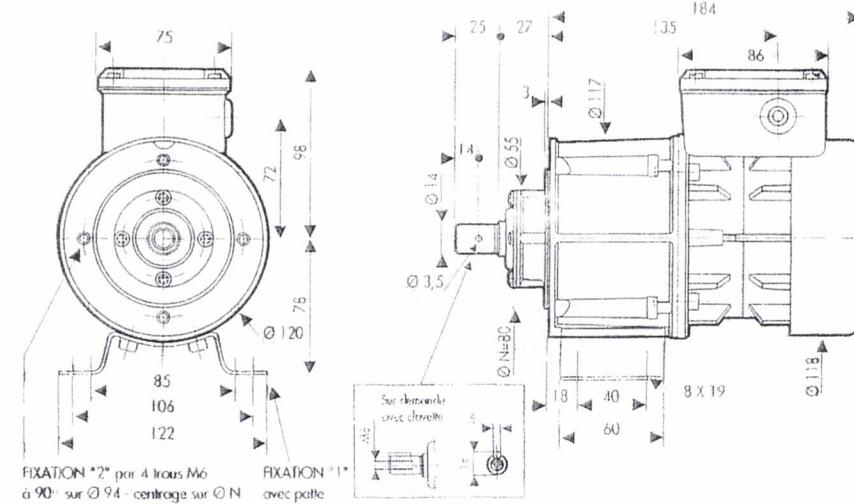
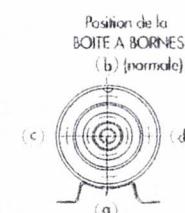
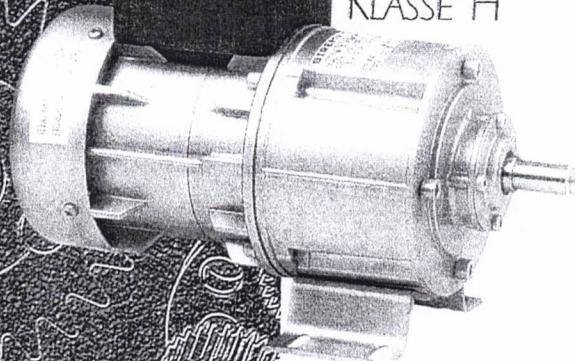
Minuterie déchargeur
Collect timer (H3CA OMRON)
Minuterie chargeur
Load timer (H3CA OMRON)

Contact d'arrêt automatique ST
Automatic stop switch ST

TAPIMATIC REVERSIBLE
REVERSE TARMATIC

TYPE H

KLASSE H



Caractéristiques techniques Technische Daten

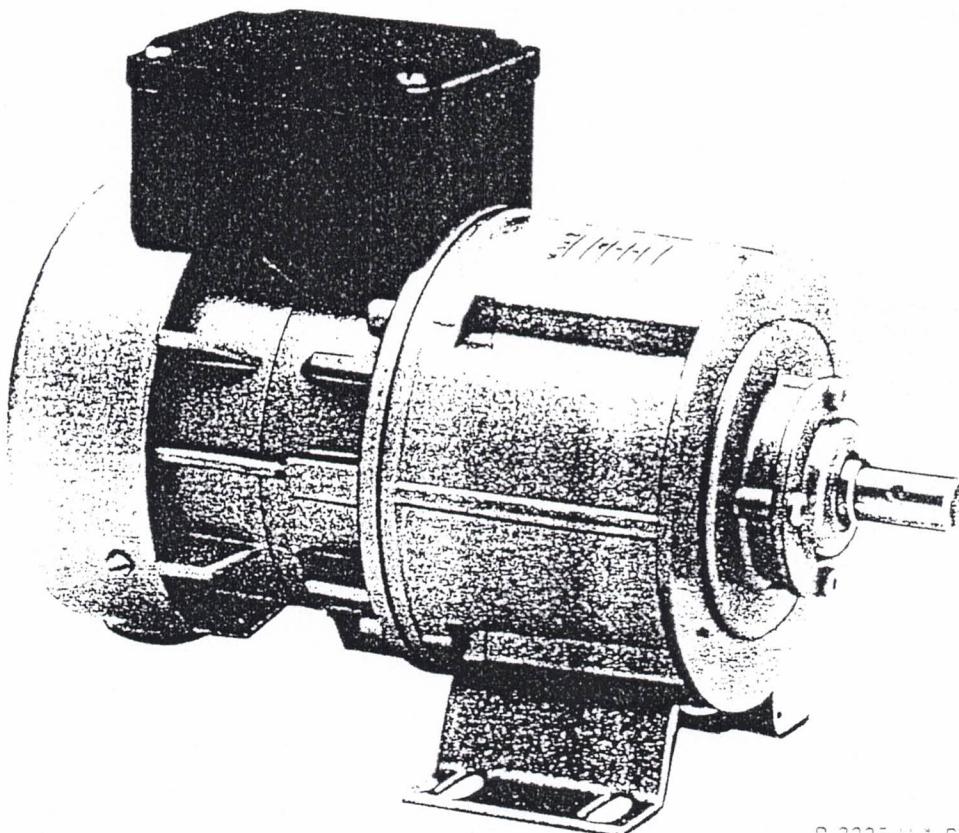
Col. 1	Col. 2	Vitesse n ₂ Tr/min	Rapport de réduction n ₂ /n ₁	Couple nominal m.daN Nmrehmoment m.daN		Charges maxi sur l'arbre lent ⁽¹⁾ Maxi. Belastung auf den well ⁽¹⁾		kg kg
		Drehzahl n ₂ U/min	Untersetzung n ₂ /n ₁	Col. 1	Col. 2	Radiale daN Radial daN	Axiale daN Axial daN	
RIC 625 HB	R3625 HB	1,5	1/547	3,5*	3,5*	100	105	
RIC 425 HB	R3425 HB	2,3	1/547	3,5*	3,5*	100	105	
RIC 225 HB	R3225 HB	3,5	1/390	3*	3*	100	105	
RIC 425 HB	R3425 HB	4,5	1/547	3,5*	3,5*	100	105	
		7	1/390	3*	3*	100	105	
RIC 225 HB	R3225 HB	10,5	1/134	1,5*	1,5*	92	80	
		15	1/184	1,5*	1,5*	82	70	
		21	1/134	1,2	1,4	74	60	
RIC 225 HB	R3225 HB	30	1/96	0,87	1	64	50	
		39	1/72	0,66	0,76	60	46	
		48	1/59	0,54	0,62	56	42	
RIC 425 HB	R3425 HB	65	1/45	0,41	0,47	50	36	
RIC 225 HB	R3225 HB	100	1/14	0,22*	0,22*	44	30	
		125	1/22	0,22	0,26	41	27	
		200	1/14	0,14	0,17	35	23	

Caractéristiques moteur Motor kennlinie	Pôles Pole	Monophasé à condensateur Einphasig mit Kondensator 230 V-50Hz	Triphasé Dreiphasig 230/400 W 50 Hz	Couple nominal Nmrehmoment cm.N	Puissance utile Leistung W	Vitesse n ₁ Tr/min Drehzahl n ₁ U/min	Intensité sous 230 V - A Stromaufnahme bei 230 V - A	I _A IN	C _d Cs	Cos φ
1C 625	6	•		14,2	13	870	0,37	1,1	1,31	0,99
3 625	6		•	15,3	14	870	0,32	1,5	2,1	0,67
1C 425	4	•		28,3	40	1350	0,55	1,34	0,85	0,99
3 425	4		•	27,3	40	1400	0,41	2	1,90	0,65
1C 225	2	•		13,4	38	2700	0,47	1,67	1,4	0,99
3 225	2		•	15,5	44	2700	0,29	2,45	0,97	0,82

1,5 à 200 Tr/min
0,17 à 3,5 m.daN

Monophasé à condensateur permanent ou triphasé
1,5 bis 200 U/min
0,17 bis 3,5 m.daN
Einphasig mit Dauerkondensator oder Dreiphasig

TYPE H



R 3225 H 1 S

MOTEUR deux sens de rotation.

Monophasé à condensateur permanent, ou triphasé.

MOTOR bi-directed MOTOR either.

Single phase with permanent capacitor or three phase.

MOTOR mit 2 Drehrichtungen.

Einphasig, mit Dauer-Kondensator oder für Drehstrom.

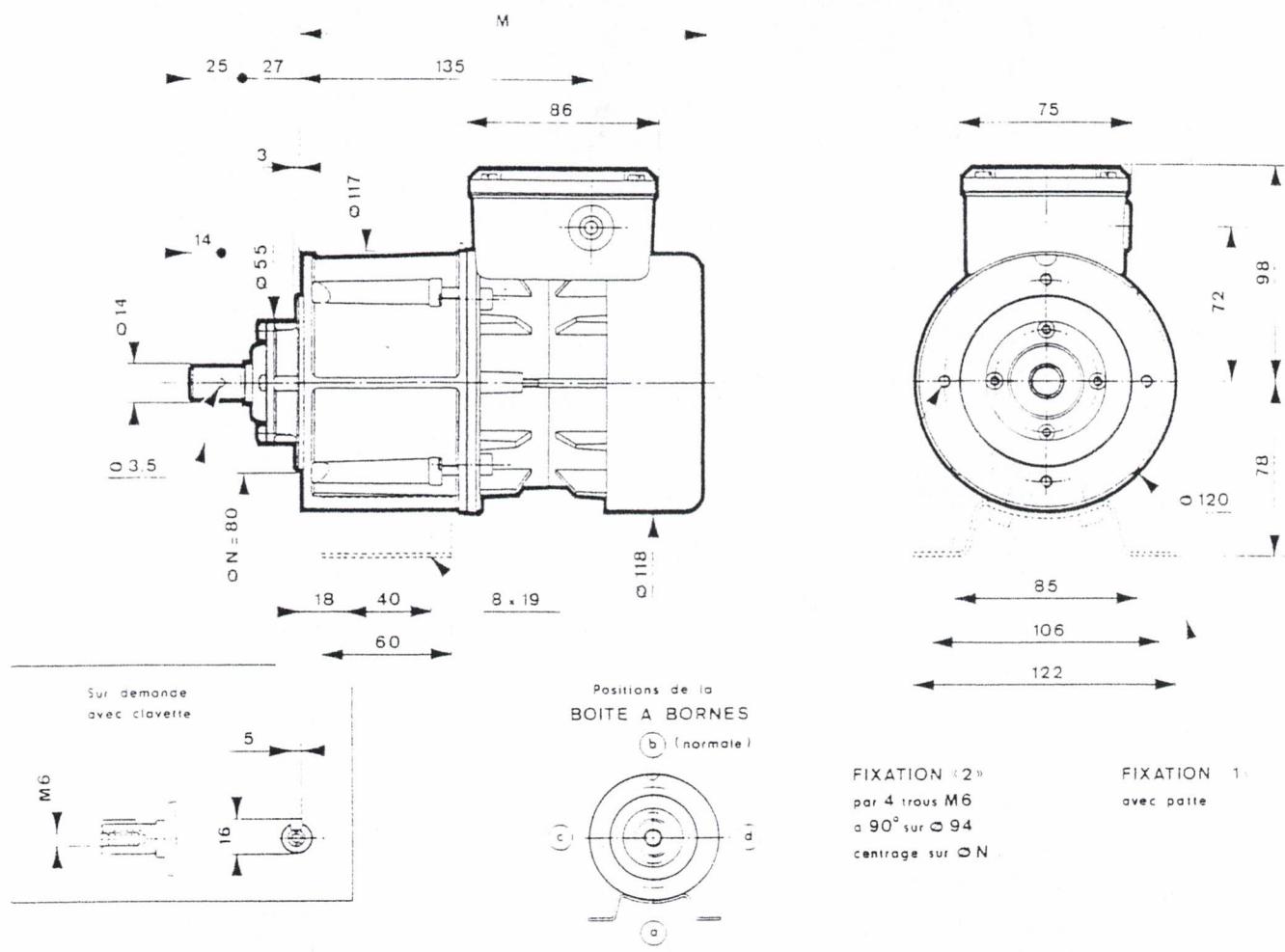
MOTORE a due sensi di rotazione.

Monofase con condensatore permanente, oppure trifase.

MOTOR dos sentidos de rotación.

Monofasico condensador permanente a trifasico.

Sirem	Pôles	Monophasé à condensateur permanent 220 V-50 Hz	Triphasé 220/380 V 50 Hz	Couple nominal cm.N	Puissance utile W	Vitesse n1 tr/mn	Intensité sous 220 V A	I _A / I _N	C _d / C _N	Cos φ
1C 625	6	•		13,4	12	870	0,35	1,1	1,31	0,99
3 625			•	14,5	13	870	0,31	1,48	2,1	0,67
1C 425	4	•		25,8	36,5	1350	0,53	1,34	0,85	0,99
3 425			•	25,5	37	1400	0,23	2	1,9	0,65
1C 225	2	•		12,2	35	2700	0,45	1,67	1,41	0,99
3 225			•	14,2	40	2700	0,28	2,45	0,97	0,82



Sirem	Vitesse n ₂ tr/mn	Rapport de réduction n ₂ /n ₁	Couple nominal m.daN ⁽¹⁾	Charges maxi sur l'arbre lent		Cote M	kg
				Radiale ⁽²⁾ daN	Axiale daN		
R 1C 625 HB	R 3 625 HB	1,5	1/547	3,5*	3,5*	100	105
R 1C 425 HB	R 3 425 HB	2,3	1/547	3,5*	3,5*	100	105
		3,5	1/390	3*	3*	100	105
R 1C 225 HB	R 3 225 HB	4,5	1/547	3,5*	3,5*	100	105
		7	1/390	3	3*	100	92
R 1C 425 HB	R 3 425 HB	10,5	1/134	1,5*	1,5*	92	80
		15	1/184	1,4	1,6	82	70
		21	1/134	1,15	1,3	74	60
		30	1/96	0,82	0,95	64	50
		39	1/72	0,61	0,7	60	46
		48	1/59	0,50	0,59	56	42
		65	1/45	0,38	0,45	50	36
R 1C 425 HB	R 3 425 HB	100	1/14	0,20*	0,20*	44	30
R 1C 225 HB	R 3 225 HB	125	1/22	0,21	0,25	41	27
		200	1/14	0,14	0,16	35	23

1 daN = 1 kgF. (2) Appliquée au milieu du bout d'arbre. * Couple maxi à ne pas dépasser (moteur surpuissant pour ce rapport).

E3JK

E3JK-5L

- 光电开关
- PHOTOELECTRIC SWITCH
- CELLULE PHOTOELECTRIQUE
- FOTOSCHALTER
- SENSORE FOTOELETTRICO
- FOTOCELULA

この製品は人体の保護を目的とした安全装置にはご使用いただけません。

Do not use this product as a safety device for part of safety systems for ensuring safety of persons.

Ne pas utiliser ce produit en tant que dispositif de sécurité ou même élément de dispositif assurant la sécurité de personnes.

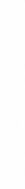
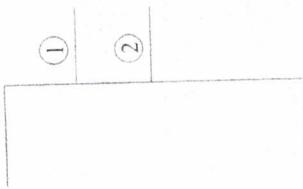
Verwenden Sie dieses Produkt nicht als Sicherheitseinrichtung oder Teil eines Sicherheitssystems für den Personenschutz.

Non utilizzare questo prodotto né come dispositivo ne come parte di un sistema per tutelare la sicurezza delle persone.

No utilizar este producto como dispositivo de seguridad ni como parte de sistemas de seguridad para garantizar la integridad de las personas.

不要将此产品用作保护人身安全的安装备置或安全系统的部分使用。

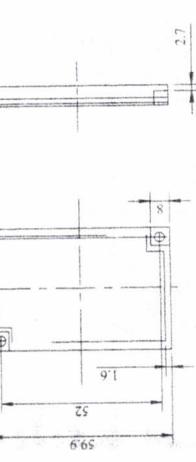
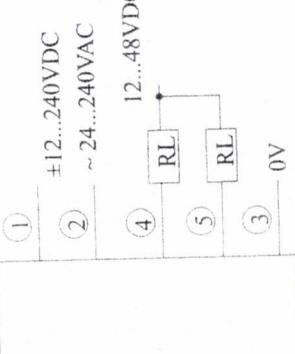
9413466-2



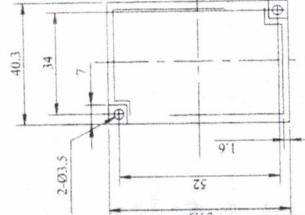
安全に正しくご使用いただくために、お使いになる前に必ず取り扱い方法を記載した「タロガ」をお読みになり十分に理解して下さい。

This sheet primarily describes precautions required in installing and operating the product. Before operating the product, read this sheet thoroughly to acquire sufficient knowledge of the product. For your convenience, keep this sheet for your disposal.

E3JK- S3



E39-R1



E39-R1

Type	L1	L2	L3
E3JK-DS40	□	40	30
E3JK-R	□ □ □		25
E3JK-5L		36.5	26.5
E3JK-5D	□ □		21.5

(1) 紫	Brown	Marron	Braun	Marrone	Marron
(2) 青	Blue	Bleu	Blau	Blau	Azul
(3) 白	White	Blanc	Weiß	Blanco	Blanco
(4) 黑	Black	Noir	Schwarz	Nero	Negro
(5) 灰	Gray	Gris	Grau	Gris	Gris

F	動作表示窓	Operation indicator	Indicateur d'opération
Bereichsanzeige	Spia funzionamento	Indicador de operación	Indicador de operación

F	動作表示窓	Operation indicator	Indicateur d'opération
Bereichsanzeige	Spia funzionamento	Indicador de operación	Indicador de operación

此说明书罗列了产品安装及使用过程中的注意事项，为了保证安全，请务必充分领会本说明书，使用完请妥善保管，以备随时食用。

重測量圧										Supply voltage		Tension d'alimentation		Nennspannung		Tension de alimentación		电源电压		12...240VDC±10% 24...240VAC±10% 50/60 Hz	
消費電力		Power consumption		Consumption		Assorbimento		Consumo		消費电力		≤3W		≤2W		≤3W		≤2W			
検出距離 E39-R1反射板		Sensing distance with reflector E39-R1		Distance de détection Avec réflecteur E39-R1		Distanza di rilevamento Con riflettore E39-R1		Distancia de detección nominal Con reflector E39-R1		検出距離 E39-R1反射板		5m		2.5m		30cm		2.5m		4m	
指向角 E39-R1反射板		Directional angle with reflector E39-R1		Angle directonnael Avec réflecteur E39-R1		Richtungswinkel mit Reflektor E39-R1		Angolo direzionale Con riflettore E39-R1		指向角 E39-R1反射板		1...5° ≥40°		3...20° ≥40°		1...5° ≥40°		1...5° ≥40°		-	
応答の距離 Hysteresis		Differential travel		Distance Différentielle		Hysterese		Distanza differenziale		Distancia diferencial		-		-		-		-			
制御出力 ルレーブル (最大) 無接點(最大)		Control output Relay output (max) (min)		Sortie de contrôle Sortie relais(max) (min)		Kontrollausgang Relais-aus-gang(max) (min)		Uscita A relé (max) (min)		Salida de control Salida de relé (máx) (min)		250VAC 3A 5VDC 10mA		-		-		-			
応答時間		Response time		Temps de réponse		Antsprachzeit		Tempo di risposta		Tempo de respuesta		30ms		≤10ms		≤5 ms		-			
周囲温度 動作時 保存時		Ambient humidity Operating Storage		Temperature ambiante En fonctionnement En stockage		Umgebungstemperatur Betrieb Lagerung		Temperatura ambiente Funzionamento Stoccaggio		Temperatura ambiente Operación Almacenaje		30°C		25...55°C -30...70°C		-		-			
周囲湿度 動作時 保存時		Ambient humidity Operating Storage		Humidité ambiante En fonctionnement En stockage		Umgebungsfeuchtigkeit Betrieb Lagerung		Umidità ambiente Funzionamento Stoccaggio		Humedad ambiente Operación Almacenaje		30%		45...85% RH 35...95% RH		-		-			
使用周間照度		Ambient operating illumination		Luminosità ambiente		Fremdflich-Sicherheit		Illuminazione ambiente		Iluminación ambiente de operación		3000lx		≤3000lx		-		-			
保護構造		Degree of protection		Indice de protection		Schutzzart		Grado de protección		Grado de protección		IP64		IP64		保護构造		保護构造			

1	2	3	4	16	17	18	19	20
---	---	---	---	----	----	----	----	----

A

B

C

D

E

F

G

H

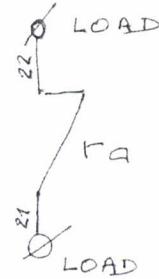
I

J

K

L

M

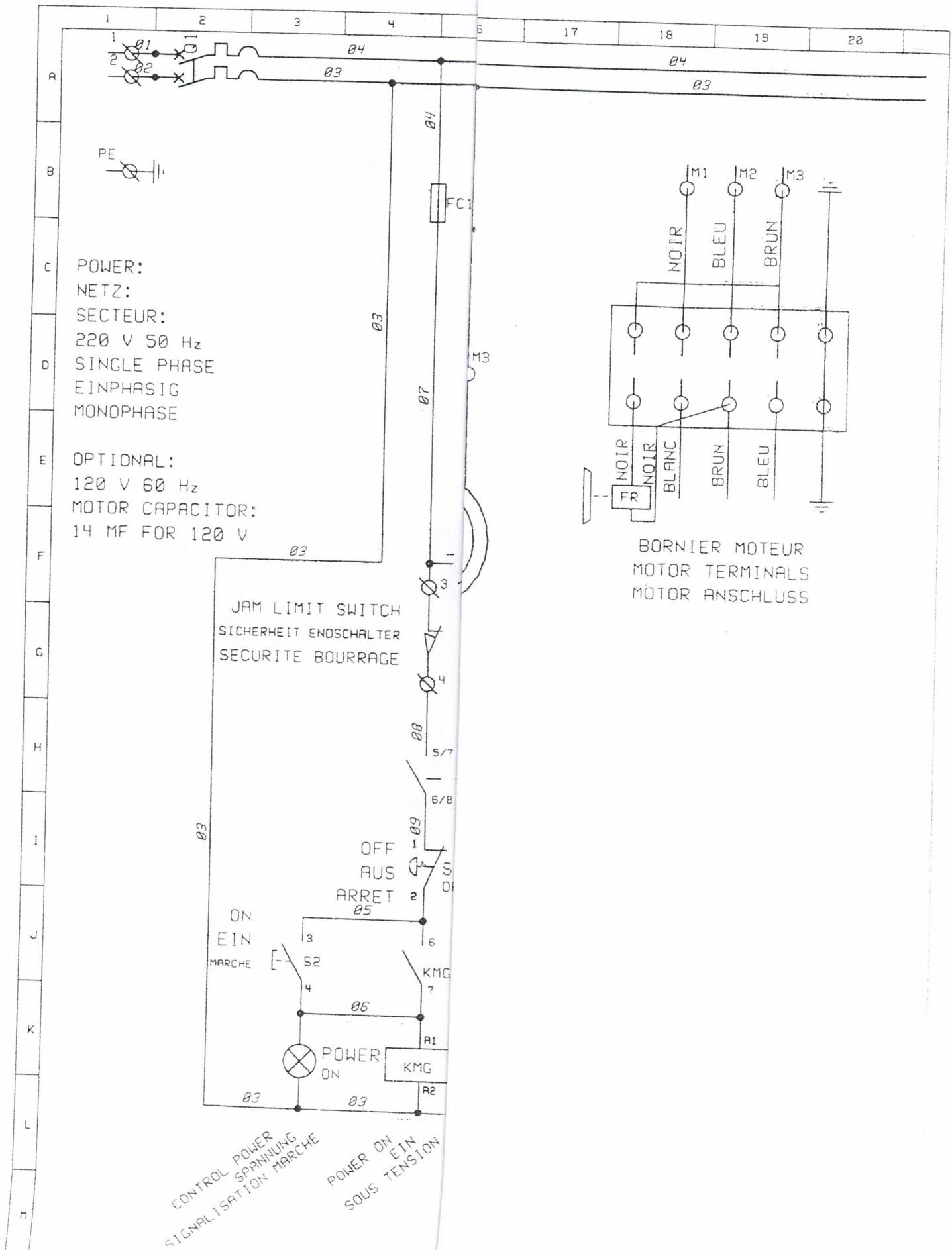


T C M D
10 rue PASTEUR
95410 GROSLAY
Tel : 01 34 05 82 36
Fax : 01 34 28 79 90

NE

ETUDE PAR:
JEAN DELCAMPE
ETUDE CAO DAO:
JEAN DELCAMPE

PRG REF:
DAO N: OPFUL 1
DATE: 27/04/20
N : 167273



TCMD

10 rue PASTEUR
95410 GROSLEY
Tel : 01 34 05 82 36
Fax : 01 34 28 79 90

	ETUDE PAR: JEAN DELCAMPE	PRO REF: DAO N: TAPTR DATE: 04/10/96 N : 16715
S	ETUDE CAD DAO: JEAN DELCAMPE	